

LIBRAK380 LIBRAK380P LIBRAK380S LIBRAK380PS LIBRAK380PW LIBRAK380PW LIBRAK380PWS

INSTRUCTION MANUAL

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TRANSLATION FROM THE ORIGINAL INSTRUCTIONS

For spare parts drawings refer to the section "LIST OF COMPONENTS" enclosed to this manual.

• For any further information please contact your local dealer or call:

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1297-M003-3_B - Rev. n. 3 (02/2018)



1297-M003-3_B

Page 2 of 67

GB

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

SUMMARY

SYM	BOLS USED IN THE MANUAL	_ 5
1.0 1.1	GENERAL INTRODUCTION	_ 7 7
2.0 2.1	INTENDED USE Training of personnel	_ 7 _ 7
3.0 3.1	SAFETY DEVICES Residual risks	_ 8 _ 8
4.0	GENERAL SAFETY RULES	8
5.0	PACKING AND MOBILIZATION FOR TRANSPORT	_ 9
6.0	UNPACKING	10
7.0	MOBILIZATION	10
8.0		10
8.1	TIONS Working area	11
	Lighting	
9.0	MACHINE ASSEMBLY	11
9.1	Anchoring system	11
	Fixtures contained in the packing	
	Assembly procedures	
	3.1 Fitting the mandrel on the flange	
	3.2 Fitting and removal of the pneu-	
	matic mandrel on the flange	13
	3.3 Fitting the protection guard	15
9.	3.4 Fitting of wheels width external	
	data gauge (only for LIBRAK380 -	
o	LIBRAK380P models) 3.5 Fitting of professional external	10
э.	data gauge (standard for	
	LIBRAK380S and LIBRAK380PS	
	models) (optional for LIBRAK380	
	and LIBRAK380P models)	16
9.	3.6 Monitor fitting	17
10.0	ELECTRICAL CONNECTIONS	1 8
10.0	1 Electrical checks	19
	AIR CONNECTION	- 19
	FITTING THE WHEEL ON THE MAN- DREL	20
12.	DREL	20
	LIBRAK380S - LIBRAK380W -	20
10	LIBRAK380WS)	20
12.2	2 Fitting of the wheel (LIBRAK380P - LIBRAK380PS - LIBRAK380PW -	
	LIBRAK380PS - LIBRAK380PW - LIBRAK380PWS)	21

12.3 Adjustment of ultrasound sensor sup port (only for LIBRAK380W -)-
LIBRAK380PW - LIBRAK380WS -	00
LIBRAK380PWS models)	23
13.0 CONTROL PANEL	_23
14.0 WHEEL BALANCING	_24
14.1 Switching the machine on and off	24
14.2 Balancing programs setting	25
14.2.1 Programs rapid setting and measurements through distance-	
diameter caliper arm	25
14.2.2 Programs setting through "Meas-	
urement being acquired" screen page 14.3 Indicative display of points where to	28
14.3 Indicative display of points where to detect measures/to fit weight	30
14.3.1 Weights positioning	30
14.3.1 weights positioning 14.4 Displaying the active/modifiable field	
14.5 Wheel balancing screen page descrip	_
tion	- 31
14.5.1 Balancing mode	01 32
14.5.1 Balancing mode 14.6 Use of machines with disabled auto-	32
matic gauge	34
14.6.1 Manual setting of wheel	
dimensions	34
14.7 Standard balancing programs	35
14.7.1 Static	35
14.7.2 Static-1	35
14.7.3 Static-2	35
14.7.4 Dynamic	36
14.7.5 ALU-S	36
14.7.6 ALU-S1	36
14.7.7 ALU-S2	36
14.7.8 ALU-1	37
14.7.9 ALU-2 14.7.10 ALU-3	37 37
14.7.11 ALU-3	37 37
14.8 Optional balancing programs	
14.8.1 ECO-WEIGHT mode	38
14.8.2 SPLIT mode	
14.8.3 Weights hidden behind spokes	
mode	42
14.8.4 matching mode 14.9 Special balancing programs	43
14.9 Special balancing programs	45
14.9.1 Pax	45
14.10 Recalculation function	46
14.11 Motorbike mode wheel balancing	46
15.0 USER MENU (OPTIONS AND CALI-	
BRATION)	_ 47
15.1 Options menu	48
15.1.1 Lower weight limit	49

Page 3 of 67

GB

INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

15.1.2 Setting adhesive weight dimen- sions and static threshold per-	
centage	50
15.1.3 User management	50
15.2 Machine calibrations	51
15.2.1 Mandrel "0" (zero) calibration	51
15.2.2 Weight measurement sensors	
calibration	_52
15.2.3 Gauges calibration	53
15.2.4 Mobile laser pointer calibration_	57
16.0 ERROR SIGNALS	_ 59
17.0 ROUTINE MAINTENANCE	60

18.0 TECHNICAL DATA	61
18.1 Dimensions	62
19.0 STORING	64
20.0 SCRAPPING	64
21.0 REGISTRATION PLATE DATA	64
22.0 FUNCTIONAL DIAGRAMS	64
Table A - Electric diagram	65
Table B - Pneumatic diagram	67

23.0 LIST OF COMPONENTS

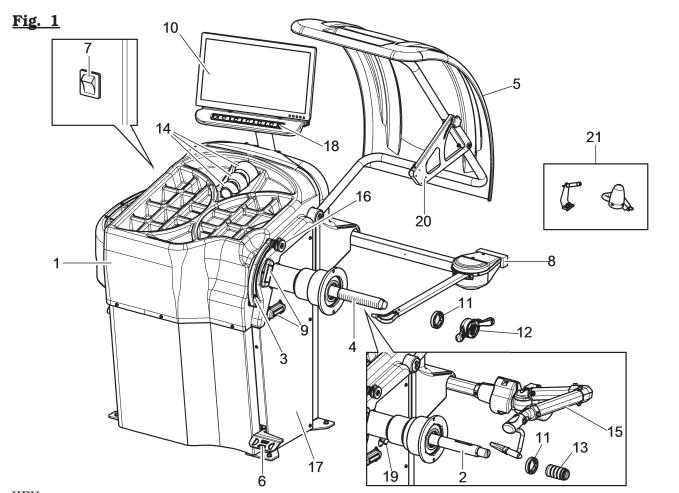


1297-M003-3 B

Page 4 of 67

GB

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS



KEY

- 1 Weight holding bridge
- 2 Pneumatic mandrel (only for LIBRAK380P LIBRAK380PS LIBRAK380PW LIBRAK380PWS models)
- 3 Distance-diameter caliper
- 4 Threaded mandrel (only for LIBRAK380 LIBRAK380S LIBRAK380W LIBRAK380WS models)
- 5 Protection guard
- 6 Foot brake (only for LIBRAK380 LIBRAK380S LIBRAK380W LIBRAK380WS models) / pneumatic mandrel open-close pedal (only for LIBRAK380P LIBRAK380PS LIBRAK380PW LIBRAK380PWS models)
- 7 Main switch
- 8 Wheels width external data gauge (only for LIBRAK380 LIBRAK380P models)
- 9 Led light unit
- 10 Monitor
- 11 Pressure ring
- 12 Rapid locking ring nut (only for LIBRAK380 LIBRAK380S LIBRAK380W LIBRAK380WS models)
- 13 Bush (only for LIBRAK380P LIBRAK380PS LIBRAK380PW LIBRAK380PWS models)
- 14 Cones
- 15 Professional external data gauge (standard for LIBRAK380S LIBRAK380PS models) (optional for LIBRAK380 LIBRAK380P models)
- 16 Grippers for weight fitting
- 17 Lateral guard
- 18 7-keys keyboard
- 19 Mobile laser pointer (only for LIBRAK380S LIBRAK380PS LIBRAK380WS LIBRAK380PWS models)
- 20 Automatic width measuring device unit (only for LIBRAK380W LIBRAK380PW LIBRAK380PWS LIBRAK380PWS models)
- 21 12 o'clock laser device (optional)

Page 5 of 67

GB

INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

SYMBOLS USED IN THE MANUAL

Symbols	Description	Symbols	Description
	Read instruction manual.	0	Mandatory. Operations or jobs to be performed compulsorily.
	Wear work gloves.		Danger! Be particularly careful.
	Wear work shoes.		Move with fork lift truck or pallet truck.
00	Wear safety goggles.		Lift from above.
()	Warning. Be particularly careful (possible material damages).		Technical assistance necessary. Do not perform any intervention.
Ø	Note. Indication and/or useful information.		Attention: never lift the machine by means of the mandrel.



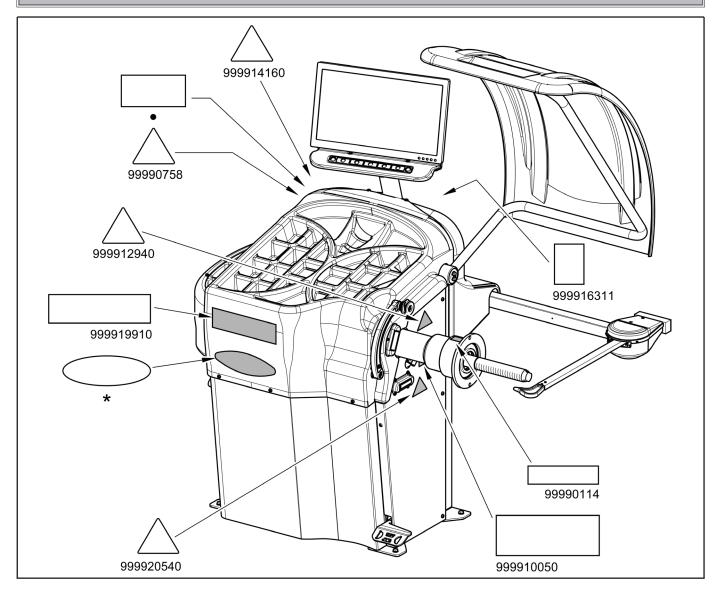
1297-M003-3_B

Page 6 of 67

GB

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

INFORMATION PLATE LOCATION TABLE



Code numbers of plates		
99990114	Arrow plate	
99990758	Electricity danger plate	
999910050	Protection device use plate	
999912940	Lifting plate	
999914160	Voltage 230V 50/60 Hz 1 Ph plate	
999916311	Rubbish skip label	
999919910	Machine nameplate	
999920540	Laser point danger plate (only for models LIBRAK380S - LIBRAK380PS - LIBRAK380WS - LIBRAK380PWS)	
•	Manufacturer nameplate	
*	Serial number plate	

0

IF ONE OR MORE PLATES DISAPPEAR FROM THE MACHINE OR BECOMES DIFFICULT TO READ. REPLACE IT AND QUOTE ITS/THEIR CODE NUMBER/S WHEN REORDERING.



INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS



GB

SOME OF THE PICTURES AND/ OR DISPLAY SCREEN PAGES PRESENT IN THIS MANUAL HAVE BEEN OBTAINED FROM PICTURES OF PROTOTYPES, THEREFORE THE STANDARD PRODUCTION MA-CHINES AND ACCESSORIES CAN BE DIFFERENT IN SOME COMPO-NENTS/DISPLAY SCREEN PAGES.

1.0 GENERAL INTRODUCTION

This manual is an integral part of the product and must be retained for the whole operating life of the machine.

Carefully study the warnings and instructions contained in this manual. It contains important instructions regarding **FUNCTIONING, SAFE USE and MAINTENANCE.**



KEEP THE MANUAL IN A KNOWN, EASILY ACCESSIBLE PLACE FOR ALL ACCESSORY OPERATORS TO CONSULT IT WHENEVER IN DOUBT.



THE MANUFACTURER DISCLAIMS ALL RESPONSIBILITY FOR ANY DAMAGE OCCURRED WHEN THE INDICATIONS GIVEN IN THIS MANUAL ARE NOT RESPECTED: AS A MATTER OF FACT, THE NON-COMPLIANCE WITH SUCH INDI-CATIONS MIGHT LEAD TO EVEN SERIOUS DANGERS.

1.1 Introduction

Thank you for preferring this wheel balancer. We feel sure you will not regret your decision.

This machine has been designed for use in professional workshops and stands out for its reliability and easy, safe and rapid operation. With just a small degree of maintenance and care, this wheel balancer will give you many years of trouble-free service and lots of satisfaction.

2.0 INTENDED USE

The machines described in this manual and their different versions, are wheels balancing machines for trucks, projected to be used exclusively to cancel out, or at least reduce to acceptable limits the vibrations of the wheels, by fitting counterweights of suitable size and in specific positions to the same wheels that are not correctly balanced.



DANGER: EMPLOYING THESE MACHINES OUTSIDE THE USE DESTINATION THEY HAVE BEEN DESIGNED FOR (AS INDICATED IN THIS MANUAL) IS INAPPROPRI-ATE AND DANGEROUS.



THE MANUFACTURER CANNOT BE HELD RESPONSIBLE FOR ANY DAMAGE CAUSED BY IMPROPER, ERRONEOUS, OR UNACCEPTABLE USE.



AN INTENSIVE USE OF THE EQUIP-MENT IN INDUSTRIAL ENVIRON-MENT IS NOT RECOMMENDED.

2.1 Training of personnel

The machine may be operated only by suitably trained and authorized personnel.

Given the complexity of the operations necessary to manage the machine and to carry out the operations safely and efficiently, the personnel must be trained in such a way that they learn all the information necessary to operate the machine as intended by the manufacturer.



A CAREFUL READING OF THIS INSTRUCTION MANUAL FOR USE AND MAINTENANCE AND A SHORT PERIOD OF TRAINING WITH SKILLED PERSONNEL CAN BE AN ENOUGH PREVENTIVE PREPARATION.



1297-M003-3_B

GB

Page 8 of 67

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

3.0 SAFETY DEVICES



PERIODICALLY, AT LEAST MONTH-LY, CHECK THE INTEGRITY AND THE FUNCTIONALITY OF THE SAFETY AND PROTECTION DE-VICES ON THE MACHINE.

• Master switch positioned on the rear of the machine

Its function is to disconnect machine electric supply.

• Protection guard

Its function is to protect the operator from possible projections of materials on the wheel during its spin. Wheel spinning is normally prevented if the wheel protection guard is raised (open). When the protection guard is open, this interrupts the circuit that triggers the motor and automatic start is prevented, including in the case of an error.



Press stop key to stop wheel rotation in emergency conditions.

3.1 Residual risks

The machine was subjected to a complete analysis of risks according to reference standard EN ISO 12100. Risks are as reduced as possible in relation with technology and product functionality.

Possible residual risks have been emphasized through pictorial representations and warnings which placing is indicated in "PLATE POSITIONING TABLE" at page 6.

4.0 GENERAL SAFETY RULES



- Any tampering with or modification to the machine not previously authorized by the manufacturer exempts the latter from all responsibility for damage caused by or derived from said actions.
- Removing of or tampering with the safety devices or with the warning signals placed on the machine leads to serious dangers and represents a transgression of European safety rules.
- Use of the machine is only permitted in places free from **explosion** or **fire** hazard and in **dry places under cover**.
- Original spare parts and accessories should be used.



THE MANUFACTURER DENIES ANY RESPONSIBILITY IN CASE OF DAMAGES CAUSED BY UNAU-THORIZED MODIFICATIONS OR BY THE USE OF NON ORIGINAL COMPONENTS OR EQUIPMENT.

- Installation must be conducted only by qualified personnel exactly according to the instructions that are given below.
- Ensure that there are no dangerous situations during the machine operating manoeuvres. Immediately stop the machine if it miss-functions and contact the assistance service of an authorized dealer.
- In emergency situations and before carrying out any maintenance or repairs, disconnect all supplies to the machine by using the main switch, placed on the machine itself, and unplugging the power supply.
- The machine electrical supply system must be equipped with an appropriate earthing, to which the yellow-green machine protection wire must be connected.
- Ensure that the work area around the machine is free of potentially dangerous objects and that there is no oil since this could damage the tyre. Oil on the floor is also a potential danger for the operator.
- UNDER NO CIRCUMSTANCES must the machine be used to spin anything but vehicle wheels. Bad locking can cause rotating parts to come loose, with potential damage to the machine and anything in the vicinity and injury to the operator.

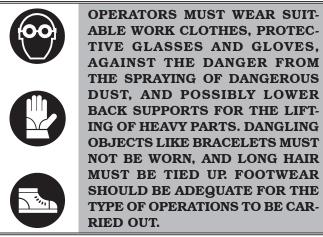
Page 9 of 67

GB

INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS



- The machine handles and operating grips must be kept clean and free from oil.
- The workshop must be kept clean and dry. Make sure that the working premises are properly lit. The machine can be operated by a single operator.

Unauthorized personnel must remain outside the working area, as shown in **Fig. 3**.

Avoid any hazardous situations. Do not use airoperated or electrical equipment when the shop is damp or the floor slippery and do not expose such tools to atmospheric agents.

• When operating and servicing this machine, carefully follow all applicable safety and accident-prevention precautions.

The machine must not be operated by professionally unskilled persons.



WHEN USING THE MODELS WITH WHEEL PNEUMATIC CLAMPING, DURING MANDREL OPENING/ CLOSING OPERATIONS, BE EX-TREMELY CAREFUL AND KEEP YOUR HANDS OR OTHER PARTS OF YOUR BODY AWAY FROM THE MOVING MANDREL.

5.0 PACKING AND MOBILIZATION FOR TRANSPORT

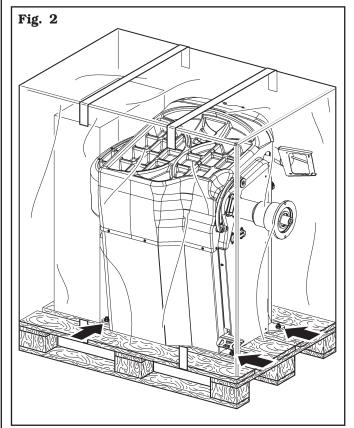


HAVE THE MACHINE HANDLED BY SKILLED PERSONNEL ONLY.

THE LIFTING EQUIPMENT MUST WITHSTAND A MINIMUM RATED LOAD EQUAL TO THE WEIGHT OF THE PACKED MACHINE (SEE PARAGRAPH "TECHNICAL SPECIFICATIONS").

The machine is packed completely assembled. The machine is inside a carton box which size is mm 1300x1000x1150.

Movement must be by pallet-lift or fork-lift trolley. The fork lifting points are indicated on the packing.





1297-M003-3_B

Page 10 of 67

GB

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

6.0 UNPACKING



DURING UNPACKING, ALWAYS WEAR GLOVES TO PREVENT ANY INJURY CAUSED BY CONTACT WITH PACKAGING MATERIAL (NAILS, ETC.).

The cardboard box is supported with plastic strapping. Cut the strapping with suitable scissors. Use a small knife to cut along the lateral axis of the box and open it like a fan.

It is also possible to unnail the cardboard box from the pallet it is fixed to. After removing the packing, and in the case of the machine packed fully assembled, check that the machine is complete and that there is no visible damage.

If in doubt **do not use the machine** and refer to professionally qualified personnel (to the seller).

The packing (plastic bags, expanded polystyrene, nails, screws, timber, etc.) should not be left within reach of children since it is potentially dangerous. These materials should be deposited in the relevant collection points if they are pollutants or non biodegradable.



THE BOX CONTAINING THE FIX-TURES IS CONTAINED IN THE WRAPPING. DO NOT THROW IT AWAY WITH THE PACKING.

7.0 MOBILIZATION



THE LIFTING EQUIPMENT MUST WITHSTAND A MINIMUM RATED LOAD EQUAL TO THE WEIGHT OF THE MACHINE (SEE PARAGRAPH TECHNICAL SPECIFICATIONS). DO NOT AL-LOW THE LIFTED MACHINE TO SWING.



NEVER LIFT THE MACHINE BY MEANS OF THE MANDREL.

If the machine has to be moved from its normal work post, the movement must be conducted following the instructions listed below.

- Protect the exposed corners with suitable material (Pluribol/cardboard).
- Do not use metallic cables for lifting.
- Make sure the electrical and pneumatic supply (only for LIBRAK380P, LIBRAK380PS, LIBRAK380PW and LIBRAK380PWS models) of the machine is not connected.
- Place again the machine onto the original pallet with whom it was delivered.
- Use transpallet or fork-lift for handling.

8.0 WORKING ENVIRONMENT CONDI-TIONS

The machine must be operated under proper conditions as follows:

- temperature: $0^{\circ} + 45^{\circ} C$
- relative humidity 30 90% (dew-free)
- atmospheric pressure: 860 1060 hPa (mbar).

The use of the machine in ambient conditions other than those specified above is only allowed after prior agreement with and approval of the manufacturer. Page 11 of 67

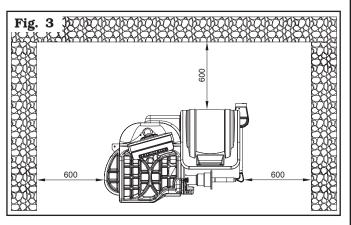
INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

8.1 Working area

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USE THE MACHINE IN A DRY AND AD-EQUATELY LIT PLACE, POSSIBLY INDOORS OR ANYWAY IN A ROOFED AREA, THIS PLACE MUST BE IN COMPLIANCE WITH APPLICABLE SAFETY REGULATIONS.

The location of the machine requires a usable space as indicated in **Fig. 3**. The positioning of the machine must be according to the distances shown. From the control position the operator is able to observe all the machine and surrounding area. He must prevent unauthorized personnel or objects that could be dangerous from entering the area.

The machine must be fixed on a flat floor surface, preferably of cement or tiled. Avoid yielding or irregular surfaces.

The base floor must be able to support the loads transmitted during operation.

This surface must have a capacity load of at least 500 $\mbox{kg/m^2}.$

The depth of the solid floor must be sufficient to guarantee that the anchoring bolts hold.

8.2 Lighting

The machine does not require its own lighting for normal working operations. However, it must be used in an adequately lit environment.

In case of poor lighting use lamps having total power of 800/1200 Watt.



IF IT IS INSTALLED, EACH TIME THE ROD OF THE GAUGE IS EX-TRACTED FROM ITS HOUSING, THE LED LIGHT (FIG. 1 REF. 9) TURNS ON MAKING THE INSIDE OF THE WHEEL WHERE THE OP-ERATOR MUST WORK BRIGHTER.

9.0 MACHINE ASSEMBLY

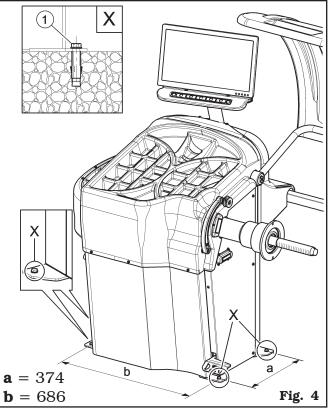
After having freed the various components from the packing check that they are complete, and that there are no anomalies, then comply with the following instructions for the assembly of the components making use of the attached series of illustrations.

9.1 Anchoring system

The packed machine is fixed to the support pallet through the holes prearranged on the frame. Such holes can be used also to fix the machine to the ground, through floor anchor small blocks (**Fig. 4 ref. 1**) (excluded from supply). Before carrying out the definitive fixing, check that all the anchor points are laid down flat and correctly in contact with the fixing surface itself. If not so, insert shimming profiles between the machine and the fixing lower surface, as indicated in **Fig. 4**.



IN CASE OF WHEEL WEIGHING MORE THAN 30 KG, IT IS COM-PULSORY TO FIX TO THE GROUND BY MEANS OF SCREW ANCHORS.



• Execute 4 holes with 10 mm diameter on the floor by the holes on the bottom floor;

- insert the small blocks (excluded from supply) into the holes;
- fix the machine to the ground with 4 M8x80 mm screws (excluded from supply) (**Fig. 4 ref. 1**) (or with 4 8x80 mm stud bolts (excluded from supply)). Tighten the screws with an approximate tightening torque of 70 Nm.



1297-M003-3_B

Page 12 of 67

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

9.2 Fixtures contained in the packing

The packing case contains also the fixtures box. Check that all the parts listed below are there (see **Fig. 5**).

For LIBRAK380 model

Code	Description	N .
GAR345	Rapid locking ring nut + pres- sure ring	1
GAR111	Cones + protection cup	1
129571492	Gauge	1
1300A004	Weight pliers	1
999072	Carriages counterweight	1
GAR307	Wheels width external data gauge	1

For LIBRAK380P model

Code	Description	N .
GAR108	Bush + pressure ring	1
GAR111	Cones + protection cup	1
129571492	Gauge	1
1300A004	Weight pliers	1
999072	Carriages counterweight	1
GAR307	Wheels width external data	1
UAR307	gauge	

For LIBRAK380S model

Code	Description	N .
GAR345	Rapid locking ring nut + pres- sure ring	1
GAR111	Cones + protection cup	1
129571492	Gauge	1
1300A004	Weight pliers	1
999072	Carriages counterweight	1
GAR305	Professional external data gauge	1

For LIBRAK380PS model

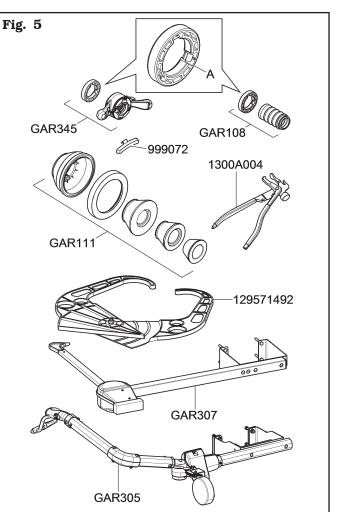
Code	Description	N .
GAR108	Bush + pressure ring	1
GAR111	Cones + protection cup	1
129571492	Gauge	1
1300A004	Weight pliers	1
999072	Carriages counterweight	1
GAR305	Professional external data gauge	1

For LIBRAK380W - LIBRAKWS model

Code	Description	N .
GAR345	Rapid locking ring nut + pres- sure ring	1
GAR111	Cones + protection cup	1
129571492	Gauge	1
1300A004	Weight pliers	1
999072	Carriages counterweight	1

For LIBRAK380PW - LIBRAKPWS model

Code	Description	N .
GAR108	Bush + pressure ring	1
GAR111	Cones + protection cup	1
129571492	Gauge	1
1300A004	Weight pliers	1
999072	Carriages counterweight	1





THE PRESSURE RING (FIG. 5 REF. A) MUST BE MOUNTED WITH THE TEETH OR DISCHARGE SIDE TOWARDS THE RING-NUT OR BUSH (SEE FIG. 5).

Page 13 of 67

GB

INSTRUCTION, USE AND MAINTENANCE MANUAL



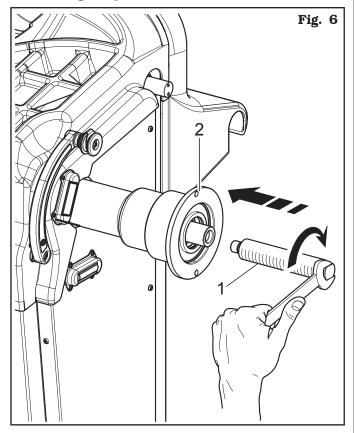
LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

9.3 Assembly procedures

9.3.1 Fitting the mandrel on the flange

Only for LIBRAK380 - LIBRAK380S - LIBRAK380W - LIBRAK380WS models

Screw with an Allen wrench the mandrel (**Fig. 6 ref. 1**) on the flange (**Fig. 6 ref. 2**).

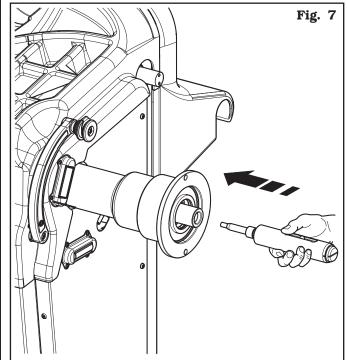


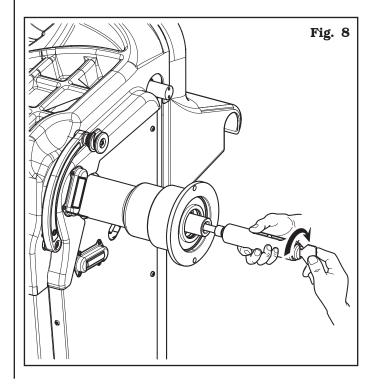
<u>9.3.2 Fitting and removal of the pneumatic</u> <u>mandrel on the flange</u>

Only for LIBRAK380P - LIBRAK380PS -LIBRAK380PW - LIBRAK380PWS models

FITTING

1. After making power and air connections switch on the machine (the pneumatic mandrel always opens when the machine is switched on). Switch the machine off. Fit the internal mandrel on the flange and tighten it with the wrench provided (**Fig. 7** and **ref. 8**).







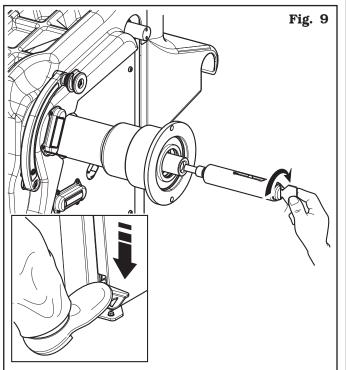
1297-M003-3_B

Page 14 of 67

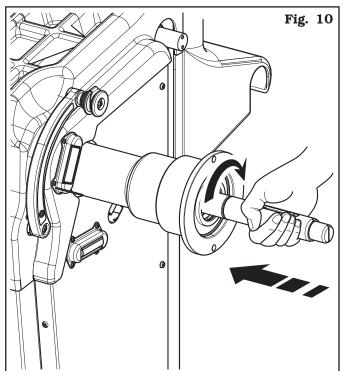
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LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

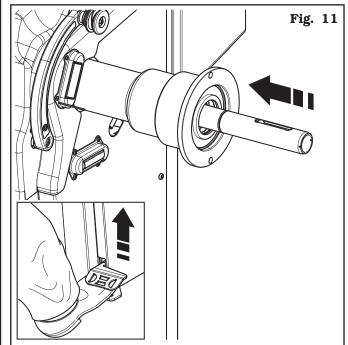
2. Press the brake's pedal and, at the same time, tighten the internal mandrel as far as it will go using the wrench provided (Fig. 9).



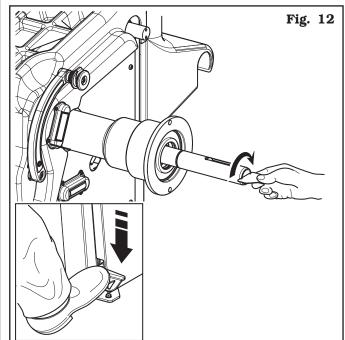
3. Fit the external mandrel and tighten it manually (Fig. 10).



4. Close the pneumatic mandrel by means of the pedal to access the key socket (Fig. 11).



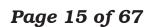
5. Press the brake pedal and at the same time block the external mandrel using the wrench supplied (Fig. 12).



REMOVAL

- Close the pneumatic mandrel by means of the pedal provided to access the key socket (Fig. 11).
- Press the brake pedal and at the same time release the external mandrel by using the wrench supplied (Fig. 12).
- Remove the external mandrel, open the pneumatic mandrel by means of the pedal provided and loosen the internal mandrel using the special wrench (Fig. 9).

1297-M003-3 B



INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

9.3.3 Fitting the protection guard

- Mount the protection guard (Fig. 13 ref. 1) to the support (Fig. 13 ref. 2) using the screws (Fig. 13 ref. 3), interposing the Belleville washers (Fig. 13 ref. 4).
- 2. Tighten the screws (**Fig. 13 ref. 3**) in order to make the guard (**Fig. 13 ref. 1**) lift or lower without bumping against the limit switch. Carry out the adjustment so that it's possible to manually guide the guard both during closing and opening.

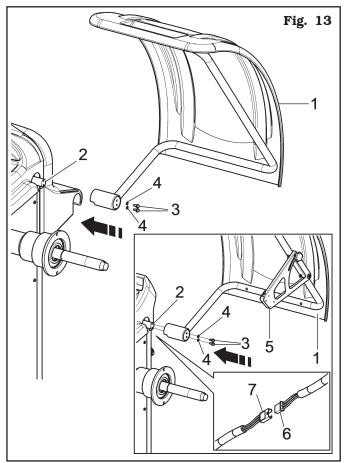


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DURING GUARD'S ASSEMBLY, PAY ATTENTION TO THE MICRO PLACED INSIDE THE MACHINE.

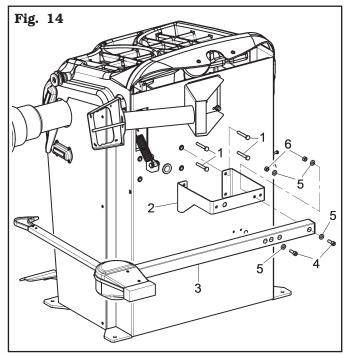
Only for LIBRAK380W - LIBRAK380PW LIBRAK380WS - LIBRAK380PWS models

3. Connect the ultrasound sensor cable (**Fig. 13 ref. 6**) of the automatic width measuring device (**Fig. 13 ref. 5**) to the pre-arranged connector (**Fig. 13 ref. 7**).

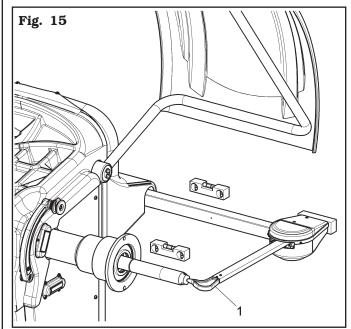


<u>9.3.4 Fitting of wheels width external</u> <u>data gauge (only for LIBRAK380 -</u> <u>LIBRAK380P models)</u>

Introduce the 4 screws (Fig. 14 ref. 1) in the gauge bracket (Fig. 14 ref. 2) and screw them on the special threaded rivets placed on the rear side of the frame. Lock the gauge arm (Fig. 14 ref. 3) to the bracket (Fig. 14 ref. 2) using the 2 screws (Fig. 14 ref. 4) and the washers (Fig. 14 ref. 5). Lock the screws (Fig. 14 ref. 4) through the washers (Fig. 14 ref. 5) and the nuts (Fig. 14 ref. 6) so that the shaft and the gauge arm are levelled (see Fig. 15).



2. Also make sure the gauge tip (**Fig. 15 ref. 1**) is positioned at the centre of the mandrel.



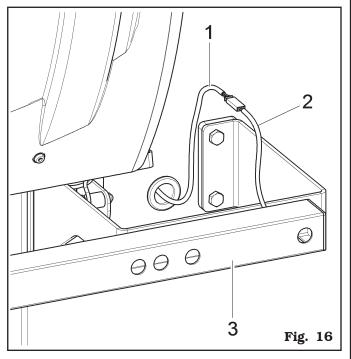


1297-M003-3_B

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LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

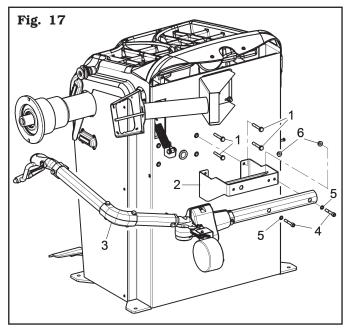
- Connect connector (Fig. 16 ref. 1) of the cable coming from inside the machine to connector (Fig. 16 ref. 2) of the cable coming from the gauge arm. Fit the section of the cable with the connectors inside the arm (Fig. 16 ref. 3).
- 4. Fasten the cable with clamps.
- 5. Enable the external data gauge and carry out the device's calibration.



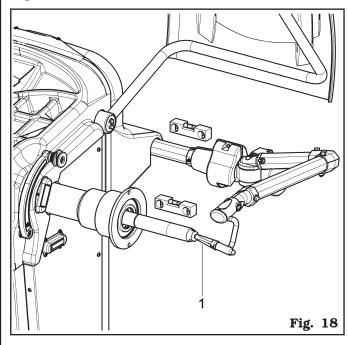
IF THE FRAME OF THE WHEEL BALANCER IS NOT EQUIPPED WITH THE 4 THREADED RIVETS, TO FIX THE GAUGE FIX THE BRACKET (Fig. 14 ref. 2) US-ING ONLY SCREWS (# 272038). BLOCK THE BRACKET FROM THE INSIDE WITH THE NUTS AND THE WASHERS SUPPLIED WITH THE DEVICE.

<u>9.3.5 Fitting of professional external data</u> <u>gauge (standard for LIBRAK380S and</u> <u>LIBRAK380PS models) (optional for</u> <u>LIBRAK380 and LIBRAK380P models)</u>

 Introduce the 4 screws (Fig. 17 ref. 1) to the gauge bracket (Fig. 17 ref. 2) and screw them to the special threaded rivets placed on the rear side of the frame. Lock the gauge arm (Fig. 17 ref. 3) to the bracket (Fig. 17 ref. 2) using the 2 screws (Fig. 17 ref. 4) and the washers (Fig. 17 ref. 5). Lock the screws (Fig. 17 ref. 4) through the nuts (Fig. 17 ref. 6), so that the shaft and the gauge arm are levelled (see Fig. 18).



2. Also make sure the gauge tip (**Fig. 18 ref. 1**) is positioned at the centre of the mandrel.



Page 17 of 67

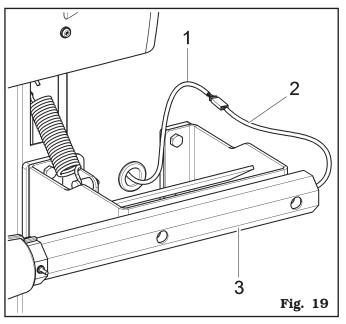
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INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

- Connect connector (Fig. 19 ref. 1) of the cable coming from inside the machine to connector (Fig. 19 ref. 2) of the cable coming from the gauge arm. Fit the section of the cable with the connectors inside the arm (Fig. 19 ref. 3).
- 4. Fasten the cable with clamps.
- 5. Enable the external data gauge and carry out the device's calibration.



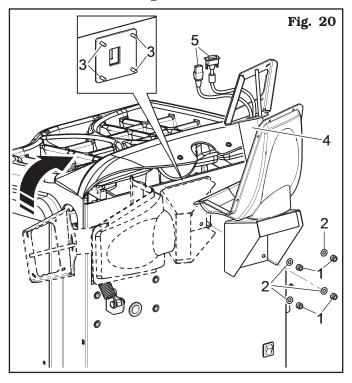


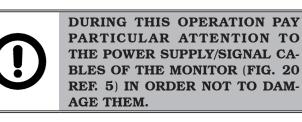
BALANCER IS NOT EQUIPPED WITH THE 4 THREADED RIVETS, TO FIX THE GAUGE FIX THE BRACKET (Fig. 17 ref. 2) US-ING ONLY SCREWS (# 272038). BLOCK THE BRACKET FROM THE INSIDE WITH THE NUTS AND THE WASHERS SUPPLIED WITH THE DEVICE.

IF THE FRAME OF THE WHEEL

9.3.6 Monitor fitting

 Unscrew screws (Fig. 20 ref. 1) and the nuts (Fig. 20 ref. 2) from the screws (Fig. 20 ref. 3). Fit the support tube (Fig. 20 ref. 4) rotated through 90°. Then screw the previously unscrewed nuts and washers again.





2. Connect the plugs on the power supply sockets and monitor signal. Connect the wiring of the keyboard.

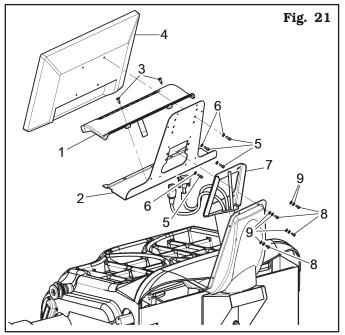


1297-M003-3_B

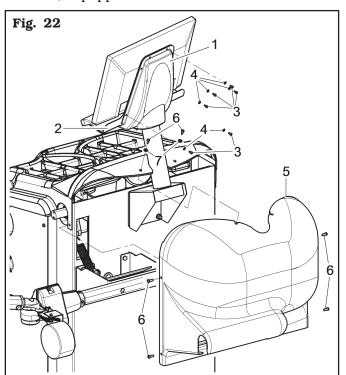
Page 18 of 67

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

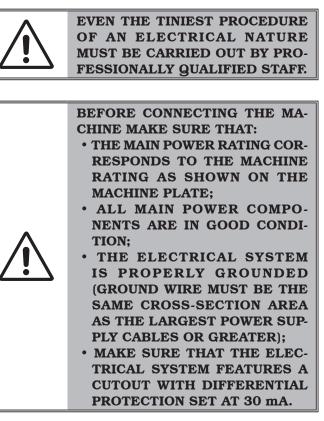
 Fix the keyboard (Fig. 21 ref. 1) to the support (Fig. 21 ref. 2) with the screws (Fig. 21 ref. 3).
 Fix the monitor (Fig. 21 ref. 4) to the support (Fig. 21 ref. 2) by means of the screws (Fig. 21 ref. 5) and washers (Fig. 21 ref. 6), equipped on issue. Fix the support (Fig. 21 ref. 2), complete with monitor and keyboard, to monitor support (Fig. 21 ref. 7) by means of the screws (Fig. 21 ref. 8) and the washers (Fig. 21 ref. 9), equipped on issue.



- 4. Fix the guard (Fig. 22 ref. 1) to the support (Fig. 22 ref. 2) with the 6 screws (Fig. 22 ref. 3) and the washers (Fig. 22 ref. 4), equipped on issue.
- 5. Mount machine rear covering (**Fig. 22 ref. 5**) using the screws (**Fig. 22 ref. 6**) and washers (**Fig. 22 ref. 7**), equipped on issue.



10.0 ELECTRICAL CONNECTIONS



Connect the machine up to the mains by means of the 3-pole plug provided (230 V single-phase).

If the plug provided is not suitable for the wall socket, fit a plug that complies with local and applicable regulations. This operation must be performed by expert and professional personnel.



FIT A TYPE-APPROVED (AS RE-PORTED BEFORE) PLUG TO THE MACHINE CABLE (THE GROUND WIRE IS YELLOW/GREEN AND MUST NEVER BE CONNECTED TO ONE OF THE TWO PHASE LEADS).



MAKE SURE THAT THE ELECTRI-CAL SYSTEM IS COMPATIBLE WITH THE RATED POWER AB-SORPTION SPECIFIED IN THIS MANUAL AND APT TO ENSURE THAT VOLTAGE DROP UNDER FULL LOAD WILL NOT EXCEED 4% OF RATED VOLTAGE (10% UPON START-UP). Page 19 of 67

INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS



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FAILURE TO OBSERVE THE ABOVE INSTRUCTIONS WILL IMMEDIATE-LY INVALIDATE THE WARRANTY.

10.1 Electrical checks

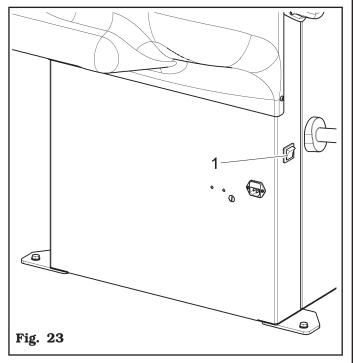


BEFORE STARTING UP THE WHEEL-BALANCER, BE SURE TO BECOME FAMILIAR WITH THE LO-CATION AND OPERATION OF ALL CONTROLS AND CHECK THEIR PROPER OPERATION (SEE PAR. "CONTROLS").



CARRY OUT A DAILY CHECK OF MAINTAINED-TYPE CONTROLS CORRECT FUNCTIONING, BEFORE STARTING MACHINE OPERATION.

Once the plug/socket connection has been made, turn on the machine using the master switch (Fig. 23 ref. 1).



11.0 AIR CONNECTION

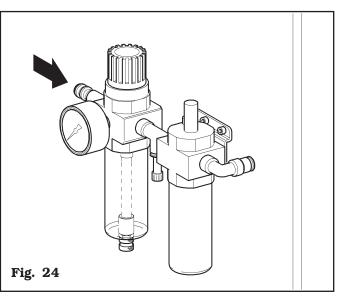
Only for LIBRAK380P - LIBRAK380PS -LIBRAK380PW - LIBRAK380PWS models



IN CASE OF A CHANCE SUP-PLY FAILURE, AND/OR BEFORE ANY PNEUMATIC CONNECTIONS, MOVE THE CONTROLS TO THE NEUTRAL POSITION.

Connect the wheel balancer to the centralised compressed-air system by means of the connection on the back of the machine (see **Fig. 24**).

The air system supplying the machine must be able to supply filtered and de-humidified air at a pressure between 8 and 10 bar. It must feature an on-off valve upstream of the machine.





1297-M003-3 B

Page 20 of 67

GB

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

12.0 FITTING THE WHEEL ON THE MANDREL



To achieve perfect balancing, the wheel must be carefully and properly fitted on the mandrel. Imperfect centring will inevitably cause unbalances.

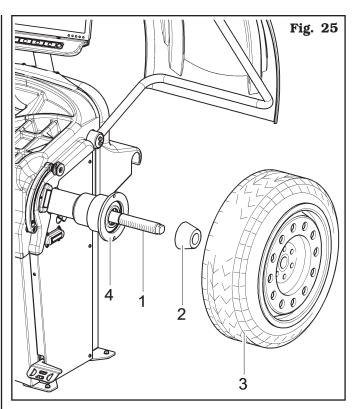


MOST IMPORTANT IS THAT ORIGI-NAL CONES AND ACCESSORIES ARE USED MADE SPECIFICALLY FOR USE ON THE WHEEL BAL-ANCER.

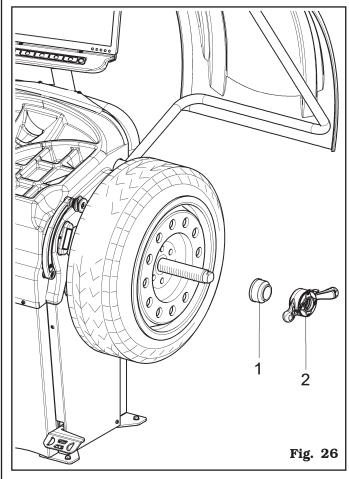
Wheel fitting using the cones provided is illustrated below. For alternative fittings, using optional accessories, refer to the special instructions provided separately.

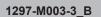
<u>12.1 Fitting of the wheel (LIBRAK380 -LIBRAK380S - LIBRAK380W -LIBRAK380WS)</u>

- 1. Remove any type of foreign body from the wheel (**Fig. 25 ref. 3**): pre-existing weights, stones and mud, and make sure the mandrel (**Fig. 25 ref. 1**) and the rim centring area are clean before fitting the wheel on the mandrel.
- Carefully choose the cone (Fig. 25 ref. 2) most suitable for the wheel to be balanced. These accessories must be selected according to the shape of the rim. Carefully position the wheel (Fig. 25 ref. 3), fitting the cone (Fig. 25 ref. 2) onto the mandrel (Fig. 25 ref. 1) carefully (otherwise this could seize) until this rests against the support flange (Fig. 25 ref. 4).
- 3. Fit the wheel with the inner side of the rim towards the wheel balancer and against the cone.



 Fit the protection cap (Fig. 26 ref. 1) in the nut (Fig. 26 ref. 2) and fasten against the wheel.





Page 21 of 67

GB

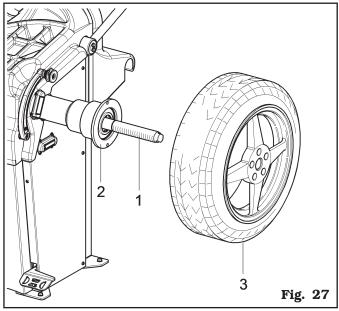
INSTRUCTION, USE AND MAINTENANCE MANUAL



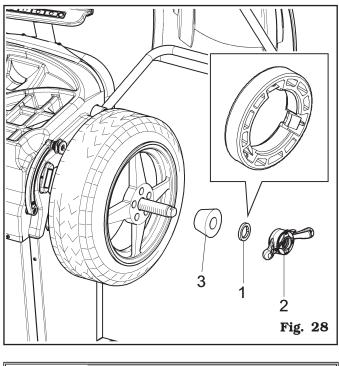
LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

Some aluminium wheels, with very high centring, must be fitted with the cone outside the wheel.

- 5. Clean the mandrel (**Fig. 27 ref. 1**) before fitting the wheel.
- 6. Fit the wheel (**Fig. 27 ref. 3**) with the inside of the rim towards the wheel balancer, until the wheel is up against the support flange (**Fig. 27 ref. 2**).



- 7. Fit the cone (**Fig. 28 ref. 3**) with the narrowest part turned towards the wheel.
- 8. Fit the pressure ring (Fig. 28 ref. 1) in the nut (Fig. 28 ref. 2) and fasten the cone (Fig. 28 ref. 3).

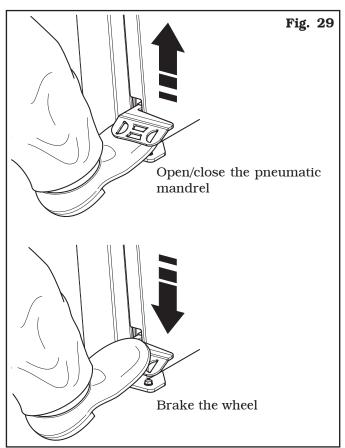


THE PRESSURE RING (FIG. 28 REF. 1) MUST BE MOUNTED WITH THE TEETH SIDE TOWARDS THE RING-NUT (FIG. 28 REF. 2).

<u>12.2 Fitting of the wheel (LIBRAK380P</u> <u>- LIBRAK380PS - LIBRAK380PW -</u> <u>LIBRAK380PWS)</u>



Open the pneumatic mandrel by means of the special pedal, see **Fig. 29**.



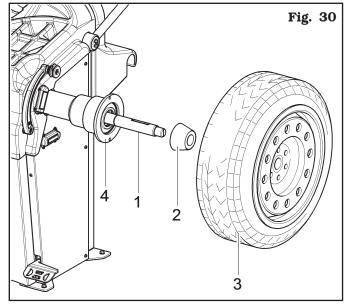
- 1. Remove any type of foreign body from the wheel (**Fig. 30 ref. 3**): pre-existing weights, stones and mud, and make sure the mandrel (**Fig. 30 ref. 1**) and the rim centring area are clean before fitting the wheel on the mandrel.
- Carefully choose the cone (Fig. 30 ref. 2) most suitable for the wheel to be balanced. These accessories must be selected according to the shape of the rim. Carefully position the wheel (Fig. 30 ref. 3), fitting the cone (Fig. 30 ref. 2) onto the mandrel (Fig. 30 ref. 1) carefully (otherwise this could seize) until this rests against the support flange (Fig. 30 ref. 4).
- 3. Fit the wheel with the inner side of the rim towards the wheel balancer and against the cone.



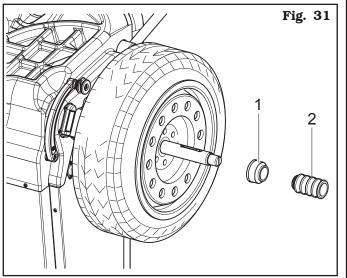
1297-M003-3_B

Page 22 of 67

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS



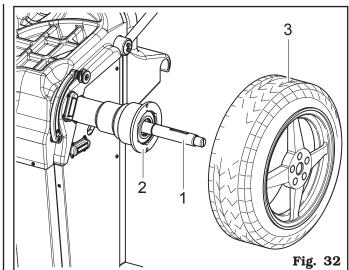
 Fit the protection cap (Fig. 31 ref. 1) in the bush (Fig. 31 ref. 2) and bring everything against the wheel.



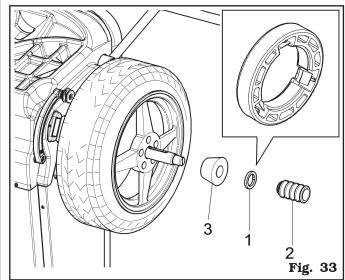
Lift the control pedal to close the mandrel and then clamp the wheel.

Some aluminium wheels, with very high centring, must be fitted with the cone outside the wheel.

- 5. Clean the mandrel (**Fig. 32 ref. 1**) before fitting the wheel.
- 6. Fit the wheel (**Fig. 32 ref. 3**) with the inside of the rim towards the wheel balancer, until the wheel is up against the support flange (**Fig. 32 ref. 2**).



- 7. Fit the cone (**Fig. 33 ref. 3**) with the narrowest part turned towards the wheel.
- 8. Fit the pressure ring (**Fig. 33 ref. 1**) in the bush (**Fig. 33 ref. 2**) and bring everything against the wheel.





THE PRESSURE RING (FIG. 33 REF. 1) MUST BE MOUNTED WITH THE DISCHARGE SIDE TOWARDS THE BUSH (FIG. 33 REF. 2).

9. Close the pneumatic mandrel by lifting the appropriate control pedal.



DURING MANDREL OPENING/ CLOSING OPERATIONS, BE CARE-FUL TO KEEP YOUR HANDS AND OTHER PARTS OF THE BODY AWAY FROM THE MANDREL.

GB

Page 23 of 67

GB

INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

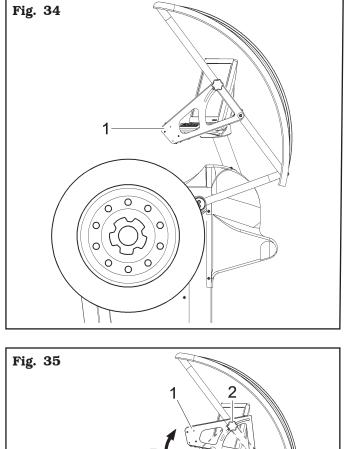
<u>12.3 Adjustment of ultrasound sensor</u> <u>support (only for LIBRAK380W -</u> <u>LIBRAK380PW - LIBRAK380WS -</u> <u>LIBRAK380PWS models)</u>

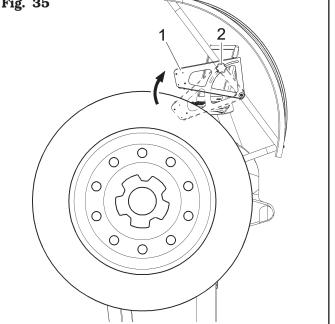
Ultrasound sensor support (**Fig. 34-35 ref. 1**) must be used in the "fully-lowered" position, as shown in **Fig. 34**.

However with wheels with great diameter, you can set it higher so that the wheel can be mounted easily onto the mandrel (see **Fig. 35**).

In order to carry out the adjustment, just loosen the handwheel (**Fig. 35 ref. 2**) and place the support in the desired position.

At the end tighten the handwheel (Fig. 35 ref. 2).





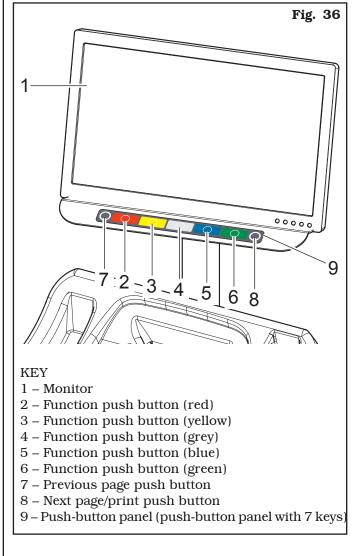


IF ACTIVATED, EACH TIME THAT THE WHEEL PROTECTION GUARD IS LOWERED, THE DEVICE DE-TECTS AUTOMATICALLY THE DI-MENSION OF THE WHEEL WIDTH.

13.0 CONTROL PANEL

The wheel balancers are equipped with a control panel equipped with a keyboard to interact/operate the controls presented in graphical form on the monitor. On the monitor are displayed all the instructions for the correct wheel balancing, for example indicating where the operator shall fit adhesive or clip weights and the

balancing mode and/or option used, as well as correct wheel rotation for inner/outer weights positioning.





1297-M003-3 B

Page 24 of 67

GB

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

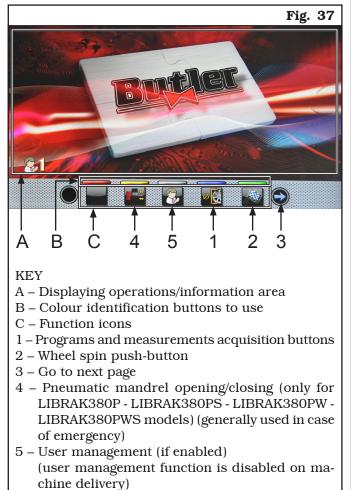
14.0 WHEEL BALANCING

14.1 Switching the machine on and off

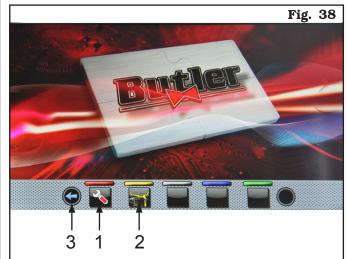
Press the "ON" switch (Fig. 23 ref. 1), located in the rear part of the equipment.

IN THE CASE OF PNEUMATIC MODELS, ON STARTING, THE PNEUMATIC MANDREL IS ALWAYS **OPENED. ALWAYS KEEP YOUR** HANDS AND OTHER PARTS OF THE BODY AWAY FROM THE MOV-**ING MANDREL.** ALSO TAKE CARE IF A WHEEL **IS ALREADY FITTED ON THE** MANDREL, AS THIS COULD BE FORCED OFF THE SHAFT DURING THE OPENING OF THE MANDREL ITSELF.

Wait a few seconds until the complete loading of the operational program. The equipment is ready to operate when the main screen "Home" appears on the monitor.



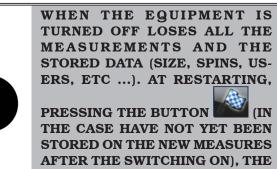
At the bottom of the main screen and each screen described below, there will be coloured rectangles (Fig. 37 ref. B) located above function identification icons (Fig. 37 ref. C). These functions are activated by pressing the appropriate coloured button on the push-button panel (Fig. 36 ref. 9). Press the button (Fig. 37 ref. 3) to display a second page where you can access the "Technical assistance" menu and the "Run-out" menu (see Fig. 38).



KEY

- 1 User menu
- 2 Run-out menu (visible only if the machine is fit or if the Run-out device is enabled)
- 3 Return to previous page

In order to turn off the machine, simply press the main switch on "OFF" (Fig. 23 ref. 1).



MACHINE DOES NOT PERFORM ANY OPERATION.

1297-M003-3 B

Page 25 of 67

GB

INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

14.2 Balancing programs setting

The setting of the balancing programs can be performed in two ways:

- through the gauge arm (rapid setting);
- through "Measurement being acquired" screen, ap-

pearing when the **ref.** 1).



button is pressed (**Fig. 37**

The setting modes are completely different even if they allow to reach the same result (but with different times).

<u>14.2.1 Programs rapid setting and meas-</u> <u>urements through distance-diameter</u> <u>caliper arm</u>

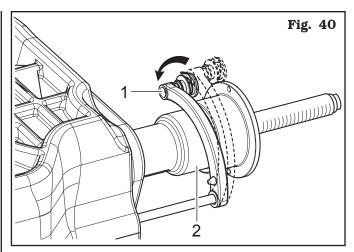
The use of the distance-diameter caliper arm allows the rapid automatic wheel balancing program and the measures entry. From page "Home":

- bring into contact the weights fitting gripper with the inner part of the rim (1 contact only) to select "STATIC" program (see **Fig. 39**).





REPEATEDLY BRINGING THE GAUGE'S ARM (FIG. 40 REF. 1) IN CONTACT WITH THE MANDREL (FIG. 40 REF. 2), THE PROGRAM WILL CYCLE FROM "STATIC" TO "STATIC 1" TO "STATIC 2" THEN RETURNING TO THE BEGINNING.



- bring into contact the weights fitting gripper with the inner part of the rim (2 contact points) (see **Fig. 39**) to select "ALU-S" program.



REPEATEDLY BRINGING THE GAUGE'S ARM (FIG. 40 REF. 1) IN CONTACT WITH THE MANDREL (FIG. 40 REF. 1), THE PROGRAM WILL CYCLE FROM "ALU-S" TO "ALU-S1" TO "ALU-S2" THEN RE-TURNING TO THE BEGINNING.

WHENEVER THE DISTANCE-DI-AMETER CALIPER AND/OR THE EXTERNAL DATA GAUGE (GAR307 OR GAR305, SEE FIG. 41) (IF ANY) IS KEPT IN POSITION FOR A FEW SECONDS AGAINST THE RIM (UNTIL THE MACHINE MAKES AN APPROPRIATE SOUND NOTIFICA-TION), THE POSITION IS STORED AND THE VALUES MEASURED IN THE PRE-ARRANGED FIELDS IN THE SELECTED WHEEL BALANC-ING PROGRAM ARE LOADED.

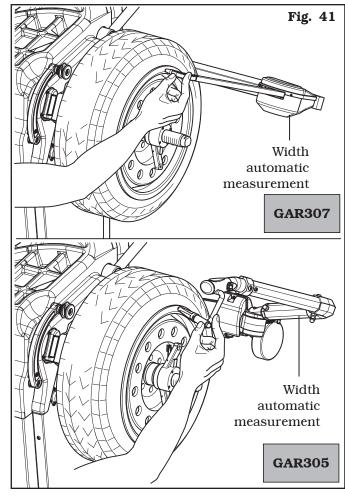


1297-M003-3_B

Page 26 of 67

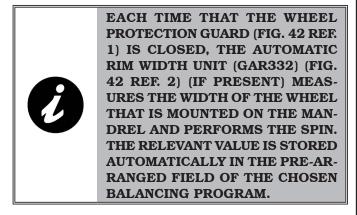
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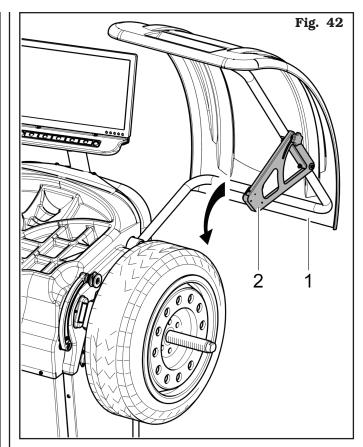
LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS



- After entering all the required measures, you can spin

the wheel by pressing the button **and closing** the protective guard.





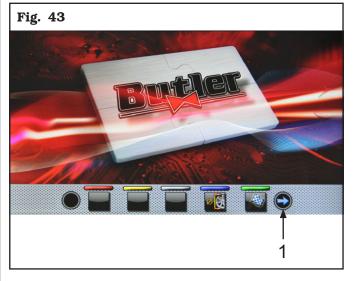
• Measuring procedure of electronic RUN-OUT with the distance-diameter caliper arm.

The electronic RUN-OUT measuring device is useful to check if the rim has some imperfections. To access the screen to choose the rim control mode, proceed as follows:

- from the "Home" page, press the button



(Fig. 43 ref. 1) and then the button **Fig. 44 ref. 1**).



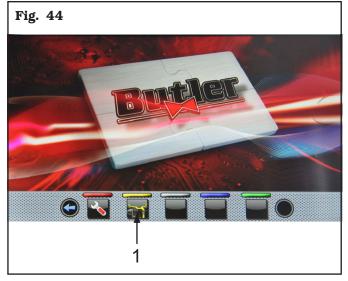


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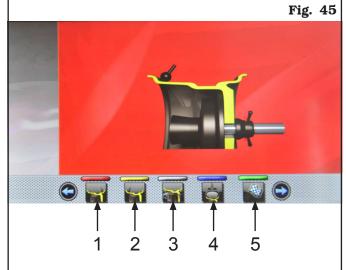
INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS



- On the monitor you will see the screen below where there are buttons to select the type of flaw detection.



- 1 Rim inner right lateral fault detection (enabled only with GAR303)
- 2 Rim inner left lateral fault detection (enabled only with GAR303)
- 3 Rim inner lateral fault detection
- 4 Tyre fault detection (enabled only with GAR303)
- 5 Wheel spin push-button

Tyre fault detection (lateral inner side).

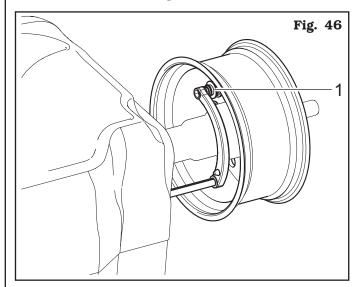
From the screen page of **Fig. 45** press the button (**Fig. 45 ref. 3**). The screen page below is displayed.



Place the distance-diameter caliper grippers (**Fig. 46 ref. 1**) on the inner side of the rim, as shown in **Fig. 46**.

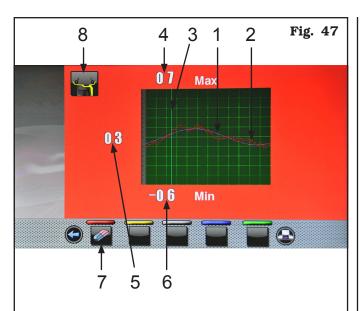


Press the green button on the monitor **(Fig. 45 ref. 5)** to start the rim analysis procedure. The circle starts to spin at low speed (30 rpm) and at the end of the measurement the roundness graph appears, as shown in **Fig. 47**.





LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS



- 1 Fundamental sine wave(fuchsia-colouredgraph)
- 2 Graph of detected roundness (red)
- 3 Slider that indicates the current position of the rim ("12 o'clock") (green)
- 4 Value in mm of the highest peak of imperfection detected on the rim
- 5 Value in mm of imperfection of the rim at the current position
- 6 Value in mm of the lowest peak of imperfection detected on the rim
- 7 Graph deleting button
- 8 Run-out mode carried out where the data is displayed in the graph

The red graph (**Fig. 47 ref. 2**) represents exactly the geometric shape of the rim. The more the circle is round and linear, the more the graph is flat, unlike the more the circle has deficiencies, the more the graph is large.

You can follow the eccentricity in the graph by manually turning the rim, the green-coloured-slider (**Fig. 47 ref. 3**), indicates the position of the rim in "12 o'clock" position.

<u>14.2.2 Programs setting through "Measure-</u> <u>ment being acquired" screen page</u>



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From the "Home" page, press the **Sec. 37 ref. 1**) button to display the "Measurement being acquired" screen below:



PRESS THE BUTTON (Fig. 37 ref. 1) TO DISABLE AU-TOMATIC FUNCTION OF DIS-TANCE-DIAMETER CALIPER ARM WHEEL BALANCING SELECTION, DESCRIBED IN PAR. 14.2.1. TO BE ABLE TO REUSE THE AUTOMATIC FUNCTION TO SE-LECT THE WHEEL BALANCING PROGRAM WITH GAUGE ARM, IT IS NECESSARY TO RETURN TO "HOME" PAGE, BY PRESSING THE

The selection of the wheel balancing program is possible in 2 ways:

BUTTON

- with highlighted program (blue colour) by pressing the

With this mode only the 11 standard programs can be selected (DYN, ALU-S, ALU-S1, ALU-S2, STAT, STAT-1, STAT-2, ALU-1, ALU-2, ALU-3, ALU-4).



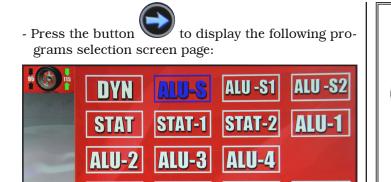
Page 29 of 67

GB

INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS



EACH TIME THAT THE WHEEL PROTECTION GUARD IS CLOSED; THE AUTOMATIC RIM WIDTH UNIT (GAR332) (FIG. 1 REF. 20) (IF PRESENT) MEASURES THE WIDTH OF THE WHEEL THAT IS MOUNTED ON THE MANDREL. THE RELEVANT VALUE IS STORED AUTOMATICALLY IN THE PRE-AR-RANGED FIELD OF THE CHOSEN BALANCING PROGRAM.

- After entering all the required measures, you can spin

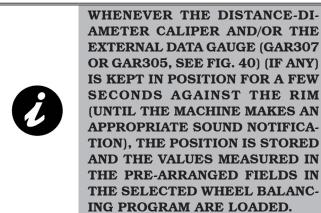
the wheel by pressing the button the protective guard.



Use the arrows and/or to select the wished mode (blue). In this mode you can select the 11 standard programs (listed above) and special programs (PAX360, PAX420, PAX460, PAX700).



AFTER YOU HAVE SELECTED THE DESIRED PROGRAM, USE THE DISTANCE-DIAMETER CALIPER AND/OR THE EXTERNAL DATA GAUGE (GAR307 OR GAR305) (IF ANY) TO DETECT THE MEASURES REQUIRED BY THE PROGRAM.



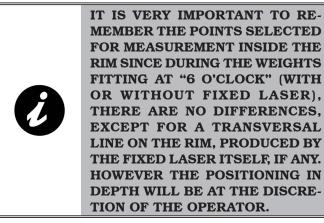


1297-M003-3_B

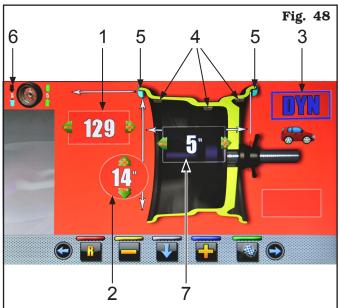
Page 30 of 67

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

<u>14.3 Indicative display of points where to</u> <u>detect measures/to fit weight</u>



Depending on the type of program selected, the machine shows on the monitor the guideline points where to take measures and, consequently, where you must apply weights (**Fig. 48 ref. 4-5**).



KEY

- $1 1^{st}$ weight fitting point distance
- 2 Rim diameter
- 3 Balancing mode
- 4 Point at which to take the measure/adhesive weight fitting
- 5 Point at which to take the measure/clip weight fitting
- 6 Last unbalance detected by the machine
- 7 Rim width

THE MORE THE POINTS CHOSEN FOR THE PROBING ARE DISTANT FROM EACH OTHER THE MORE THE BALANCING WILL BE EFFEC-TIVE.

14.3.1 Weights positioning

The monitor displays when it is absolutely necessary that the weight is applied at "12 o'clock" position. Pay particular attention to the content of the weights iden-

tification icons since if the following words H12 are displayed, then the icon corresponding weight has to be applied at "12 o'clock" position (typical of ALU-S1, ALU-S2 programs).



IF ALL MEASURES REQUIRED BY THE PROGRAM HAVE NOT BEEN TAKEN/INSERTED, THE MACHINE DOES NOT ALLOW THE WHEEL SPIN TO DETECT THE UNBAL-ANCE.

14.4 Displaying the active/modifiable field

During the various phases of measures detection, the active field turns blue.



Pressing the buttons **and** or **button** you can change the value and/or program inside the active field. To <u>change</u> the selected active field, simply press the button

until the desired field is coloured blue.



THE SELECTION OF THE ACTIVE FIELD IS DONE BY HIGHLIGHT-ING THE FIELDS IN A CLOCKWISE DIRECTION. Page 31 of 67

GB

INSTRUCTION, USE AND MAINTENANCE MANUAL

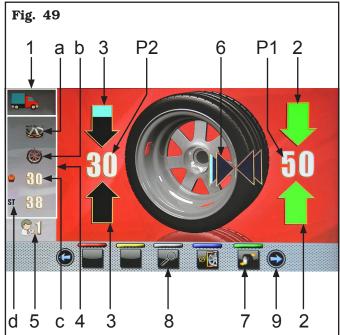


LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS



<u>14.5 Wheel balancing screen page descrip-</u> <u>tion</u>

After executing the spin of the wheel, the monitor displays a series of important information that helps the operator in his operations and subsequent choices.



KEY

- 1 Measures used by the program to perform the spin and detect the values in P1 P2
- P1 Weight to be fitted on rim outer side
- P2 Weight to be fitted on rim inner side
- 2 Wheel placed to fit the weight on wheel outer side (arrows both green)
- 3 Wheel not placed to fit the weight on wheel inner side (blue/black arrows)
- 4 Wheel balancing suggestions
- 4a SPLIT Program (Clip weights program) or MATCHING Program
- 4b SPOKES Program (program with adhesive weights)
- 4c ECO-WEIGHT Program with weight value to be fitted (if the value is of blue, the machine advises not to use it)
- 4d STATIC Program
- 5 N° user (if selected)
- 6 Arrows indicating the weight fitting point with distance-diameter caliper arm
- 7 Wheel repositioning button for weights fitting
- 8 Display the actual weight
- 9 By pressing the button vou will see the following page where you can select one of the programs suggested by the machine.



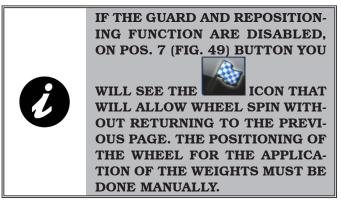
1297-M003-3_B

Page 32 of 67

GB

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

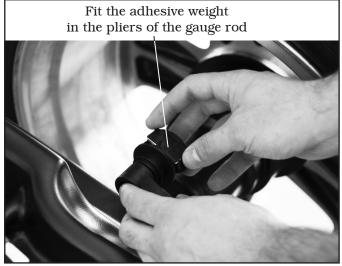




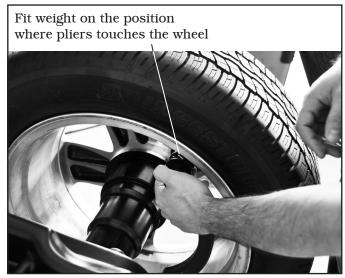
14.5.1 Balancing mode

The machine has the ability to perform the wheel balancing (weights fitting) in 3 different ways:

- using the distance-diameter caliper arm with weights fitting grippers;
- using the mobile laser pointer at "6 o'clock" (only for LIBRAK380S - LIBRAK380PS -LIBRAK380WS - LIBRAK380PWS models);
- weights fitting at "6 o'clock" (without the use of lasers).
- Weights fitting with distance-diameter caliper arm.
 - 1. Place the adhesive weight on the arm grippers.



- 2. Pull out the gauge until the arrows (**Fig. 49 ref. 6**) both turn green.
- 3. Rotate the gauge arm until the weight touches the rim.



4. Bring the distance-diameter caliper arm in resting position, after having led it towards the mandrel to unlock it from the position of weight application.



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS



- 5. Press the **button** to change the weight fitting side.
- 6. Proceed in the same way as described in points 1-2-3.



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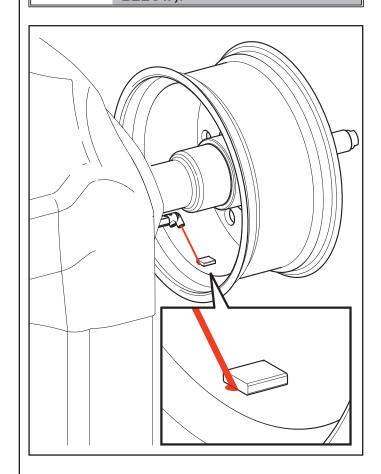
BEFORE REMOVING THE DIAME-TER-DISTANCE CALIPER, PRESS THE BRAKE PEDAL AND HOLD IT DOWN UNTIL THE WEIGHT HAS NOT BEEN APPLIED, ENSURING IN THIS WAY THAT, DURING THESE PHASES, THE WHEEL CAN NOT ROTATE. • Weights' application with mobile laser pointer at "6 o'clock" (only for LIBRAK380S - LIBRAK380PS - LIBRAK380WS - LIBRAK380PWS models).



At the end of the spin, on the rim at "6 hours" is displayed a laser pointer indicating the exact point where the weight has to be applied.



THE WEIGHT HAS TO BE APPLIED FROM THE POINT HIGHLIGHTED BY THE POINTER TOWARDS THE INSIDE OF THE RIM, AND ITS CENTRE LINE MUST BE RIGHT BY THE SAME POINTER (SEE FIGURE BELOW).





1297-M003-3 B

GB

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

• Weights fitting at "6 o'clock" (without the use of lasers).

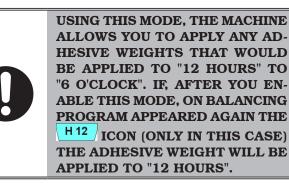


SARY THAT THE RELEVANT FUNC-TION IS ENABLED **ON THE** MENU "OPTIONS" DESCRIBED IN PAR. 15.1.

TO USE THIS MODE, IT IS NECES-



TO USE THIS WEIGHT APPLICA-TION MODE THE OPERATOR **MUST REMEMBER THE PRECISE** POINT WHERE THE MEASURE-MENT WAS TAKEN WITH THE **DISTANCE-DIAMETER CALIPER** ARM.



At the end of the spin, the wheel stops in place to apply the weight at "6 o'clock". The positioning of the weight (s) in depth shall be at the discretion of the operator, depending on where remembers taking the measure.



BE SURE TO APPLY THE (INTER-NAL OR EXTERNAL) WEIGHT AS **INDICATED BY THE 2 GREEN** ARROWS (Fig. 49 ref. 2 or 3) ON THE CORRESPONDING MONITOR SCREEN PAGE.

14.6 Use of machines with disabled automatic gauge

The entry of diameter, width and distance measures of the machine rim must be performed manually. The reading of these measures can be made as follows:

- visual readout on caliper graduated scale (distance);
- values readout on rim (diameter and width);
- width value detection with manual caliper (width) (see Fig. 50).



MANUAL CALIPER. Width manual detection

Fig. 50

14.6.1 Manual setting of wheel dimensions

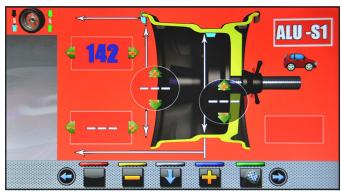
In case the operator wants to edit and/or manually enter the wheel dimensions, proceed as follows:

- from the desired measurement mode screen, press

until highlighting with blue the field the button to modify/edit;



- press the buttons or until reaching the desired value;
- to shift to the next value. press button



1297-M003-3 B

Page 35 of 67

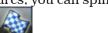
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INSTRUCTION, USE AND MAINTENANCE MANUAL



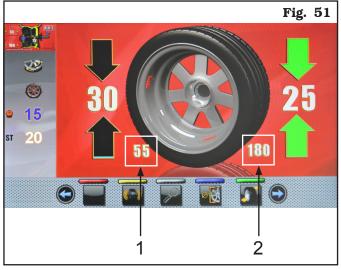
LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

After entering all the required measures, you can spin



the wheel by pressing the button and closing the protective guard.

NOTE: if the distance-diameter caliper is disabled, the displayed page for detected unbalance is as follows:



In this screen page, in addition to the information of the detected unbalance, there are measurements in mm at which you must remove the caliper's arm (**Fig. 51 ref. 1-2**) to apply the weights inside the rim.

14.7 Standard balancing programs

14.7.1 Static

The STATIC program permits balancing wheels by fitting adhesive weights on the outer and inner sides of the rim. Enter the measurements (see Par. 14.2.1 or 14.6.1) and proceed as described in Par. 14.5. At the end of the procedure, the wheel balancing condi-



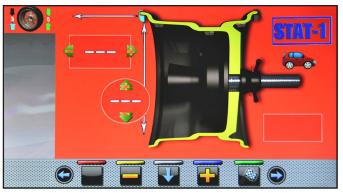
The procedure has now been completed.

<u>14.7.2 Static-1</u>

STATIC 1 function is a procedure that offsets wheel vibrations using a single weight with clip on a single plane positioned exactly at 12 o' clock.

Enter the measurements (see Par. 14.2.1 or 14.6.1) and proceed as described in Par. 14.5 "Dynamic balancing" (only for wheel inner side).

At the end of the procedure, the wheel balancing conditions can be checked by performing a trial spin.



The procedure has now been completed.

<u>14.7.3 Static-2</u>

STATIC 2 function is a procedure that offsets wheel vibrations using a single adhesive weight on a single plane positioned exactly at 12 o' clock.

Enter the measurements (see Par. 14.2.1 or 14.6.1) and proceed as described in Par. 14.5 "Dynamic balancing" (only for wheel inner side).

At the end of the procedure, the wheel balancing conditions can be checked by performing a trial spin.



The procedure has now been completed.



1297-M003-3 B

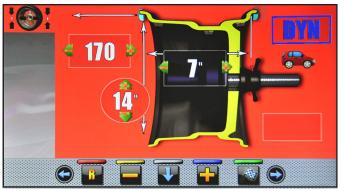
Page 36 of 67

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

<u>14.7.4 Dynamic</u>

The DYNAMIC program allows the wheels balancing by fitting two clip adhesive weights: one on the outside and one on the inside rim. Enter the measurements (see Par. 14.2.1 or 14.6.1) and proceed as described in Par. 14.5.

At the end of the procedure, the wheel balancing conditions can be checked by performing a trial spin.



The procedure has now been completed.

14.7.5 ALU-S

ALU-S program permits balancing wheels by two fitting adhesive weights on the outer and inner sides of the rim. Enter the measurements (see Par. 14.2.1 or 14.6.1) and proceed as described in Par. 14.5.

At the end of the procedure, the wheel balancing conditions can be checked by performing a trial spin.



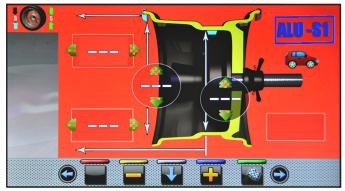
The procedure has now been completed.

14.7.6 ALU-S1

ALU-S1 function permits balancing wheels with light alloy rims by fitting adhesive weights on the outer side and weight with clip on inner side of wheel (at 12 o' clock).

Enter the measurements (see Par. 14.2.1 or 14.6.1) and proceed as described in Par. 14.5 (the inner weight is with clip).

At the end of the procedure, the wheel balancing conditions can be checked by performing a trial spin.



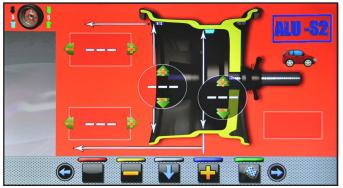
The procedure has now been completed.

<u>14.7.7 ALU-S2</u>

ALU-S2 function permits balancing wheels with light alloy rims by fitting two adhesive weights: one on the outer and one on inner sides of the rim (the inner weight is at 12 o' clock).

Enter the measurements (see Par. 14.2.1 or 14.6.1) and proceed as described in Par. 14.5.

At the end of the procedure, the wheel balancing conditions can be checked by performing a trial spin.



The procedure has now been completed.

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INSTRUCTION, USE AND MAINTENANCE MANUAL



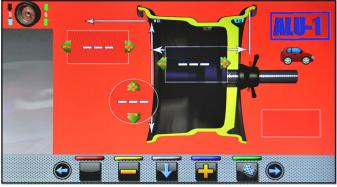
LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

14.7.8 ALU-1

ALU-1 function permits balancing wheels with light alloy rims by fitting adhesive weights on the outer and inner sides of the rim at 12 o' clock.

Enter the measurements (see Par. 14.2.1 or 14.6.1) and proceed as described in Par. 14.5.

At the end of the procedure, the wheel balancing conditions can be checked by performing a trial spin.



The procedure has now been completed.

14.7.9 ALU-2

ALU-2 function balances wheels with light alloy rims by fitting adhesive weights on the outside and inside of the rim. The position of the outer weight is not visible but hidden inside. Enter the measurements (see Par. 14.2.1 or 14.6.1) and proceed as for dynamic unbalance.

At the end of the procedure, the wheel balancing conditions can be checked by performing a trial spin.



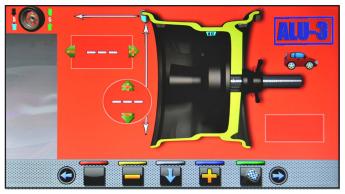
The procedure has now been completed.

<u>14.7.10 ALU-3</u>

ALU-3 function is a procedure that uses mixed weights to offset wheel unbalance: weight with clip on inner side of wheel, adhesive weight on outer side, not visible because inside the rim.

Enter the measurements (see Par. 14.2.1 or 14.6.1) and proceed as for dynamic unbalance.

At the end of the procedure, the wheel balancing conditions can be checked by performing a trial spin.



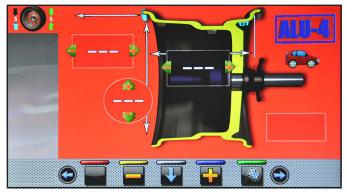
The procedure has now been completed.

<u>14.7.11 ALU-4</u>

ALU-4 function is a procedure that uses mixed weights to offset wheel unbalance: weight with clip on inner side of wheel, adhesive weight on outer side.

Enter the measurements (see Par. 14.2.1 or 14.6.1) and proceed as for dynamic unbalance.

At the end of the procedure, the wheel balancing conditions can be checked by performing a trial spin.



The procedure has now been completed.



1297-M003-3 B

Page 38 of 67

GB

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

14.8 Optional balancing programs

14.8.1 ECO-WEIGHT mode



TO USE THE ECO-WEIGHT PRO-CEDURE IT IS NECESSARY THAT THE DISTANCE-DIAMETER CALI-PER ARM IS ENABLED IN THE "OPTIONS" MENU DESCRIBED IN PAR. 15.1.



THE ECO-WEIGHT PROCEDURE CAN ONLY BE USED WITH THE PROGRAM ALU-S.

This procedure represents a modern system for the reset of the unbalance in order to reduce weights consumption. This procedure ensures a fastest execution of the operations, thanks to a lesser number of spins and repositioning.

After making the wheel spin in ALU-S mode, the monitor shows the total of 2 adhesive weights to precisely correct STATIC and DYNAMIC unbalance.



It is possible to fit a single weight at a predetermined distance from the machine, so as to optimize the weight consumption and reduce both the DYNAMIC and any remaining STATIC unbalance as much as possible. Unlike the standard STATIC procedure, the ECO-WEIGHT procedure, though only using one weight, also considerably reduces the DYNAMIC unbalance, because the fitting distance of the weight on the rim is also calculated.

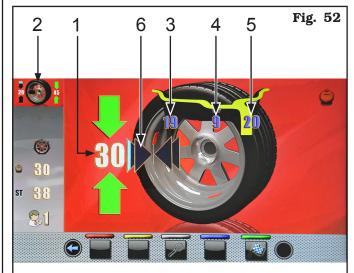
From ALU-S unbalance results page, if there is con-



siderable static unbalance, press the button display on the following monitor screen:



Press button **to** select such procedure and bring automatically the wheel into weight fitting position.



KEY

- 1 Only weight to be fitted
- 2 Last program and last values used for the spin
- 3 Residual dynamic unbalance value (if the value is blue it is not to carry out ECO-WEIGHT procedure)
- 4 Static unbalance value (if the value is blue it is not to carry out ECO-WEIGHT procedure)
- 5 Residual dynamic unbalance value (if the value is blue it is not to carry out ECO-WEIGHT procedure)
- 6 Arrows indicating the weight fitting point with distance-diameter caliper arm



Page 39 of 67

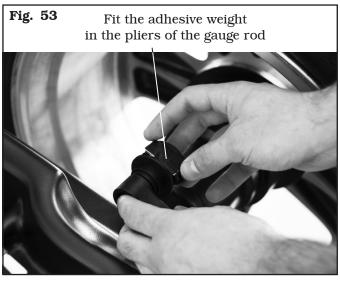
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INSTRUCTION, USE AND MAINTENANCE MANUAL

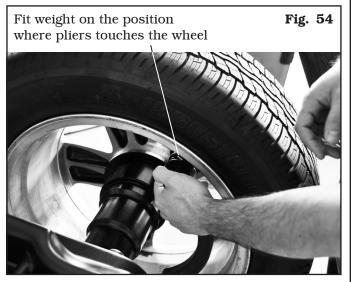


LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

Press the brake pedal and fit the adhesive weight inside pliers as shown in **Fig. 53**.



Pull out the gauge rod until the arrows (**Fig. 52 ref. 6**) turn green.



At the end of the procedure, the wheel balancing conditions can be checked by performing a trial spin. The ECO-WEIGHT procedure has now been completed. **IMMEDIATELY AFTER HAVING** SELECTED THE ECO-WEIGHT **PROCEDURE, YOU CAN KNOW** IN ADVANCE THE TWO DYNAMIC UNBALANCES AND THE STATIC **RESIDUE IN ORDER TO DECIDE** WHETHER IT IS CONVENIENT TO CONTINUE (SEE FIG. 52). **IF BOTH DYNAMIC UNBALANCES** AND STATIC RESIDUE ARE SHOWN AS WHITE VALUES ON THE MONI-TOR, THIS MEANS THAT THE **PROGRAM HAS DECIDED THAT IT IS BETTER TO CONTINUE. WHILE** IF. ON THE OTHER HAND. ONE OR MORE VALUES ARE BLUE, THE **PROGRAM SUGGESTS USING THE** STANDARD ALU-S PROCEDURE. PRESS BUTTON **ONCE, THE** TWO RESIDUAL DYNAMIC UNBAL-ANCES WILL BE DISPLAYED ON MONITOR. PRESS BUTTON ONCE MORE, THE CALCULATED REAL STATIC WEIGHT AND THE RE-SIDUAL STATIC WEIGHT WILL BE **DISPLAYED ON SCREEN.** IF YOU ARE NOT WISHING TO OP-ERATE WITH ECO-WEIGHT PRO-CEDURE, PRESS BUTTON **ONCE MORE, ALU-S UNBALANCE** VALUES WILL BE DISPLAYED AGAIN.

WHILE IF YOU WISH TO OPERATE WITH THE ECO-WEIGHT PROCE-

DURE, PRESS BUTTON



A LONGER TIME (OR KEY) TO GO BACK TO THE RESIDUAL DYNAMIC/ECO-WEIGHT WEIGHT DISPLAY SCREENS.



1297-M003-3 B

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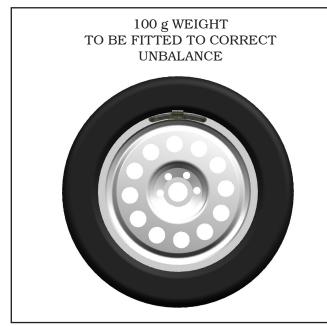
LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

14.8.2 SPLIT mode

Split procedure proves useful when the dynamic unbalance of a wheel is fairly high and the weight to be fitted is not available, for instance a 100 g weight. It's possible then to correct the unbalance dividing the amount of weight into two weights of smaller size.

Split procedure eliminates errors by using "DYNAMIC" program, for example by manually fitting two 50 g weights close to one another, instead of only a 100 gr one.

For example:



TWO SMALLER WEIGHTS (50g) FITTED MANUALLY



TWO SMALLER WEIGHTS (55g) USING SPLIT PROCEDURE



Proceed to "DYNAMIC" unbalance measurement displaying by performing a standard wheel spin.



Once detected the unbalance values, verify that the machine displays the ability to use the "SPLIT" option

(**Fig. 49 ref. 4a**). Press button \bigvee to shift to the next screen page.



Press button **to** enter "SPLIT" function. On the monitor screen will be displayed where you must enter the value of the weights to be fitted.



INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS



Press button to select the outer weight to edit. Press buttons or to increase or decrease

the total weight to be fitted.



THE BLUE VALUE INDICATES WHICH VALUE IS ACTIVE AND YOU ARE EDITING.

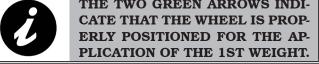


THE HIGHER THE CHOSEN WEIGHTS VALUE IS, THE MORE THEY WILL BE SPACED.

After choosing the value of the weights to be fitted,

press button **button** to position the wheel for the application of the 1st clip weight.





Fit the clip weight of the chosen value at 12 o'clock on

the outside of the wheel. Press again button \mathbf{P} to position the wheel for the fitting of the 2^{nd} clip weight.



Fit the clip weight of the chosen value at 12 o'clock

on the outside of the wheel. Press button **w** to highlight the value of the weights to be fitted on the inside of the wheel.



Repeat the above steps for the weights to be fitted inside the wheel.

At the end perform again a checking spin to see that you have applied the weights correctly.



1297-M003-3 B

Page 42 of 67

GB

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

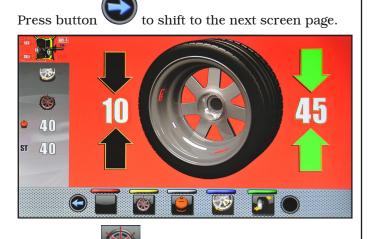
14.8.3 Weights hidden behind spokes mode

Adhesive correction weight positioning may not look attractive on some types of rims. In this case, "weights hidden behind spokes" mode can be used: it splits any correction weight on the outer side into two parts to be hidden behind rim spokes. It can be used in both ALU-S or STATIC modes.

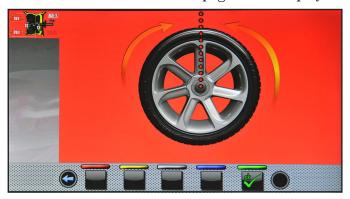
Display the ALU-S or STATIC, unbalance measurements, by performing a standard wheel spin.



Once detected the unbalance values, verify that the machine displays the ability to use the "spokes" options (**Fig. 49 ref. 4b**).



Press button **to enter the relevant function**. On the monitor the next screen page will be displayed:



Bring any spoke upwards at "12 o'clock" position and



Lead to "12 hours" the 2nd spoke. The machine will automatically calculate the total number of spokes. If the value shown on the screen (A) is correct, press the



The machine automatically calculates weight position in two positions hidden behind the spokes. The monitor shows the amount of weight to be applied behind the FIRST spoke and the rim will reach the position to apply the FIRST weight.



Extract the gauge rod, and fit the FIRST weight in the position shown by the machine, as explained in

Par. 14.5.1. Press the button to confirm that they have applied the FIRST weight and to automatically position the wheel for the fitting of the 2nd weight. The monitor shows the amount of weight to be applied behind the SECOND spoke.

Pull out the gauge rod and fit the SECOND weight in the position shown by the machine, as done for the first weight.



Press the button voto confirm that you have applied the SECOND weight and get back to the initial situation of unbalance, before performing the "weights hidden behind the spokes" procedure

Perform another test spin. The "weights hidden behind spokes" procedure is completed.

1297-M003-3 B

Page 43 of 67

GB

INSTRUCTION, USE AND MAINTENANCE MANUAL



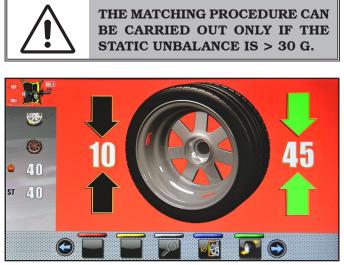
LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

Complete the operation by adding an additional weight inside the rim as required by the selected mode (ALU-S or STATIC).

14.8.4 matching mode

The Matching procedure offsets strong unbalance, reducing the weight quantity to be fitted on the wheel to achieve balancing. This procedure permits reducing unbalance as much as possible by offsetting the tyre unbalance with that of the rim in any used program.

Proceed to unbalance measurement displaying by performing a standard wheel spin.



Once detected the unbalance values, verify that the machine displays the ability to use the "matching" options (**Fig. 49 ref. 4a**).

Press button

to shift to the next screen page.

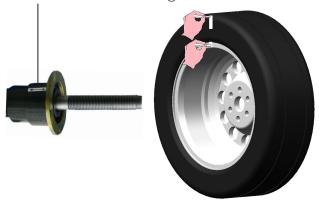


Press button **be** to enter the relevant function. On the monitor the next screen page will be displayed:



STEP 1. Move the slider on the flange to the "12 o'clock" position. Make a reference mark, using chalk for instance, on the rim and tyre, in line with the arrow on the flange, so as to be able to fit the rim back on in the same position on the machine.

Make a reference mark on the rim and tyre, in line with the arrow on the flange



Press button

completed.

to confirm that step 1 has been

On the display the next screen page will be displayed:





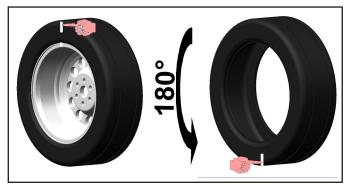
1297-M003-3 B

Page 44 of 67

GB

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

STEP 2. Remove the wheel from the wheel balancer. Remove the tyre and turn it on the rim through 180°.



Fit the wheel back on the wheel balancer, positioning the reference mark on the rim in line with the arrow on the flange.

Position the reference mark on the rim in line with the arrow on the flange





Position the tyre reference mark on the opposite side to the arrow on the flange

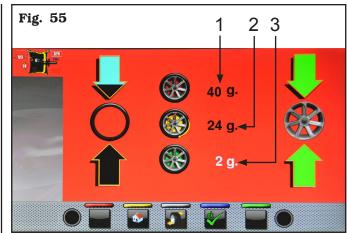
Press button completed.

to confirm that step 2 has been

On the display the next screen page will be displayed suggesting to perform a spin of the wheel.



After having fitted wheel back in position, close the protection guard to make an automatic wheel spin. At the end of the spin the monitor will display the following screen:

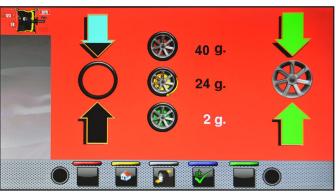


In this screen you will see the dynamic unbalance that the wheel had before performing the operation (**Fig. 55 ref. 1**), the dynamic unbalance after having rotated the tyre of 180° compared to the rim (**Fig. 55 ref. 2**) and the unbalance which can be obtained following the directions of the machine (**Fig. 55 ref. 3**).

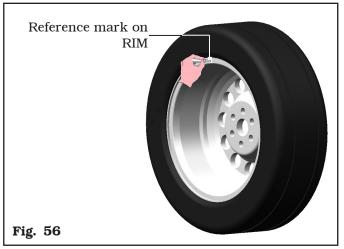
STEP 3. If the value of possible unbalance reduction is high, you can proceed as follows:

- Cancel the previously made reference marks. Put new signs, as described below.

- Press the button to bring the wheel into position.



Make the reference mark on RIM at 12 o' clock (see **Fig. 56**).



Page 45 of 67

GB

INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS



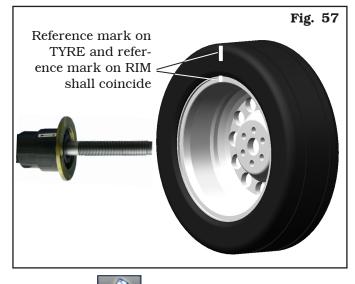


Mark the reference mark on the TIRE at "12 o'clock" position.

ok

Press button **to** confirm that step 3 has been completed.

STEP 4. Remove the wheel from the wheel balancer. Dismount and remount the tyre on the rim so as to bring the two reference marks (rim and tyre) to coincide. Refit the wheel on the balancer (see **Fig. 57**) with the two reference marks next to the arrow on the flange.



Press button completed.

to confirm that step 4 has been

Perform another spin closing the protection guard, to check the expected unbalance reduction and correct any residual unbalance, as described in Chap. 14.5.1.

14.9 Special balancing programs

<u>14.9.1 Pax</u>

PAX mode is a special procedure specially devised to balance wheels using the "PAX System ®". 2 adhesive weights on different planes are used on rim inner side.

To launch a PAX measurement, proceed as follows:

- Make sure there are no stones and/or mud on the wheel. Remove any counterweights. Fit the wheel and make sure it is properly fastened (see Chap. 12).

- Press witton from "Home" page. On the screen

that appears, press the button \bigvee to switch to measuring mode selection screen below.

	DYN	ALU-S	ALU -S1	ALU -S2
	STAT	STAT-1	STAT-2	ALU-1
	ALU-2	ALU-3	ALU-4	
-	PAX 360	PAX 420	PAX 460	PAX 700
(•		→	0

Use the arrows or to select PAX mode.

At the end press push button **Define**. The machine will be configured as follows to perform the measurement and on the video screen will appear the indication of the specific measures of the selected wheel type.

Close the protection guard to perform the automatic wheel spin.

In just a few seconds, the wheel runs at normal speed and the monitor shows wheel rotation.

After the spin, the wheel stops automatically, taking into account the measured unbalance so that the fitting position of the weight will be at 12 o' clock.

The monitor show the weight required to correct the unbalance.

Open the protection guard and proceed to fit the adhesive weight as shown for the ALU-S mode (see Par. 14.7.5).



1297-M003-3 B

GB

Page 46 of 67

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

14.10 Recalculation function

After making a spin, the wheel automatically stops, indicating the weight/s to be fitted and its/their position. In case the operator does not want the type of wheel balance proposed by the machine (program type, weights size, etc ...), proceed with the re-calculation of the wheel balancing without rerunning the spin of the wheel.

To do this, proceed as described below:



- press the button to return to the measures detection/program selection page;
- select a new balancing program as indicated in Par. 14.2.2:
- take with the gauge arm the measures required by the selected program;



- press button to perform the re-calculation. The monitor will display the weights and the positions in which they will be applied.

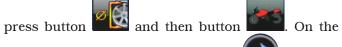
If also in this case the operator should decide to further modify the balancing program, it is sufficient to proceed as described above without having to spin the wheel.

When the result of the recalculation does not satisfy the operator, it is recommended to do a spin of the wheel to confirm the findings from the operation of recalculation itself.

After the launch of the wheel, the machine, in addition to displaying the unbalance value, draw up automatically all the programs measurement fields that are consistent with those measures that were taken previously and at the same time erases all measures which are not consistent.

14.11 Motorbike mode wheel balancing

By enabling "motorbike wheel balancing" function, the wheel balancers can also balance motorbike wheels. Before detecting the wheel sizes (see Par. 14.2.2), select motorcycle wheel balancing mode proceeding as described below:



screen that appears, press the button to switch to programs and measurements acquisition selection screen below.



Use the arrows select the wished

mode. At the end press push button The machine will be configured as follows to perform the measurement in the desired mode and on the screen will appear an indication showing the measures that will be acquired.

The "motorcycle" mode automatically recalculates the wheel distance measurement, increasing this by the length of the optional extension GAR181 A1.

To fit the extension (Fig. 58 ref. 2), first press the threaded ring nut (Fig. 58 ref. 1) in the hole provided and then screw the plastic terminal (see Fig. 58).



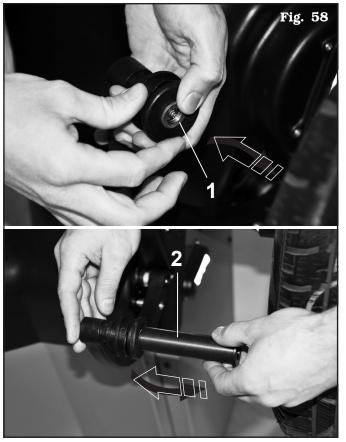
THE EXTENSION WILL ONLY HAVE TO BE SCREWED UP WHEN **BALANCING IS PERFORMED IN** "MOTORBIKE" MODE.



INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS



Balancing procedures are identical for both modes (car/motorbike).

By selecting motorbike mode, besides DYNAMIC balancing (see Par. 14.7.4) STATIC balancing and/or ALU-S (Par. 14.7.1 and/or 14.7.5) can also be performed.

15.0 USER MENU (OPTIONS AND CALI-BRATION)

From the main page "Home" press the button

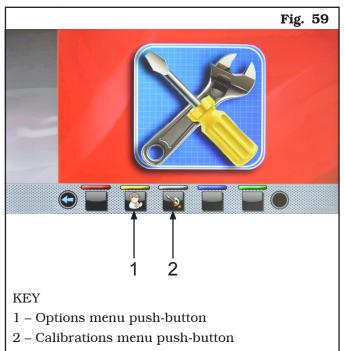


to move to the next screen page and the button to access the user menu. On the monitor, the following screen appears where you can enter the password.



The user login password is: **1234**.

After entering the correct password you will see the following screen:





1297-M003-3 B

Page 48 of 67

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

15.1 Options menu

R

Press button **E** to display the monitor screen to enable/disable the options as shown below:



To enable / disable individual functions simply high-

light the icon using the buttons

e buttons

and/or

and press the button

Pressing the button **W** may involve, besides, the change in the unit of measure from "mm" to "inch" and vice versa (where applicable) or access to a sub-screen for values settings values (see Par. 15.1.1 or 15.1.2). After you select/deselect the desired options, exit the

menu by pressing push-button

List of available options



Enable/disable the protection guard/ spin (enabled on machine delivery).



Enable/disable the distance/diameter detection caliper (enabled on machine delivery).



Enable/disable the display of static threshold after each spin (enabled on machine delivery).



It allows you to set the thresholds for each of the balancing mode weights (see Par. 15.1.1).



Enable/disable the lock function for caliper arm in position (disabled on machine delivery).



It allows you to change the unit of measurement of the weights from grams to ounces and vice versa.



It allows you to enable/disable the width function detected by GAR305 or GAR307 (enabled when fitted as standard on the machine).



Enable/disable the ECO-WEIGHT function (enabled on machine delivery).



Enable/disable the positioning of weights at "6 o'clock" (disabled on machine delivery).



Enable/disable the pneumatic brake after the spin (disabled on machine delivery).



It allows you to change the unit of measure of the distance of the weights fitting point from mm to inches and vice versa.



Enable/disable the led light (enabled if mounted on the machine).



Enable/disable the dynamic residues in the ECO-WEIGHT function (enabled on machine delivery).



Enable/disable the functions of motorbike balancing (disabled on machine delivery).



Enable/disable the encoder mounted on the spin motor (disabled on machine delivery).



It allows you to change the unit of measurement of the rims width from mm to inches and vice versa.



It allows you to set the size values of weights (see Par. 15.1.2).



Enable/disable the RUN-OUT functions (enabled on machine delivery).



Page 49 of 67

INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS



Enable/disable machine print functions (disabled on machine delivery).

X

It allows the setting of the retrieval of the measures by eye: readout of measures printed on the rim and the graduated scale of the distance-diameter caliper (disabled on machine delivery).

NOTE: it is activated only if distancediameter caliper is disabled.



Enable/disable the use of the manual caliper to measure rim width (disabled on machine delivery).

NOTE: it is activated only if distancediameter caliper is disabled.



It allows you to change the unit of measurement of the rim diameter from mm to inches and vice versa.



Enable/disable the function of weights positioning laser (disabled on machine delivery).



Enable/disable the repositioning of the wheel at the end of the spin (enabled on machine delivery).



Enable/disable user function (disabled on machine delivery).



Enable/disable the function of weights positioning laser wheel inner/outer side at 12 o' clock (disabled on machine delivery).

15.1.1 Lower weight limit

Correction weight below a certain limit is normally shown equal to zero. This limit can be set from 10 g to 1 g.

At the end of the spin however, by pressing the button

, the weight can be displayed with max resolution of 1 g, not considering the set lower limit.



LOWER LIMIT'S FACTORY SET-TING FOR DYNAMIC WHEEL BAL-ANCING MODE IS 5 g. THE LOWER LIMIT FOR ALL THE OTHER MODES IS SET AT 7 g.



KEY

- 1 Lower weight limit in the DYNAMIC program to display "OK" (default value 5 g)
- 2 Lower weight limit in the ALU-STATIC program to display "OK" (default value 7 g)
- 3 Weights display resolution (default value 5 g)
- 4 Weight % reduction in the ECO-WEIGHT function (0 \div 200) (default value 100)



Page 50 of 67

The "User Management" function is disabled on machine delivery. To enable it, proceed as described in

Para 15.1. After enabling, the icon will be displayed on

every page (Fig. 61 ref. 1). The wheel balancers can

GB

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

15.1.3 User management

<u>15.1.2 Setting adhesive weight dimensions</u> <u>and static threshold percentage</u>

To ensure the balancing machine precisely calculates the dimensions and total adhesive weights, set the height (thickness) and width of the adhesive weights at your disposal (see **Fig. 60**).



1297-M003-3 B

GB Page 51 of 67

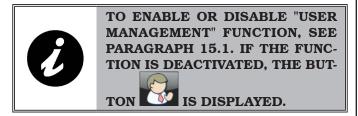
INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

Press any of the available numbers on the buttons at the bottom of the page to select the corresponding user. The system stores the data relating to the last performed spin according to the different operators. You can recall the desired user each time the program displays the specific button (**Fig. 61 ref. 2 and Fig. 62 ref. 1**). The measurements stored for each user are lost when the machine is switched off.

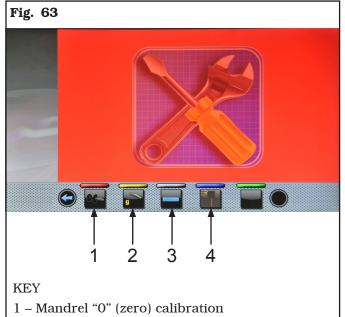
User management is valid for any wheel balancer function.



15.2 Machine calibrations



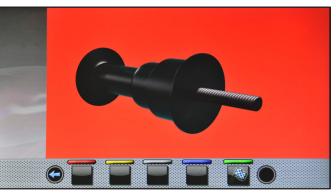
Press the button **Fig. 59 ref. 2**) to display the following screen page on monitor:



- 2 Weight measurement sensors calibration
- 3 Gauges calibration
- 4 Mobile laser pointer calibration

15.2.1 Mandrel "0" (zero) calibration

Press the button **(Fig. 63 ref. 1**) to display the following screen page on the monitor:



After making sure that the mandrel is unloaded (no wheel or mounted accessories) and in the case of closed



pneumatic mandrel, press the button and close the guard. The mandrel will rotate for a few minutes until you see the screen below:



At this point the machine has all its measuring fields.

Press button **v** to return to calibrations screen page.



1297-M003-3 B

GB

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

<u>15.2.2 Weight measurement sensors calibra-</u> <u>tion</u>



ASSEMBLE A BALANCED WHEEL ON THE SPINDLE AND PER-FORM THE SPINDLE "0" "ZERO" CALIBRATION PROCEDURE DE-SCRIBED IN PAR. 15.2.1 (WITH WHEEL MOUNTED).

- Press the button **(Fig. 63 ref. 2**) to display the following screen page on the monitor:



- Set the size of the rim on the mandrel using the distance-diameter caliper arm.
- Set the rim width using one of the following calipers:
 - Manual caliper (equipped with the machine)
 - GAR305 (if present)
 - GAR307 (if present)



- Press button and close the guard to the perform the 1st spin of the wheel without weights.



IN THE VERSIONS WITH GAR332 (AUTOMATIC WIDTH MEASUR-ING DEVICE), WHEN THE GUARD IS LOWERED, THE RIM WIDTH IS MEASURED AUTOMATICALLY AND THE SIZING SPIN IS CAR-RIED OUT.

- At the end, on the monitor will appear the following screen, saying that you should apply a weight of 100 g to the "12 o'clock" outer rim.



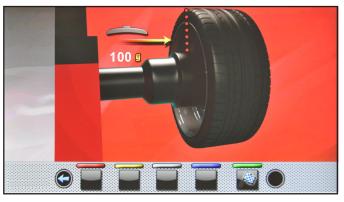


APPLY THE WEIGHT AT A POINT IN WHICH BOTH SIDES OF THE RIM THERE IS THE POSSIBILITY OF APPLYING A CLIP WEIGHT OF 100 g.

- Apply the weight and position it perfectly to the "12 o'clock".



- Press the button and close the guard to perform the 2nd spin of the wheel (100 g weight placed on the outside of the wheel).
- At the end the following screen will appear on the monitor, suggesting to remove the weight of 100 g previously applied on the outer side and apply it on the inside of the rim.



- Turn manually the wheel until you have the weight of 100 g on the outer side at "12 o'clock".
- Press the brake pedal and hold it down during the whole the following operation to avoid unexpected rotation of the spindle.
- Remove the weight from 100 g from the outside of the wheel and apply it on the inner side at "12 o'clock".
- Close the guard to perform the 3rd spin of the wheel (100 g weight placed on the inside wheel).

Page 53 of 67

GB

INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

At the end of the rotation, the video screen below will be displayed to indicate that the operation is finished.

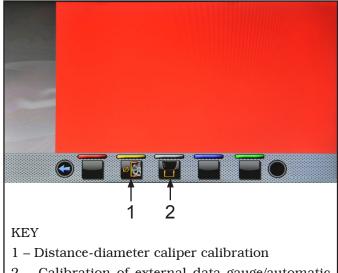




WHEN THE OPERATION IS CON-CLUDED, REMOVE THE WHEEL FROM THE MANDREL AND PER-FORM A COMPLETE CALIBRA-TION PROCEDURE "0" (ZERO) MANDREL AS DESCRIBED IN PAR. 15.2.1.

15.2.3 Gauges calibration

Press the button **(Fig. 63 ref. 3**) to display the following screen page on the monitor:



2 – Calibration of external data gauge/automatic external data gauge

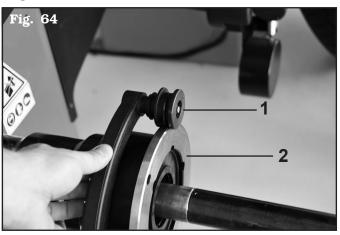
Distance-diameter caliper calibration



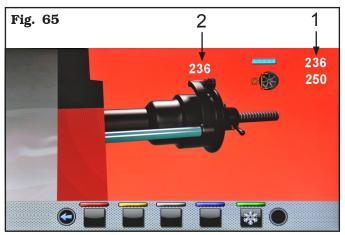
Press the button to display the following screen page on the monitor:



Place the gauge (**Fig. 64 ref. 1**) on the mandrel flange (**Fig. 64 ref. 2**).



The following screen will appear on the monitor to indicate the measured values:



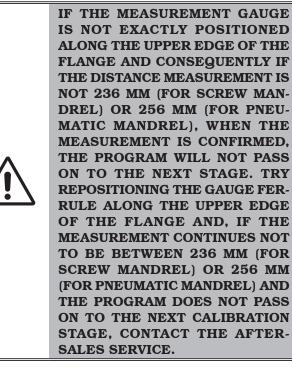


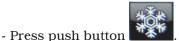
1297-M003-3 B

Page 54 of 67

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

- The value next to the symbol "scale" (Fig. 65 ref. 1) (236 mm for screw mandrel or 256 mm for pneumatic mandrel) must be equal to the value positioned above the gauge (Fig. 65 ref. 2) \pm 1 mm.





The following screen will appear on the monitor:



- Place the gauge as shown in the following figure:

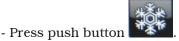




- Press push button **Wait** a few seconds until you see the following screen:



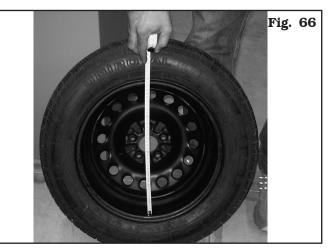
- Place the gauge against the mandrel in the lower part of the it but on a smaller diameter than before as indicated on the image on the monitor.



On the monitor the next screen page will be displayed:



Measure the exact diameter of a rim (see **Fig. 66**) and place it on the screen on the monitor by pressing the or buttons.



- Fit the measured wheel on the balancer and lock it on the mandrel.

GB

Page 55 of 67

GB

INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

- Turn the gauge ferrule (**Fig. 67 ref. 1**) on the inner edge of the wheel upwards (see **Fig. 67**).



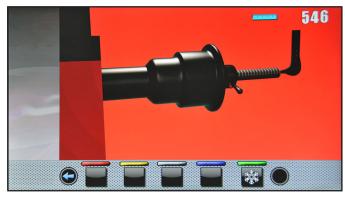
- Press button to end the operation. On the monitor the next screen page will be displayed:

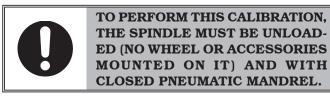


The calibration of the distance-diameter caliper is finished.

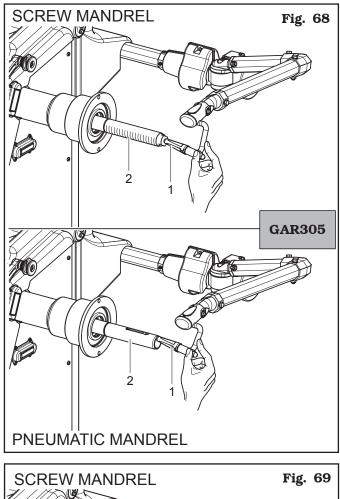
Calibration of external data gauge (optional)

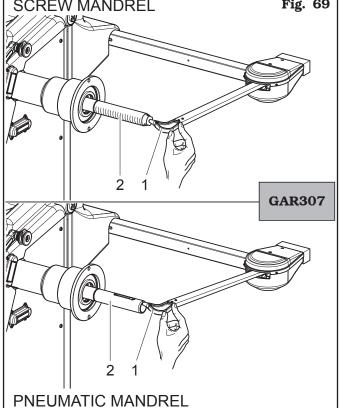
Press the button to display the following screen page on the monitor:





Move the tip of the width measuring device (**Fig. 68-69 ref. 1**) by mandrel's end (**Fig. 68-69 ref. 2**) (in case of pneumatic mandrel, move it next to upper edge of the closed mandrel).







1297-M003-3_B

Page 56 of 67

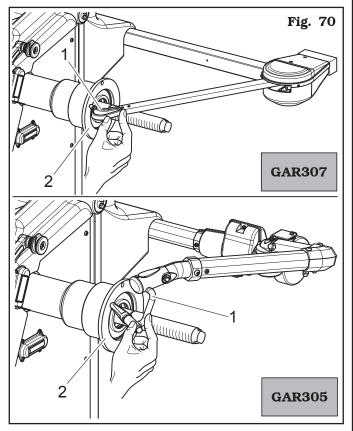
LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

Press button

On the monitor the next screen page will be displayed:



Move the tip of the width measuring device (**Fig. 70 ref. 1**) in line with the outer surface of the flange (**Fig. 70 ref. 2**).





Press button . At the end of the operation, the following screen will appear on the monitor:

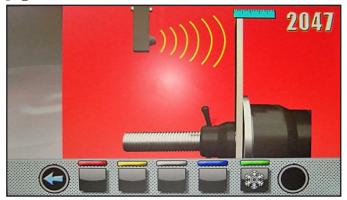


The calibration of the external data gauge is finished.

Calibration of automatic external data gauge

Mount the GAR332 sizing body onto the mandrel and fix it through the <u>special</u> locking devices.

Press the button to display the following screen page on the monitor:



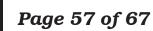
Close the wheel cover until bringing the automatic width sensor next to the sizing body previously installed.

Press button . At the end of the operation, the following screen will appear on the monitor:



The calibration of the automatic external data gauge is finished.

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INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

15.2.4 Mobile laser pointer calibration

To perform this calibration, you need two wheels with a wide rim diameter difference, a small one measuring 13"/14", and a large one measuring 18"/19".

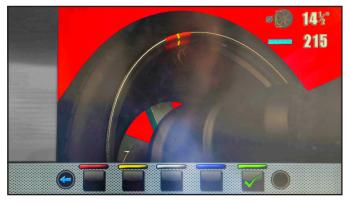
Press the button **(Fig. 63 ref. 4**) to display the following screen page on the monitor:



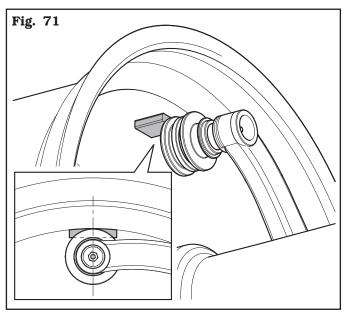
Mount the small wheel (13"/14" diameter) onto the mandrel and apply an adhesive weight in any point inside the rim. At the end of the operation press push

button

On the monitor the next screen page will be displayed:



Let the weights fitting gripper of the caliper come into contact with the previously applied weight, by manually rotating the wheel too and taking care to bring it into contact with the weight's central area (see **Fig. 71**).

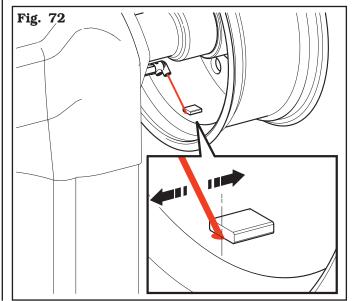


Keep the caliper in position and press push button

. On the monitor the next screen page will be displayed:



Use push button **and by manually** rotating the wheel too, make the laser pointer hit the reference point previously taken, as shown in **Fig. 72**.





1297-M003-3_B

Page 58 of 67

GB

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

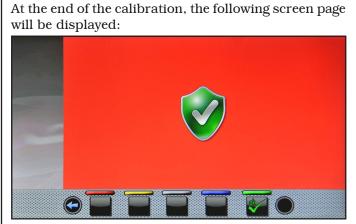


the measure is

When the button is pressed displayed and the monitor will show the following screen page:



Replace the small wheel (13"/14") with the large one (18"/19") and repeat the previously described operations.



The calibration of the laser is finished.

Page 59 of 67

INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

16.0 ERROR SIGNALS

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During wheel balancer operation, if wrong commands are given by the operator or device faults occur, an error code may appear on the monitor screen.

Below is a troubleshooting chart.

Error code	Description
2	Planned wheel speed not reached
3	Calibration overcoming
4	Wheel speed stability out of tolerance
5	Encoder calibration error
6	Encoder samples not sufficient
7	Mandrel calibration error
8	Piezo calibration values out of tolerance
9	Wheel rotations not completed
10	Pneumatic mandrel open
11	Incorrect gain calibration
12	Distance-diameter caliper value not released
13	Distance-diameter caliper value not released
14	Firmware error
15	Runout samples not sufficient
17	External data gauge enabled
27	Rotate the wheel to make a complete rotation
28	Piezo calibration error
29	Distance out of tolerance level
31	Distance-diameter caliper released
32	Parameters format incompatible



1297-M003-3 B

Page 60 of 67

GB

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

17.0 ROUTINE MAINTENANCE



BEFORE CARRYING OUT ANY ROU-TINE MAINTENANCE OR ADJUST-MENT PROCEDURE, POSITION THE MAIN SWITCH "0", DISCON-NECT THE MACHINE FROM THE ELECTRICITY SUPPLY USING THE SOCKET/PLUG COMBINATION AND CHECK THAT ALL MOBILE PARTS ARE AT A STANDSTILL.



BEFORE EXECUTING ANY MAIN-TENANCE OPERATION, MAKE SURE THERE ARE NO WHEELS LOCKED ONTO THE MANDREL.



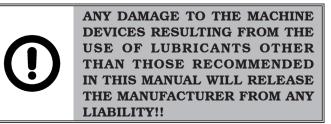
PNEUMATICALLY UNPLUG THE MACHINE (ONLY FOR LIBRAK380P - LIBRAK380PS -LIBRAK380PW - LIBRAK380PWS). To guarantee the efficiency and correct functioning of the machine, it is essential to carry out daily or weekly cleaning and weekly routine maintenance, as described below.

Cleaning and routine maintenance must be conducted by authorized personnel and according to the instructions given below.

• Remove deposits of tyre powder and other waste materials with a vacuum cleaner.

DO NOT BLOW IT WITH COMPRESSED AIR.

• Do not use solvents to clean the pressure regulator.



Page 61 of 67

GB

INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

18.0 TECHNICAL DATA

		LIBRAK						
	380	380P	3805	380PS	380W	380PW	380WS	380PWS
Wheel max. weight (Kg)				7	0			
Max. absorbed voltage (W)				20	00			
Power supply				230V 50/6	60 Hz 1 ph			
Balancing precision (g)				±	1			
Balancing speed (rpm)		< 100						
Rim width setting (inches)	1.5" ÷ 22"							
Rim diameter setting (inches)				10" -	÷ 30"			
Max wheel diameter inside protection (inches)	44"							
Max wheel width inside protection (mm)	ridth inside 560							
Sound emission level (dBA)				<'	70			
Cycle time (sec)				(3			
Weight (Kg)				13	30			

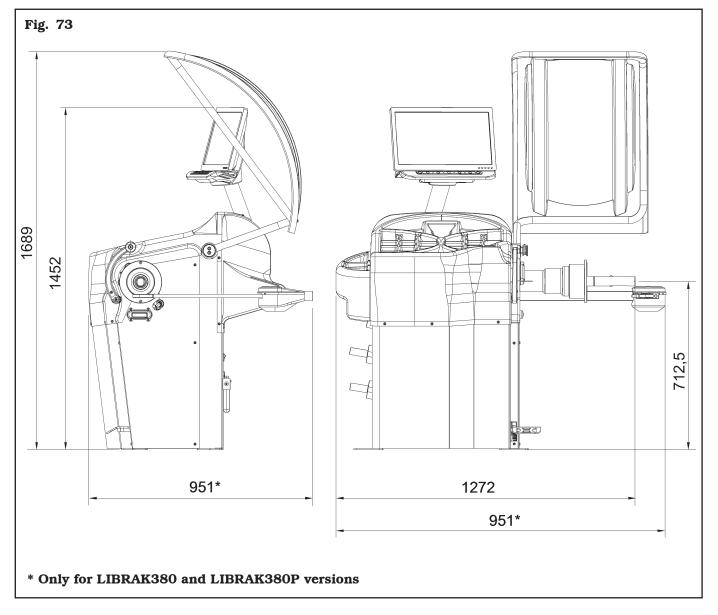


1297-M003-3_B

Page 62 of 67

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

18.1 Dimensions



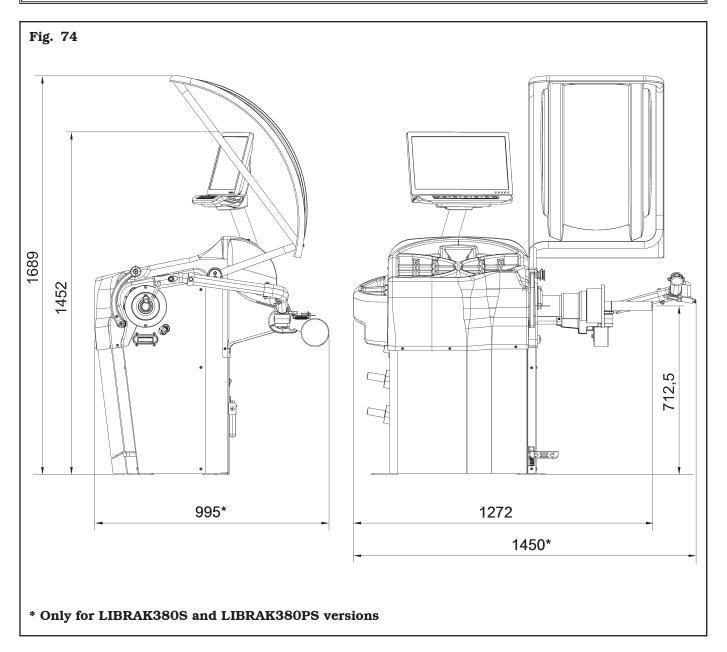
Page 63 of 67

GB

INSTRUCTION, USE AND MAINTENANCE MANUAL



LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS





1297-M003-3_B

Page 64 of 67

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS

19.0 STORING

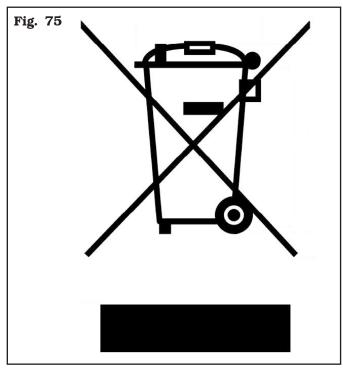
If storing for long periods disconnect the main power supply and take measures to protect the machine from dust build-up. Lubricate parts that could be damaged from drying out.

20.0 SCRAPPING

When the decision is taken not to make further use of the machine, it is advisable to make it inoperative by removing the connection pressure hoses. The machine is to be considered as special waste and should be dismantled into homogeneous parts. Dispose of it in accordance with current legislation.

Instructions for the correct management of waste from electric and electronic equipment (WEEE) according to the Italian legislative decree <u>49/14</u>

In order to inform the users on the correct way to dispose the product (as required by the article 26, paragraph 1 of the Italian legislative decree 49/14), we communicate what follows: the meaning of the crossed dustbin symbol reported on the equipment indicates that the product must not be thrown among the undifferentiated rubbish (that is to say together with the "mixed urban waste"), but it has to be managed separately, to let the WEEE go through special operations for their reuse or treatment, in order to remove and dispose safely the waste that could be dangerous for the environment and to extract and recycle the raw materials to be reused.



21.0 REGISTRATION PLATE DATA



The validity of the Conformity Declaration enclosed to this manual is also extended to products and/or devices the machine model object of the Conformity Declaration can be equipped with.



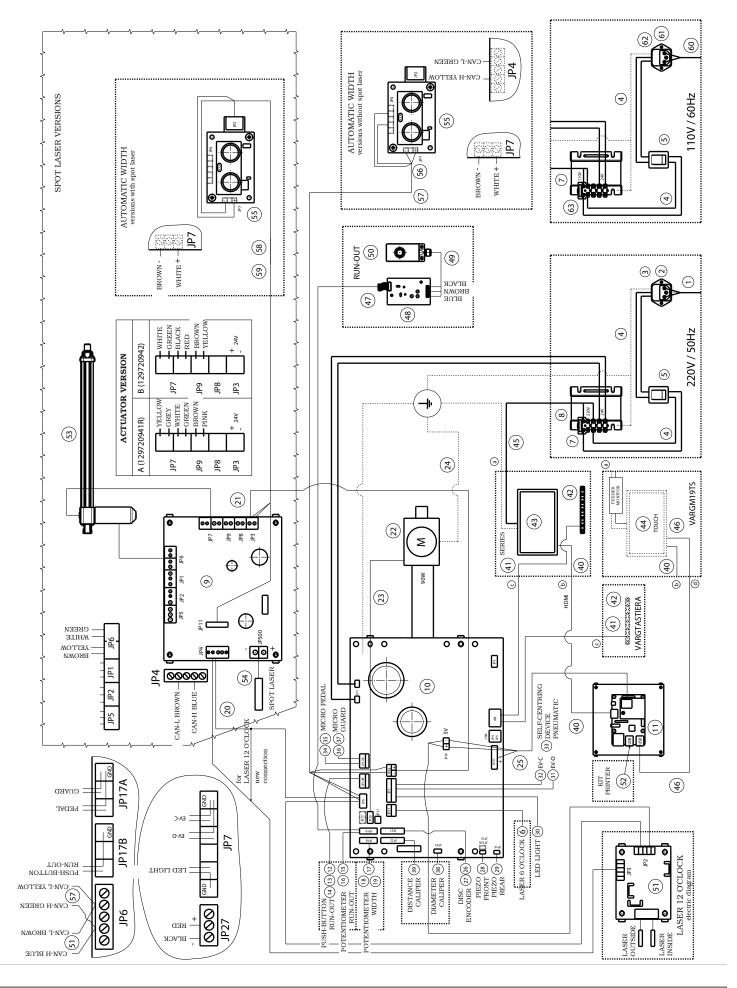
ATTENTION: TAMPERING WITH, CARVING, CHANGING ANYHOW OR EVEN REMOVING MACHINE IDENTIFICATION PLATE IS AB-SOLUTELY FORBIDDEN; DO NOT COVER IT WITH TEMPORARY PANELS, ETC., SINCE IT MUST ALWAYS BE VISIBLE.

Said plate must always be kept clean from grease residues or filth generally.

WARNING: Should the plate be accidentally damaged (removed from the machine, damaged or even partially illegible) inform immediately the manufacturer.

22.0 FUNCTIONAL DIAGRAMS

Here follows a list of the machine functional diagrams.



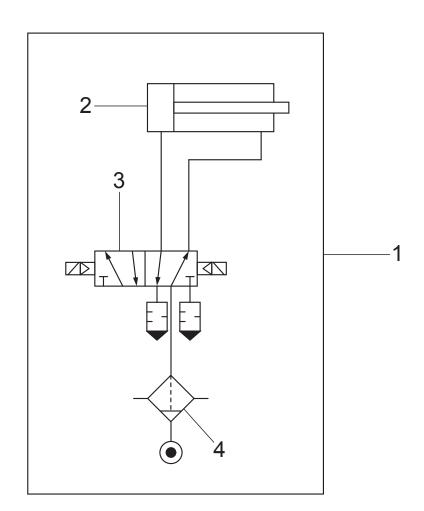
LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS								
Butler	WIRING CO		1297-M003-3_B					
DULICI	DIAG	RAM		GB				
ENGINEERING and MARKETING S.P.A.	Table N°A - Rev. 1	129705522	Page 65 of 67					

KEY

- 1 Power supply cable
- 2 Net filter
- 3 Fuse
- 4 Cable from switch to filter to transformer
- 5 Tilting switch
- 6 Line laser (with cable) (for GAR321 and GAR322)
- 7 Fuse
- 8 Transformer
- 9 Automatic measuring device electronics kit
- 10-Power card kit
- 11 Monitor SBC kit
- 12 Run-out push button cables (for GAR303)
- 13 Run-out keyboard extension cable (for GAR303)
- 14 Push-button panel with 1 key (for GAR303)
- 15 Run-out ultrasound sensor cable extension (for GAR303) $\,$
- 16 Potentiometer with cable (for GAR303)
- 17 Width potentiometer extension cable (for GAR303, GAR305, GAR307)
- 18 Width cables (for GAR303, GAR305)
- 19 Potentiometer with shielded cable (for GAR307)
- 20 Can Bus long extension cable
- 21 Power supply cable assembly
- 22 90W motor with encoder (for versions with laser spot) - DC motor (only versions without spot laser)
- 23 Motor encoder cable (only versions with laser spot)
- 24 Motor support ground cable
- 25 Power supply cable
- 26 Wheel position sensor cable
- 27 Buffered encoder card
- 28 Piezo with front cable
- 29 Piezo with cable
- 30 Led light
- 31 Cable for solenoid valve SV-O (only for pneumatic self-centring device versions)
- 32 Cable for solenoid valve SV-C (only for pneumatic self-centring device versions)
- 33 Solenoid valve mounting (only for pneumatic selfcentring device versions)
- 34 Cable for pedal micro (only for pneumatic self-centring device versions)

- 35 Limit switch (only for self-centring device pneumatic versions)
- 36 Cable for wheel micro protection
- 37 Limit switch
- 38 Potentiometer with cable
- 39 Buffered optical line card
- 40 HDMI cable
- 41 Push-button panel with 7 keys cables
- 42 7-keys keyboard
- 43 Touch screen monitor 20" HDMI
- 44 Touch screen monitor 19"
- 45 Cable from transformer to power supply
- 46 Cable for connection USB/A -USB/B
- 47 Ultrasounds sensor extension cable (for GAR315, GAR316, GAR338)
- 48 Run-out card (for GAR315, GAR316, GAR338)
- 49 Cable for ultrasounds (for GAR315, GAR316, GAR338)
- 50– Ultrasounds sensor (for GAR315, GAR316, GAR338)
- 51 Electric diagram (for GAR334, GAR335)
- 52 Printer kit
- 53 Laser unit actuator
- 54 Laser cable + laser assembly
- 55 Ultrasounds sensor card (for wheel balancers with automatic width or GAR332)
- 56 Width card cable assembly (for wheel balancers with automatic width or GAR332)
- 57 Extension cable assembly (for wheel balancers with automatic width or GAR332)
- 58 Serial width card cable assembly (for wheel balancers with automatic width)
- 59 Serial extension cable assembly (for wheel balancers with automatic width)
- 60 Power supply cable USA plug
- 61 Net filter
- 62 Fuse
- 63 Fuse

LIBRAK380 - LIBRAK380P - LIBRAK380S - LIBRAK380PS - LIBRAK380W - LIBRAK380PW - LIBRAK380WS - LIBRAK380PWS							
Butler		ONNECTION	1297-M003-3_B				
DULICI	DIAG	RAM		GB			
ENGINEERING and MARKETING S.P.A.	Table N°A - Rev. 1	129705522	Page 66 of 67				



KEY

- 1 Pneumatic tightening diagram
 2 Tightening drive cylinder
 3 5/2 NC solenoid valves
 4 Separating filter

LIBRAK380P - LIBRAK380PS - LIBRAK380PW - LIBRAK380PWS								
Butler	PNEUMATIC		1297-M003-3_B					
DULICI	DIAG	RAM		GB				
ENGINEERING and MARKETING S.P.A.	Table N°B - Rev. 0	129600170	Page 67 of 67					
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1297-R003-1 B

LIBRAK380 - LIBRAK380P LIBRAK380S - LIBRAK380PS LIBRAK380W - LIBRAK380PW LIBRAK380WS - LIBRAK380PWS

23.0 LISTA DEI COMPONENTI

23.0 LIST OF COMPONENTS GB



23.0 TEILELISTE

- F 23.0 LISTE DES PIECES DETACHEES
- 23.0 LISTA DE PIEZAS E

GLI ESPLOSI SERVONO SOLO PER L'IDENTIFICAZIONE DELLE PARTI DA SOSTITUIRE. LA SOSTITUZIONE DEVE ESSERE EFFETTUATA DA PERSONALE PROFESSIONAL-**MENTE QUALIFICATO.**

THE DIAGRAMS SERVE ONLY FOR THE IDENTIFICATION OF PARTS TO BE REPLACED. THE REPLACEMENT MUST BE CARRIED OUT PROFESSIONALLY QUALIFIED PER-SONNEL.

DIE ZEICHNUNGEN DIENEN NUR ZUR IDENTIFIZIERUNG DER ERSATZTEILE. DIE **ERSETZUNG MUSS DURCH QUALIFIZIERTES PERSONAL ERFOLGEN.**

LES DESSINS NE SERVENT QU'À L'IDENTIFICATION DES PIÈCES À REMPLACER. LE REMPLACEMENT DOIT ÊTRE EFFECTUÉ PAR UN PERSONNE PROFESSIONNEL-LEMENT QUALIFIÉ.



LOS DIBUJOS EN DESPIECE SIRVEN ÚNICAMENTE PARA IDENTIFICAR LAS PIEZAS **QUE DEBEN SUSTITUIRSE. LA SUSTITUCIÓN DE PIEZAS DEBE EFECTUARLA EXCLU-**SIVAMENTE PERSONAL PROFESIONALMENTE CUALIFICADO.

- Per eventuali chiarimenti interpellare il più vicino rivenditore oppure rivolgersi direttamente a:
- For any further information please contact your local dealer or call:
- Im Zweifelsfall ober bei Rückfragen wenden Sie sich bitte an den nächsten Wiederverkäufer oder direkt an:
- Pour tout renseignement complémentaire s'adresser au revendeur le Plus proche ou directement à:
- En caso de dudas, para eventuales aclaraciones, póngase en contacto con el distribudor más próximo ó diríjasie directamente a:

BUTLER ENGINEERING and MARKETING S.p.A. a s. u.

Via dell'Ecologia, 6 - 42047 Rolo - (RE) Italy Phone (+39) 0522 647911 - Fax (+39) 0522 649760 - e-mail: Info@butler.it



LISTA DEI COMPONENTI LIST OF COMPONENTS TEILELISTE LISTE DES PIECES DETACHEES LISTA DE PIEZAS

Pag. 2 di 36

LIBRAK380 - LIBRAK380P LIBRAK380S - LIBRAK380PS LIBRAK380W - LIBRAK380PW LIBRAK380WS - LIBRAK380PWS

SOMMARIO - SUMMARY - INHALT SOMMAIRE - SUMARIO	1297-R003-1_B
Tavola N°1 - Rev. 1	Tavola N° 9 - Rev. 1 12979422117 GRUPPO SCHEDA AGGIUNTIVA LASER 12879422117 JASER ADDITIONAL CARD UNIT 128712117 SATZ VON ZUSÄTZLICHE LASER-KARTE GROUPE CARTE ADDITIONNELLE LASER GRUPO FICHA AÑADIVA LASER 12979422117
Tavola N°2A - Rev. 11296900737	Tavola N°10 - Rev. 1 12979013118
GRUPPO MOTORE	GRUPPO IMPIANTO ELETTRICO
MOTOR UNIT	ELECTRICAL SYSTEM UNIT
MOTORSATZ	SATZ VON ELEKTROANLAGE
GROUPE MOTEUR	GROUPE INSTALLATION ÉLECTRIQUE
GRUPO MOTOR	GRUPO INSTALACIÓN ELÉCTRICA
Tavola N°2B - Rev. 11296923228	Tavola N°11 - Rev. 112939031119
GRUPPO MOTORE	IMPIANTO SERRAGGIO PNUEMATICO
MOTOR UNIT	PNEUMATIC TIGHTENING SYSTEM
MOTORSATZ	ANLAGE FÜR PNEUMATISCHE AUFSPANNUNG
GROUPE MOTEUR	SYSTÈME SERRAGE PNEUMATIQUE
GRUPO MOTOR	SISTEMA APRIETE NEUMÁTICO
Tavola N°3A - Rev. 1 1296900909	Tavola N°12 - Rev. 112979158020
GRUPPO ROTANTE COMPLETO	GRUPPO PROTEZIONE RUOTA
COMPLETE ROTARY UNIT	WHEEL PROTECTION UNIT
KOMPLETTER ROTIERENDER SATZ	SATZ FÜR RADSCHUTZ
GROUPE ROTATIF COMPLET	GROUPE PROTECTION ROUE
GRUPO GIRATORIO COMPLETO	GRUPO PROTECCIÓN RUEDA
Tavola N°3B - Rev. 112969003010	Tavola N°13 - Rev. 1 12979149021
GRUPPO ROTANTE COMPLETO	GRUPPO CALIBRO DISTANZA/DIAMETRO
COMPLETE ROTARY UNIT	CALIPER UNIT DISTANCE/DIAMETRR
KOMPLETTER ROTIERENDER SATZ	KALIBERSATZ ABSTAND/DURCHMESSER
GROUPE ROTATIF COMPLET	GROUPE CALIBRE DISTANCE/DIAMETRE
GRUPO GIRATORIO COMPLETO	GRUPO CALIBRE DISTANCIA/DIÁMETRO
Tavola N°4 - Rev. 0 12969029211	Tavola N°14 - Rev. 112979233122
GRUPPO FRENO	GRUPPO ELETTRONICA
BRAKE UNIT	ELECTRONICS UNIT
BREMSATZ	ELEKTRONIKSATZ
GROUPE FREIN	GROUPE ÉLECTRONIQUE
GRUPO FRENO	GRUPO ELECTRÓNICA
Tavola N°5 - Rev. 1 129791644 12	Tavola N°15 - Rev. 112979425023
GRUPPO TELAIO	GRUPPO ILLUMINATORE
FRAME UNIT	LIGHTING DEVICE UNIT
RAHMENSATZ	BELEUCHTUNGSATZ
GROUPE CHASSIS	GROUPE DISPOSITIF D'ÉCLAIRAGE
GRUPO ESTRUCTURA	GRUPO ILUMINADOR
Tavola N°6 - Rev. 1 12979241213 GRUPPO PLANCIA MONITOR 19" 19" MONITOR BOARD UNIT MONITOR-BRETTSATZ GROUPE PLANCHE MONITOR GRUPPO TABLERO MONITOR 10"	Tavola N°16 - Rev. 1 12979465024 GRUPPO LASER SPOT SPOT LASER UNIT SPOT LASER SATZ GROUPE LASER SPOT GRUPO LASER SPOT
Tavola N°7 - Rev. 0 12979178014 GRUPPO AZIONAMENTO FRENO 12979178014 SATZ FÜR BREMSBETÄTIGUNG 12979178014 GROUPE ACTIONNEMENT FREIN 12979178014 GRUPO ACCIONAMIENTO FRENO 12979178014	Tavola N°17A - Rev. 125 DOTAZIONE A A EQUIPMENT AUSSTATTUNG A DOTATION A DOTACION A
Tavola N°8A - Rev. 112979459015	Tavola N°17B - Rev. 126
GRUPPO PEDALIERA CON FILO	DOTAZIONE B
PEDALEOARD UNIT WITH CLAMP	B EQUIPMENT
PEDALLEISTESATZ MIT DRAHT	AUSSTATTUNG B
GROUPE PÉDALES DE DIRECTION AVEC INOX	DOTATION B
GRUPO PEDALERA CON FILO	DOTACION B
Tavola N°8B - Rev. 112979460016 GRUPPO PEDALIERA CON FILO PEDALEOARD UNIT WITH CLAMP PEDALLEISTESATZ MIT DRAHT GROUPE PÉDALES DE DIRECTION AVEC INOX GRUPO PEDALERA CON FILO	Tavola N°17C - Rev. 127 DOTAZIONE C C EQUIPMENT AUSSTATTUNG C DOTAZION C



LISTA DEI COMPONENTI LIST OF COMPONENTS TEILELISTE LISTE DES PIECES DETACHEES LISTA DE PIEZAS

Pag. 3 di 36

LIBRAK380 - LIBRAK380P LIBRAK380S - LIBRAK380PS LIBRAK380W - LIBRAK380PW LIBRAK380WS - LIBRAK380PWS

1297-R003-1_B

Tavola	N°17D -	Rev. 1	
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DOTAZIONE D D EQUIPMENT AUSSTATTUNG D DOTATION D DOTACION D

Tavola N°17E - Rev. 0 _ 29

DOTAZIONE E E EQUIPMENT AUSSTATTUNG E DOTATION E DOTACION E

Tavola N°17F - Rev. 0 _30

DOTAZIONE F F EQUIPMENT AUSSTATTUNG F DOTATION F DOTACION F

Tavola N°18 - Rev. 1___GAR305......31

CALIBRO LARGHEZZA PROFESSIONALE PROFESSIONAL EXTERNAL DATA GAUGE BERUFLICHE BREITENLEHRE CALIBRE LARGEUR PROFESSIONEL CALIBRE ANCHO PROFESIONAL

Tavola N°19 - Rev. 1___GAR307......32

CALIBRO LARGHEZZA RUOTE WHEEL WIDTH EXTERNAL DATA GAUGE BREITENTASTER TIGE EXTERNE LARGEUR ROUES PALPADOR ANCHURA RUEDAS

Tavola N°20A - Rev. 0 129791741......33

GRUPPO COMPLETAMENTO PLANCIA BOARD COMPLETION UNIT BRETTAUSBAUSATZ GROUPE D'ACHÈVEMENT PLANCHE GRUPO DE ACEBADO TABLERO

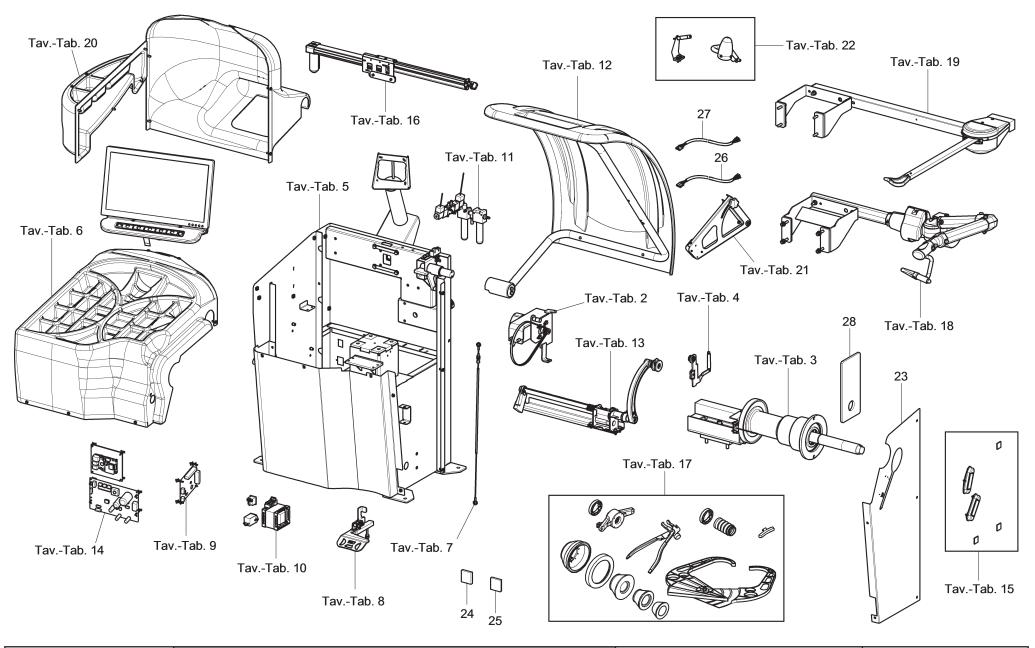
Tavola N°20B - Rev. 0 _ 129794440......34

GRUPPO COMPLETAMENTO FRAME COMPLETION UNIT AUSBAUSATZ GROUPE D'ACHÈVEMENT GRUPO DE ACEBADO

Tavola N°21 - Rev. 0____GAR332......35 GRUPPO MISURATORE LARGHEZZA AUTOMATICO

GRUPPO MISURATORE LARGHEZZA AUTOMATICO AUTOMATIC MEASURING DEVICE UNIT AUTOMATISCHE BREITEN-MESSVORRICHTUNG GROUPE MESUREUR AUTOMATIQUE DE LA LARGEUR GRUPO MEDIDOR ANCHO AUTOMÁTICO

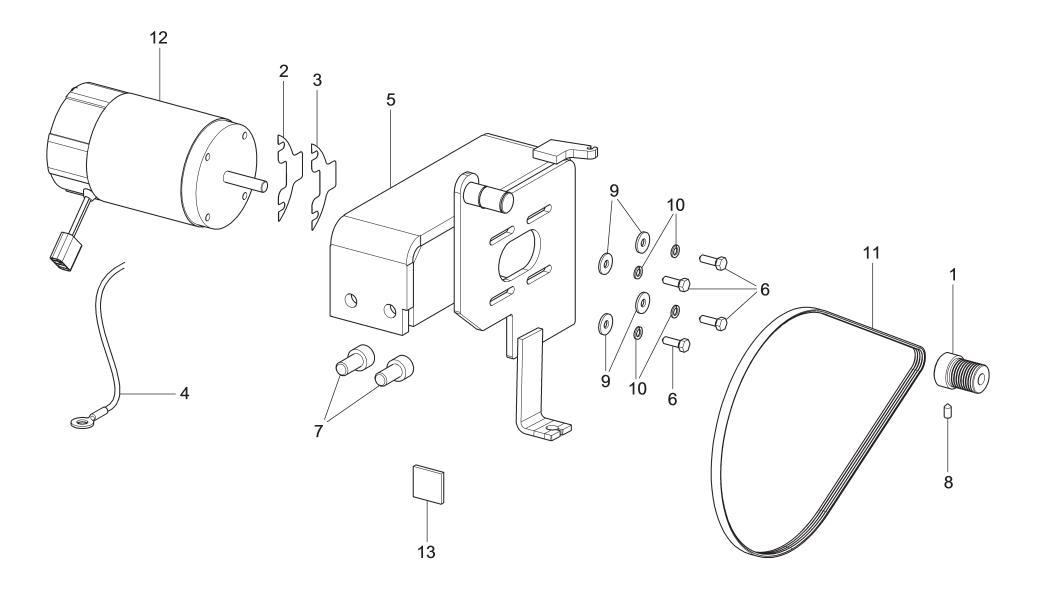
DISPOSITIVO LASER ORE 12 LASER DEVICE AT 12 O' CLOCK LASERVORRICHTUNG AUF 12 UHR DISPOSITIF LASER À MIDI DISPOSITIVO LÁSER A LAS 12



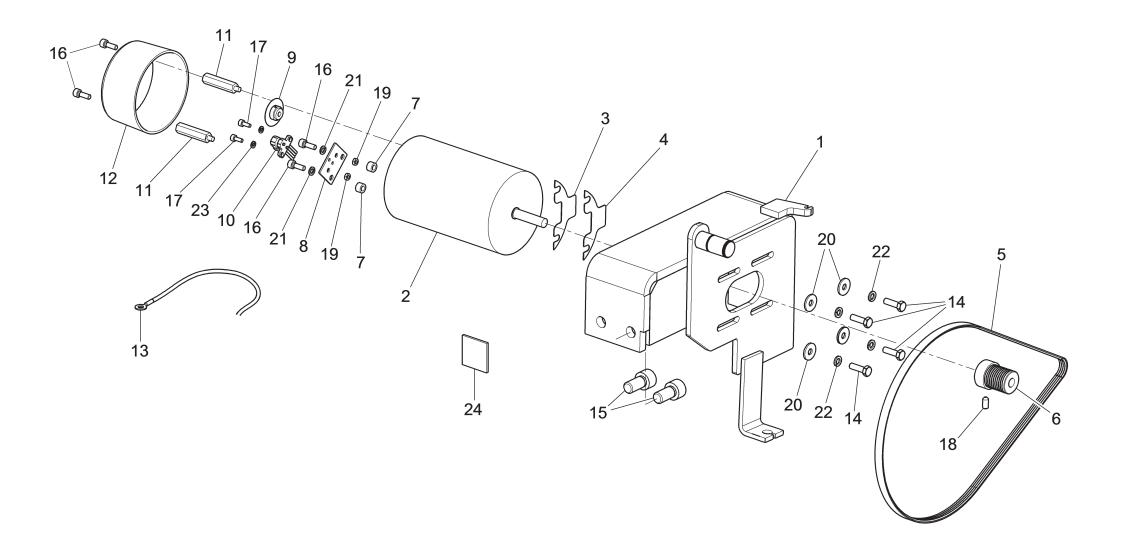
Butler ENGINEERING and MARKETING S.P.A.	LISTA DEI COMPONENTI - LIST LISTE DES PIECES DETA(OF COMPONENTS - TEILELISTE CHEES - LISTA DE PIEZAS	ASSIEME GENERALE MAIN ASSEMBLY GENERALSATZ	Pag. 4 di 36
	Tavola N°1 - Rev. 1		ASSEMBLAGE GENERAL JUNTO GENERAL	LIBRAK380 - LIBRAK380P LIBRAK3805 - LIBRAK380PS LIBRAK380W - LIBRAK380PW LIBRAK380WS - LIBRAK380PWS

	Butler		LISTA DEI COMPONENTI - LIST OF COMPONENTS - TEILELISTE LISTE DES PIECES DETACHEES - LISTA DE PIEZAS				ASSIEME GENERALE MAIN ASSEMBLY GENERALSATZ			Pag. 5 di 36	
	EERING and MARKETING S.P.A.	1	Tavola N°1 - R	ev. 1			ASSEMBLAGE GENERAL LIBRAK3800		K380 - LIBRAK380P 3808 - LIBRAK380PS 380W - LIBRAK380PW 80WS - LIBRAK380PWS		
Tav.	Cod.	Pos.	LIBRAK380	LIBRAK380P	LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBR	AK380WS	LIBRAK380PWS
2A 2B	129690073 129692322		•	•	•	•	•	•		•	•
3A	129690090		•		•		•			•	-
3B	129690030		•	•		•		•		•	•
4	129690292		•	•	•	•	•	•		•	•
5	129791644		•	•	•	•	•	•		•	•
6	129792412		•	•	•	•	•	•		•	•
7	129791780		•	•	•	•	•	•		•	•
8A	129794590		•		•		•			•	
8B	129794600			•		•		•			•
9	129794221				•	•				•	•
10	129790131		•	•	•	•	•	•		•	•
11	129390311			•		•		•			•
12	129791580		٠	•	•	•	•	•	•		•
13	129791490		•	•	•	•	•	•		•	•
14	129792331		•	•	•	•	•	•		•	•
15	129794250		•	•	•	•	•	•		•	•
16	129794650				•	•				•	•
17A	-		•								
17B	-			•							
17C	-				•						
17D	-					•					
17E							•			•	
17F								•			•
18	GAR305		OPT	OPT	•	•					
19	GAR307		•	•							
20A	129791741		•	•	•	•					
20B	129794440						•	•		•	•
21	GAR332						•	•		•	•
22	GAR334	0.00	OPT	OPT	OPT	OPT	OPT	OPT		OPT	OPT
	129715781	23A	•	•			•	•			
	129721681	23B		•	•	•				•	•
	599497	24	•	•	•	•	•	•		•	•

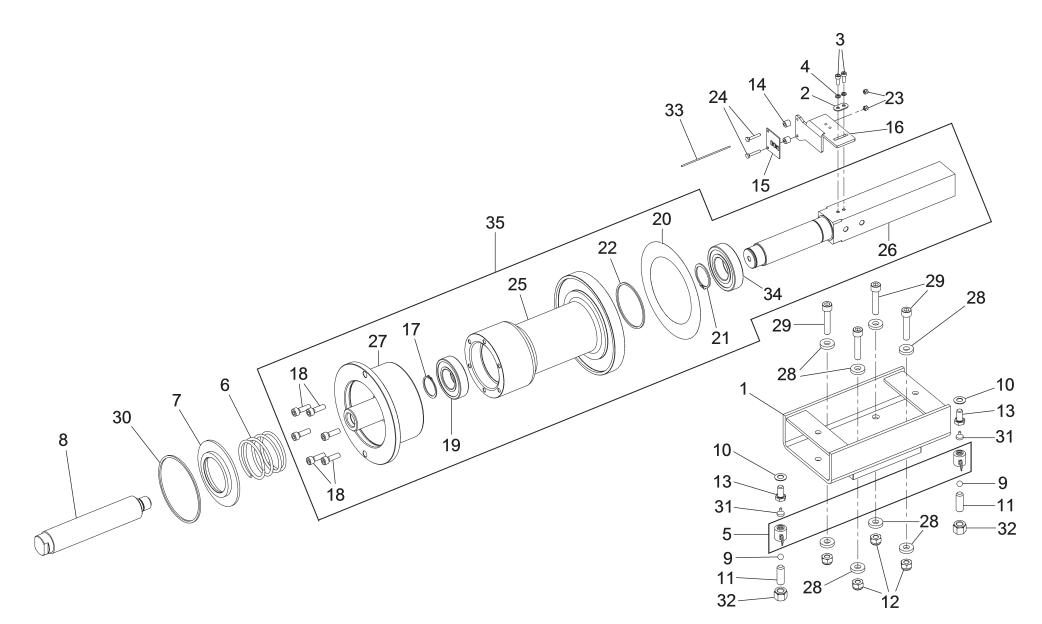
	Butler			IECES DETACHE	COMPONENTS - CES - LISTA DE P		MA GE ASSEM	CME GENERALE IN ASSEMBLY SNERALSATZ BLAGE GENERAL ITO GENERAL		Pag. 6 di 36 LIBRAK380 - LIBRAK380P LIBRAK380S - LIBRAK380PS LIBRAK380W - LIBRAK380PW LIBRAK380WS - LIBRAK380PWS		
Tav.	ERING and MARKETING S.P.A. Cod.	Pos.	LIBRAK380	LIBRAK380P	LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380WS	UWS - LIBRAK380PWS		
	599498	25	•	•	•	•	•	•	•	•		
	129765010	26A			-	-	•	•		-		
	129765030	26B					-	-	•	•		
	129765020	27A					•	•	-			
	129765040	27B					-	-	•	•		
	GAR352	215					•	•	•	•		
	0/11(002	20										



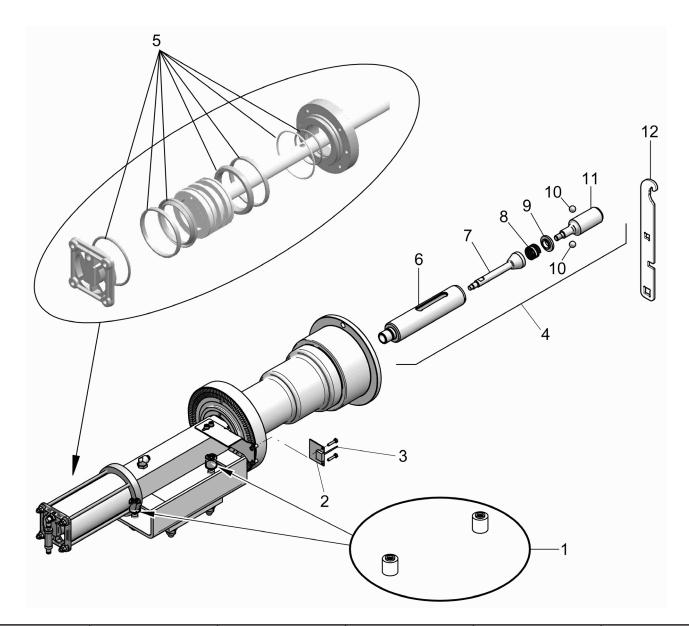
LIBRAK380	LIBRAK380 LIBRAK380P		LIBRAK380S LIBRAK380PS		LIBRAK380W	LIBRAK380PW	LIBRAK380WS	5 LIBRAK380PWS
•	• •				•	•		
Butle			COMPONENTI - LIST È DES PIECES DETA			GRUPPO MOTOR MOTOR UNIT MOTORSATZ		Pag. 7 di 36
ENGINEERING and MARKETING S.P.A.		Tavola	N°2A - Rev. 1	129690	073	GROUPE MOTEU GRUPO MOTOR		



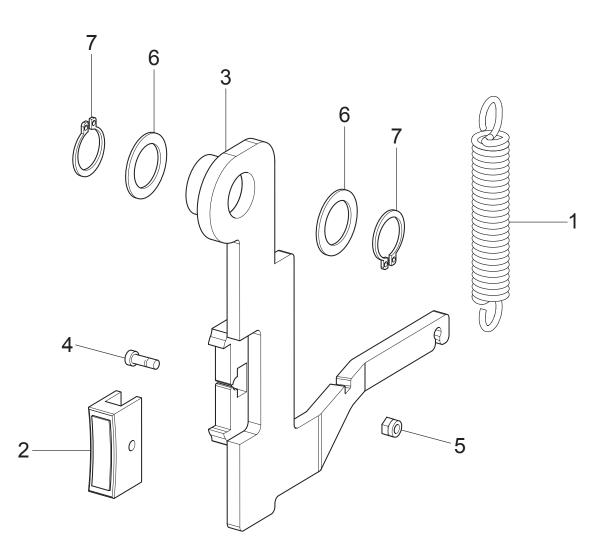
LIBRAK380	LI	BRAK380P	LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380WS		LIBRAK380PWS
			•	•			•		•
Butler		LISTA DEI LIST		OF COMPONENTS - TEILELISTE CHEES - LISTA DE PIEZAS		GRUPPO MOTORE MOTOR UNIT MOTORSATZ		1	Pag. 8 di 36
ENGINEERING and MARKETING S.P.A.		Tavola	N°2B - Rev. 1	129692	322	GROUPE MOTEUR GRUPO MOTOR			



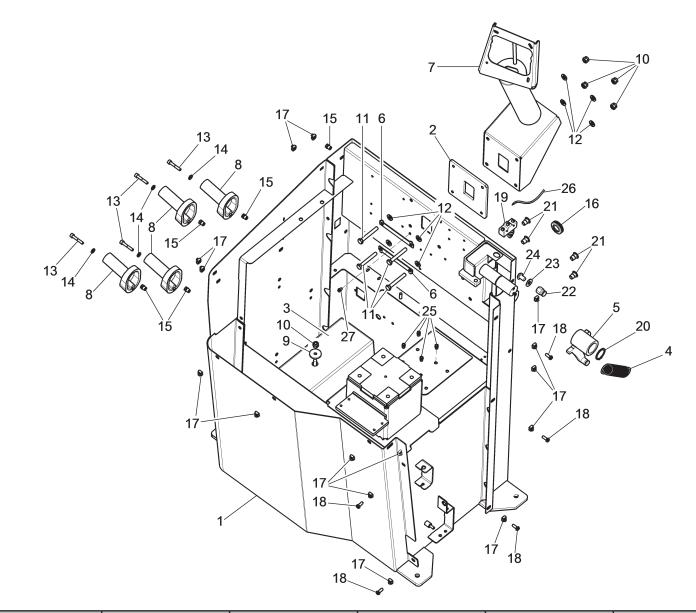
LIBRAK380 LIBRAK380P		LIBRAK380S LIBRAK380PS		LIBRAK380W	LIBRAK380PW	LIBRAK380WS		LIBRAK380PWS	
•			•		•		•		
Butler			COMPONENTI - LIST È DES PIECES DETA			GRUPPO ROTANTE COM COMPLETE ROTARY KOMPLETTER ROTIERENI	UNIT DER SATZ	F	Pag. 9 di 36
ENGINEERING and MARKETING S.P.A.		Tavola	N°3A - Rev. 1	129690	090	GROUPE ROTATIF CON GRUPO GIRATORIO CON			



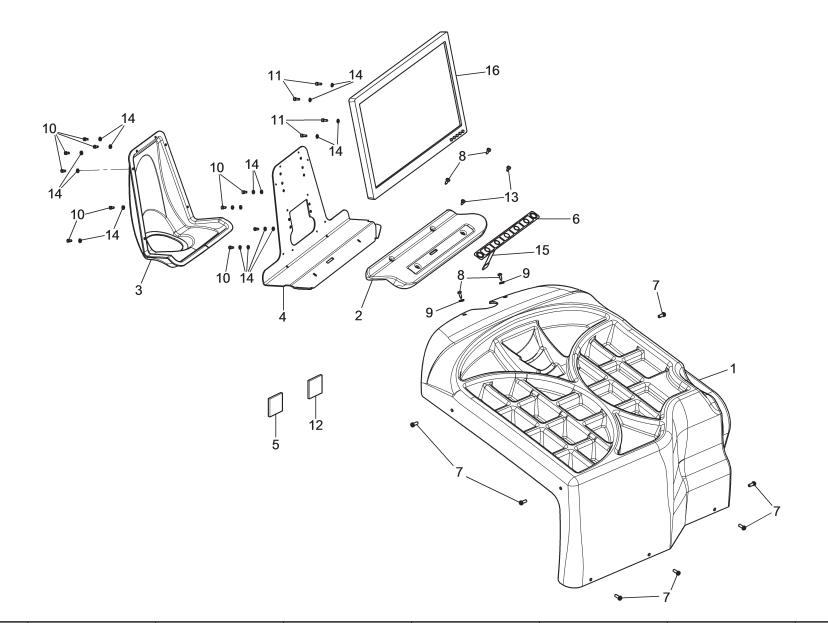
LIBRAK380	LIBRAK380P	LIBRAK380S	LIBRAK380S LIBRAK380PS		LIBRAK380PW	LIBRAK380WS	LIBRAK380PWS
	•		•		•		•
Butle			COF COMPONENTS - TEILELISTE ACHEES - LISTA DE PIEZAS		GRUPPO ROTANTE COM COMPLETE ROTARY (KOMPLETTER ROTIERENI	JNIT DER SATZ	Pag. 10 di 36
ENGINEERING and MARKETIN	GS.P.A. Tavo	la N°3B - Rev. 1	129690	0030	GROUPE ROTATIF COM GRUPO GIRATORIO COM		



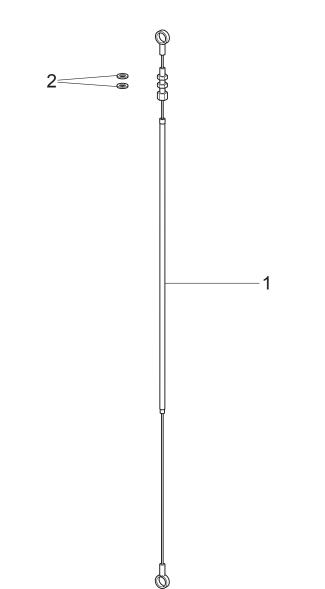
LIBRAK380	380 LIBRAK380P		RAK380P LIBRAK380S LIBRAK380PS		LIBRAK380W	LIBRAK380PW	LIBRAK380WS		LIBRAK380PWS
•	• •		•	•	•	•	•		•
Butler			COMPONENTI - LIST TE DES PIECES DETA			GRUPPO FRENO BRAKE UNIT BREMSATZ		Рад	g. 11 di 36
ENGINEERING and MARKETIN	GS.P.A.	Tavola	N°4 - Rev. 0	129690	292	GROUPE FREIN GRUPO FRENO			



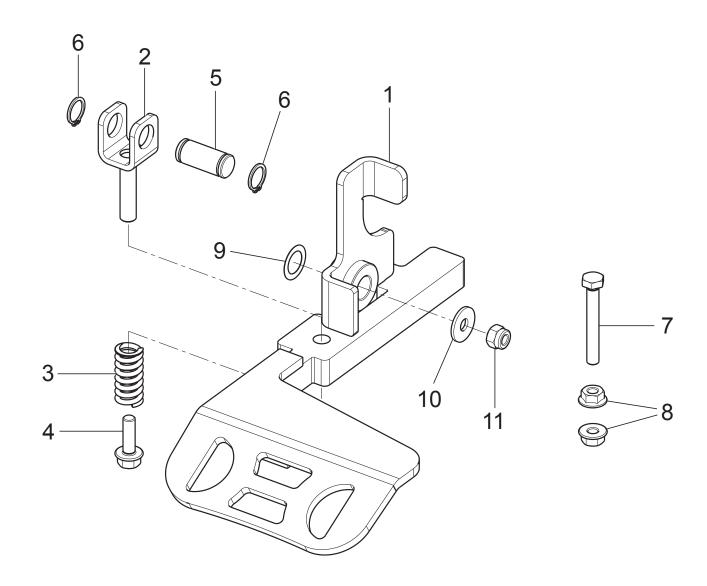
LIBRAK380 LIBRAK380P		LIBRAK380S	LIBRAK380PS LIBRAK380W		LIBRAK380PW	LIBRAK380WS		LIBRAK380PWS	
• •		•	•	•	•	•	• •		•
Butler		LISTA DEI LIST			F COMPONENTS - TEILELISTE HEES - LISTA DE PIEZAS			P	ag. 12 di 36
ENGINEERING and MARKETING S.P.A.		Tavola	N°5 - Rev. 1	129791	.644	GROUPE CHASSI GRUPO ESTRUCTU			



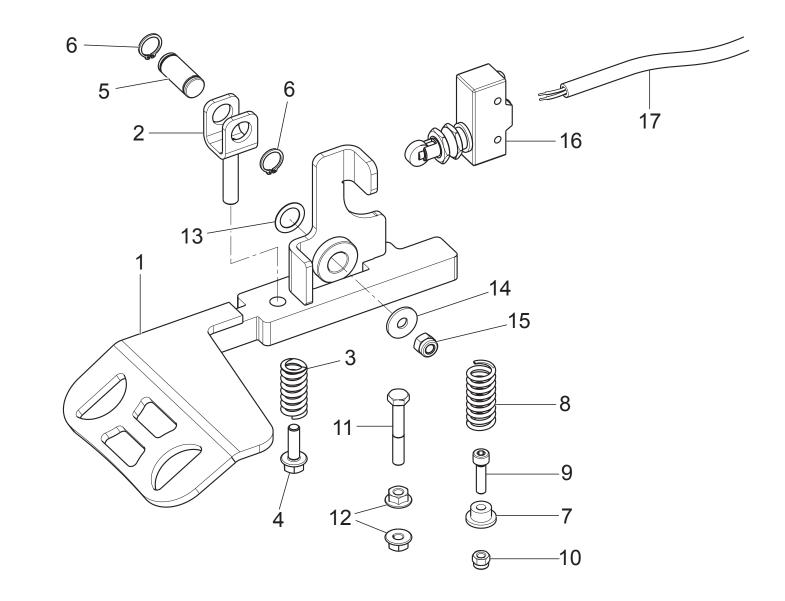
LIBRAK380 LIBRAK380P		LIBRAK380S LIBRAK380PS		LIBRAK380W	LIBRAK380PW	LIBRAK380WS		LIBRAK380PWS	
• •		•	•	•	•	•		•	
Butler		LISTA DEI LIST	COMPONENTI - LIST TE DES PIECES DETA			GRUPPO PLANCIA MONI 19" MONITOR BOARD MONITOR-BRETTS/	UNIT NTZ	Pag. 13 di 36	
ENGINEERING and MARKETING S.P.A.		Tavola	N°6 - Rev. 1	129792	2412	GROUPE PLANCHE MO GRUPO TABLERO MOI			



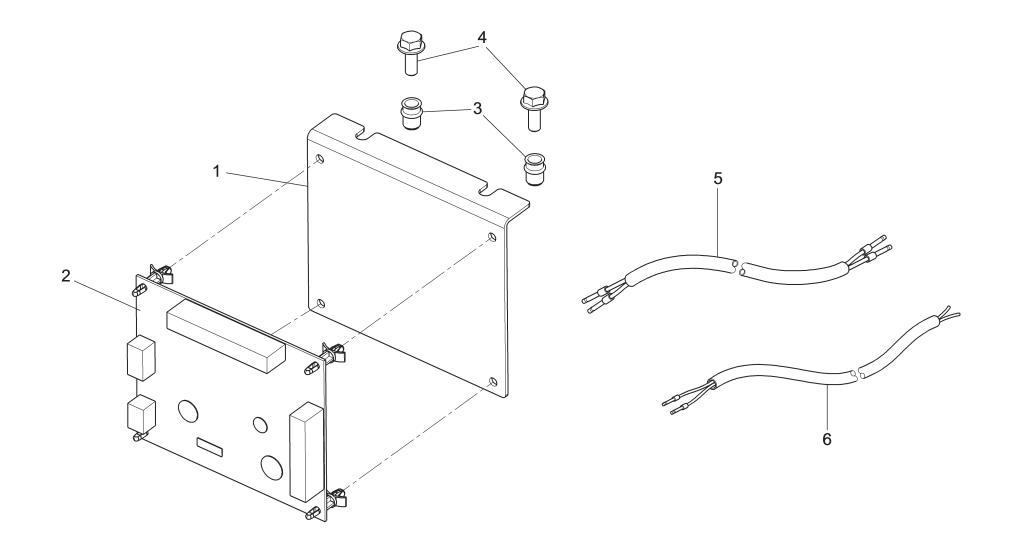
LIBRAK380 LIBRAK380P		LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380W	S LIBRAK380PWS
•	•	•	•	•	•	•	•
Butle	LISTA DE	I COMPONENTI - LIST FE DES PIECES DETA			GRUPPO AZIONAMENTO BRAKE OPERATION G. SATZ FÜR BREMSBETÄ	ROUP FIGUNG	Pag. 14 di 36
ENGINEERING and MARKETIN	GS.P.A. Tavola	N°7 - Rev. 0	129791	1780	GROUPE ACTIONNEMEN GRUPO ACCIONAMIENTO		



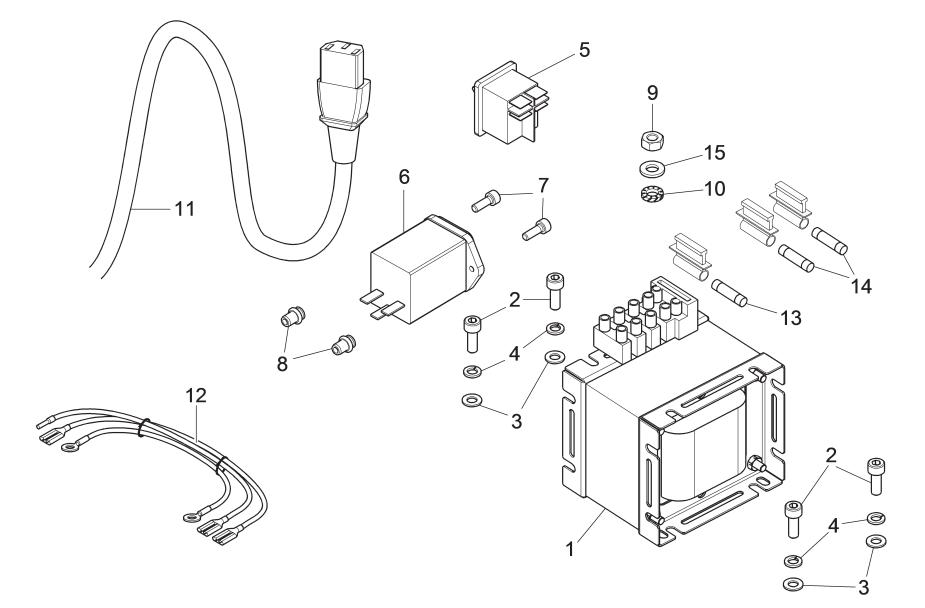
LIBRAK380	LIE	BRAK380P	LIBRAK380S LIBRAK380PS LIBRAK380W		LIBRAK380PW	LIBRAK380V	VS	LIBRAK380PWS	
•			•		•		٠		
Butle	? r				DF COMPONENTS - TEILELISTE HEES - LISTA DE PIEZAS		N FILO CLAMP DRAHT	P	ag. 15 di 36
ENGINEERING and MARKETIN	IGS.P.A.	Tavola	N°8A - Rev. 1	129794	1590	GROUPE PÉDALES DE DIRECTI GRUPO PEDALERA COI			



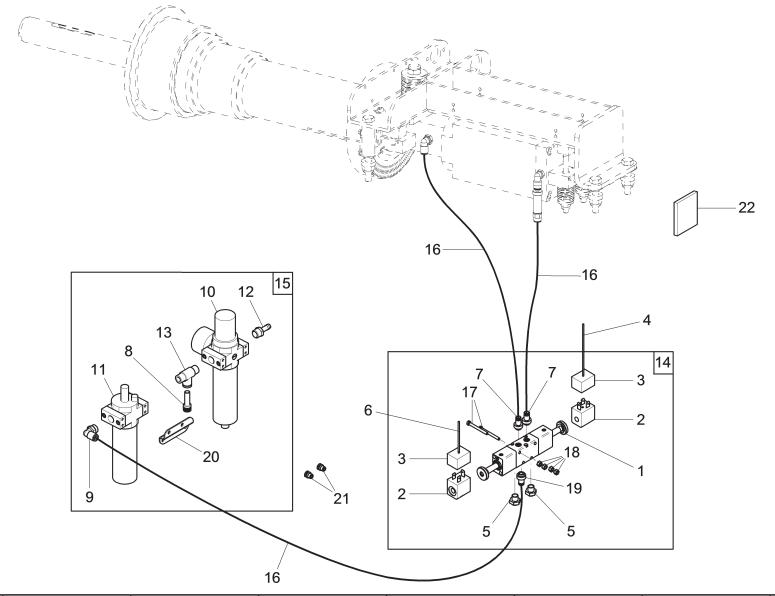
LIBRAK380	LI	BRAK380P	LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380WS		LIBRAK380PWS
	•			•		•			•
Butle	er			OF COMPONENTS - TEILELISTE CHEES - LISTA DE PIEZAS		GRUPPO PEDALIERA CO PEDALBOARD UNIT WITI PEDALLEISTESATZ MIT	I CLAMP DRAHT	P	ag. 16 di 36
ENGINEERING and MARKETI	NG S.P.A.	Tavola	N°8B - Rev. 1	129794	600	GROUPE PÉDALES DE DIRECT GRUPO PEDALERA CO.			



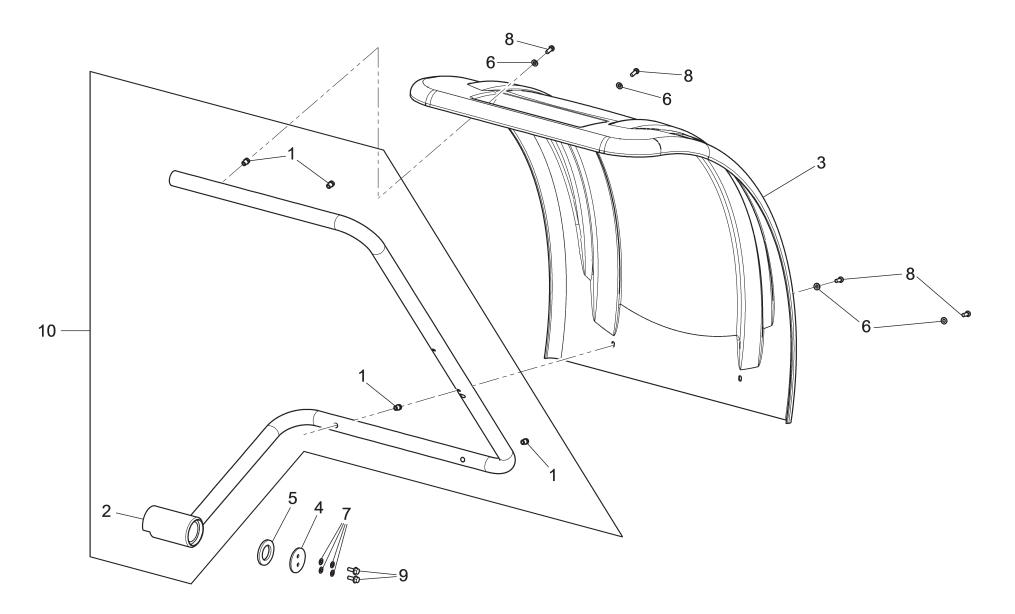
LIBRAK380	380 LIBRAK380P		LIBRAK380S LIBRAK380PS		LIBRAK380W	LIBRAK380PW	LIBRAK380WS		LIBRAK380PWS
			•	•			•		•
Butler			COMPONENTI - LIST TE DES PIECES DETA			GRUPPO SCHEDA AGGIUNT LASER ADDITIONAL CAR SATZ VON ZUSÄTZLICHE LA	ND UNIT SER-KARTE	P	Pag. 17 di 36
ENGINEERING and MARKETIN	ENGINEERING and MARKETING S.P.A.		N° 9 - Rev. 1	129794	221	GROUPE CARTE ADDITIONNI GRUPO FICHA AÑADIVA			



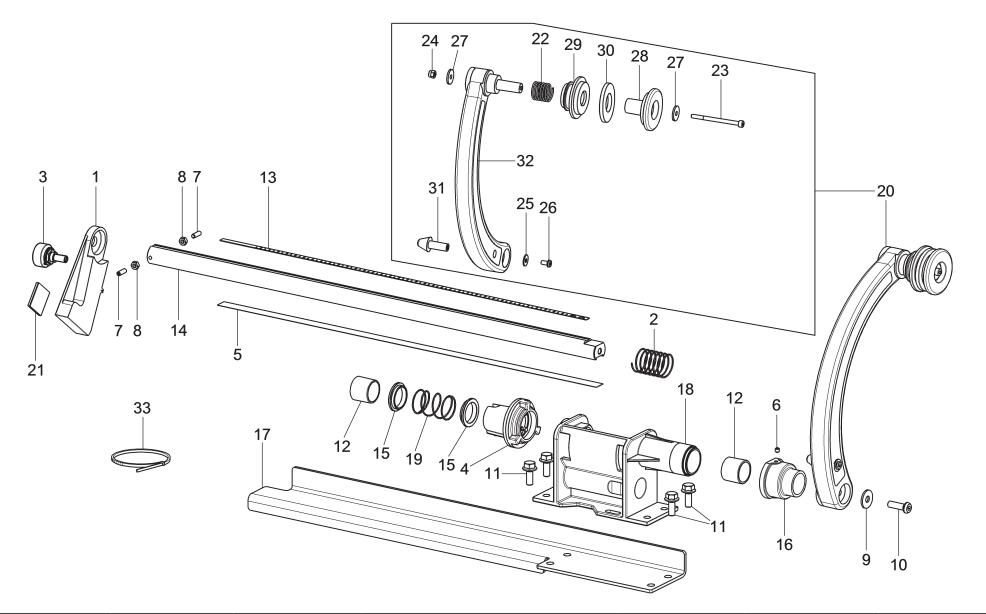
LIBRAK380	LIE	BRAK380P	LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380	vs	LIBRAK380PWS
•	•		•	٠	•	•	•		•
Butler			LISTA DEI COMPONENTI - LIST OF COMPONENTS - TEILELIS LISTE DES PIECES DETACHEES - LISTA DE PIEZAS			GRUPPO IMPIANTO ELE ELECTRICAL SYSTEM SATZ VON ELEKTROAN	UNIT ILAGE	Р	ag. 18 di 36
ENGINEERING and MARKETING S.P.A.		Tavola	N°10 - Rev. 1	129790	0131	GROUPE INSTALLATION ÈL GRUPO INSTALACIÓN EL			



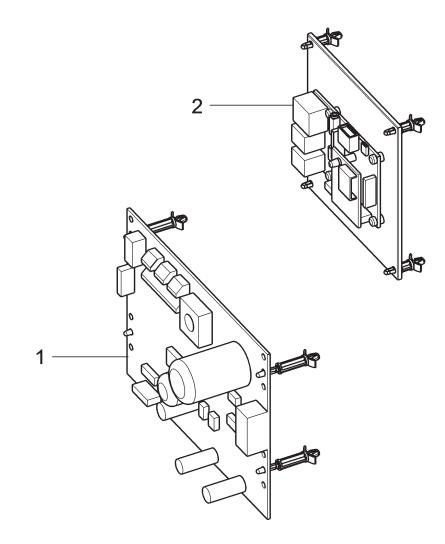
LIBRAK380	LIBRAK380P		LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380WS	S LIBRAK380PWS
	•			•		•		•
Butler		LISTA DEI LIST	COMPONENTI - LIST TE DES PIECES DETA			IMPIANTO SERRAGGIO PNU PNEUMATIC TIGHTENING ANLAGE FÜR PNEUMATISCHE A	SYSTEM AUFSPANNUNG	Pag. 19 di 36
ENGINEERING and MARKETIN	IG S.P.A.	Tavola	N°11 - Rev. 1	129390	311	SYSTÈME SERRAGE PNEU SISTEMA APRIETE NEUI		

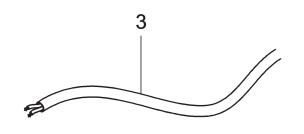


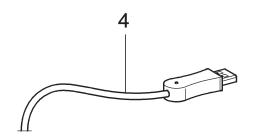
LIBRAK380	80 LIBRAK380P		LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380WS		LIBRAK380PWS
•		•	•	•	•	•	•		•
Butler ENGINEERING and MARKETING S.P.A.		LISTA DEI LIST	COMPONENTI - LIST È DES PIECES DETA			GRUPPO PROTEZIONE . WHEEL PROTECTION SATZ FÜR RADSCHU	UNIT JTZ	Р	ag. 20 di 36
		Tavola	N°12 - Rev. 1	129791	.580	GROUPE PROTECTION GRUPO PROTECCIÓN F			



LIBRAK380	LIBRAK380 LIBRAK380P		LIBRAK380S LIBRAK380PS		LIBRAK380W	LIBRAK380PW	LIBRAK380	ws	LIBRAK380PWS
•	•		•	•	•	•	•		•
ENGINEERING and MARKETING S.P.A.			COMPONENTI - LIST TE DES PIECES DETA	GRUPPO CALIBRO DISTANZA CALIPER UNIT DISTANCE/I KALIBERSATZ ABSTAND/DUI	DIAMETER RCHMESSER	Ро	ag. 21 di 36		
		Tavola	N°13 - Rev. 1	129791	490	GROUPE CALIBRE DISTANCI GRUPO CALIBRE DISTANCIA	'		

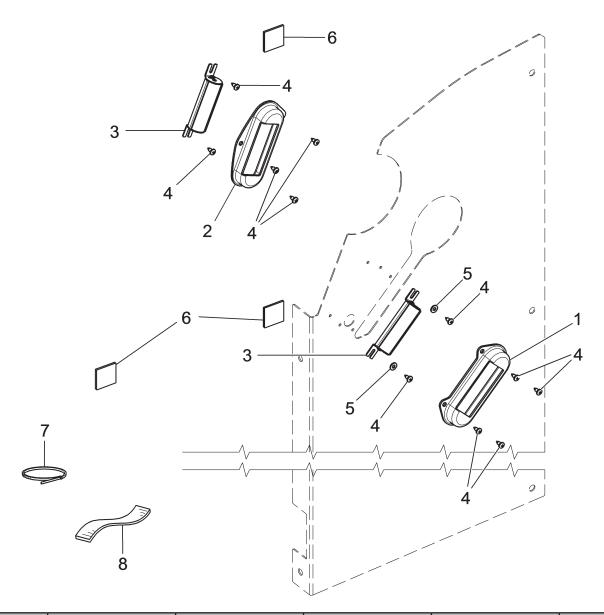




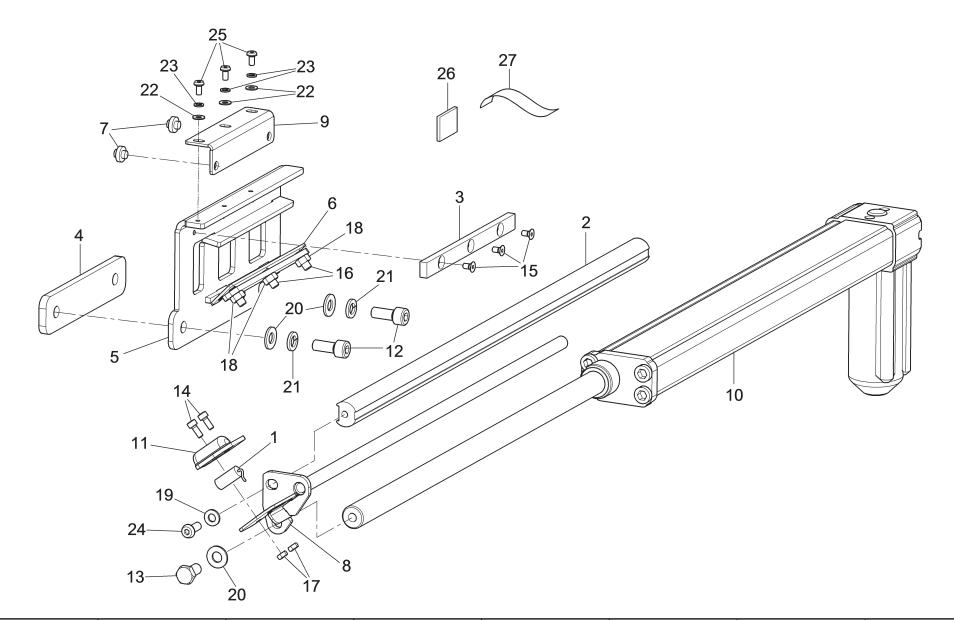




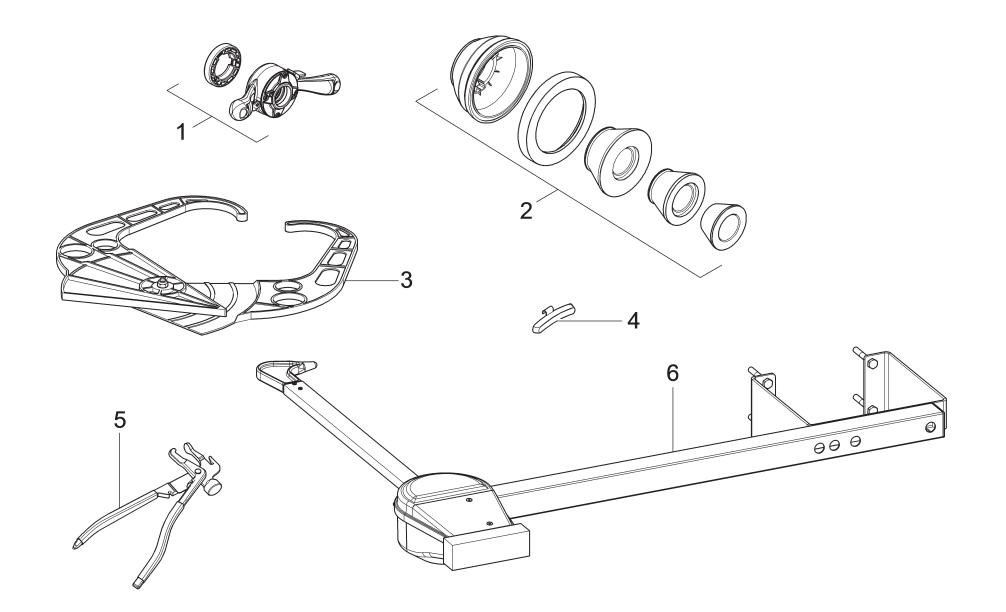
LIBRAK380	80 LIBRAK380P		K380P LIBRAK380S LIBRAK380PS LIBRAK380W LIBRAK380PW		LIBRAK380WS		LIBRAK380PWS		
•	•		•	•	•	• •			•
Butle			COMPONENTI - LIST E DES PIECES DETA			GRUPPO ELETTRON ELECTRONICS UN ELEKTRONIKSAT	IT Z	Pag	J. 22 di 36
ENGINEERING and MARKETING	GS.P.A.	Tavola	N°14 - Rev. 1	129792	331	GROUPE ÉLECTRON GRUPO ELECTRÓN			



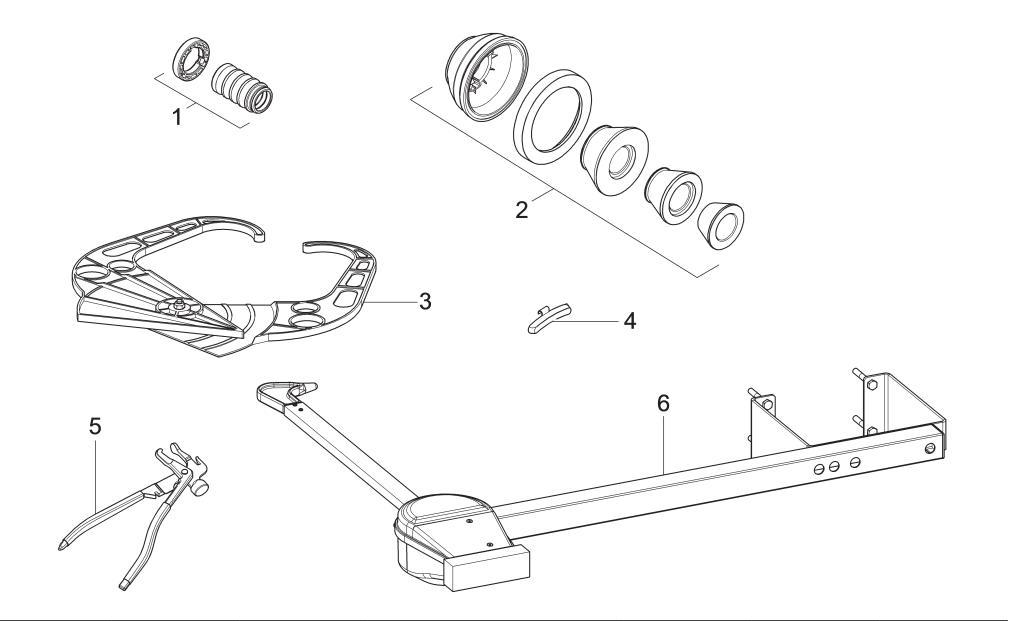
LIBRAK380	LIBRAK380 LIBRAK380P		LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380WS		LIBRAK380PWS
•	•	•	•	•	•	•		•
Butle	LISTA DEI LIST	COMPONENTI - LIST TE DES PIECES DETA		GRUPPO ILLUMINAT LIGHTING DEVICE U BELEUCHTUNGSA	NIT FZ	P	ag. 23 di 36	
ENGINEERING and MARKETING	GS.P.A. Tavola	N°15 - Rev. 1	129794	250	GROUPE DISPOSITIF D'ÉC GRUPO ILUMINADO			



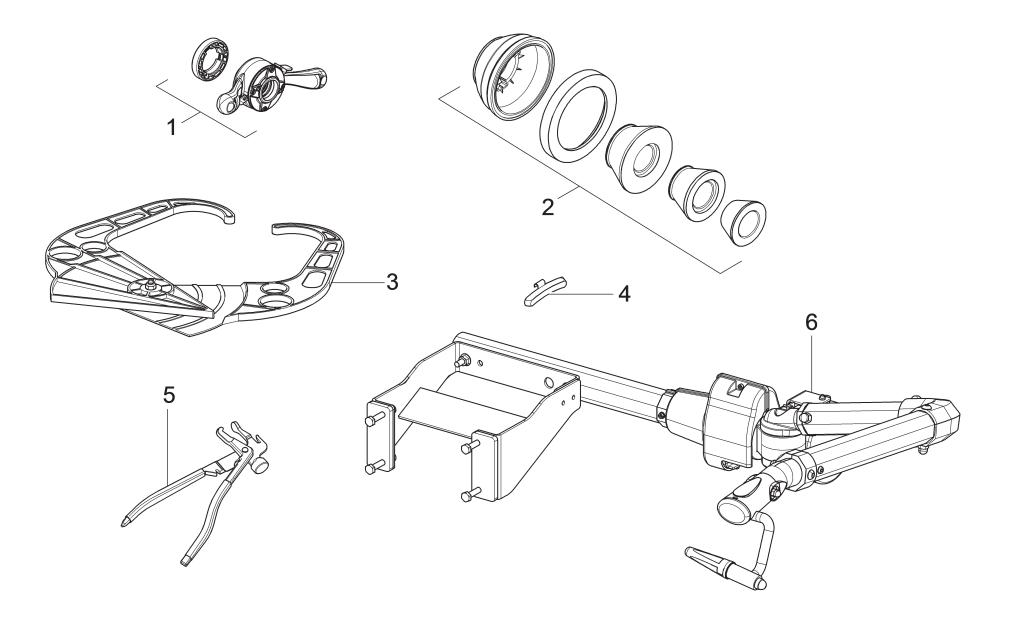
LIBRAK380	LIBRAK380P		LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380WS		LIBRAK380PWS
			•	٠			•		•
BULIEF LIS		LISTA DEI LIST	COMPONENTI - LIST TE DES PIECES DETA			GRUPPO LASER SP SPOT LASER UNI SPOT LASER SATZ		P	ag. 24 di 36
		N°16 - Rev. 1	129794	650	GROUPE LASER SP GRUPO LASER SPC				



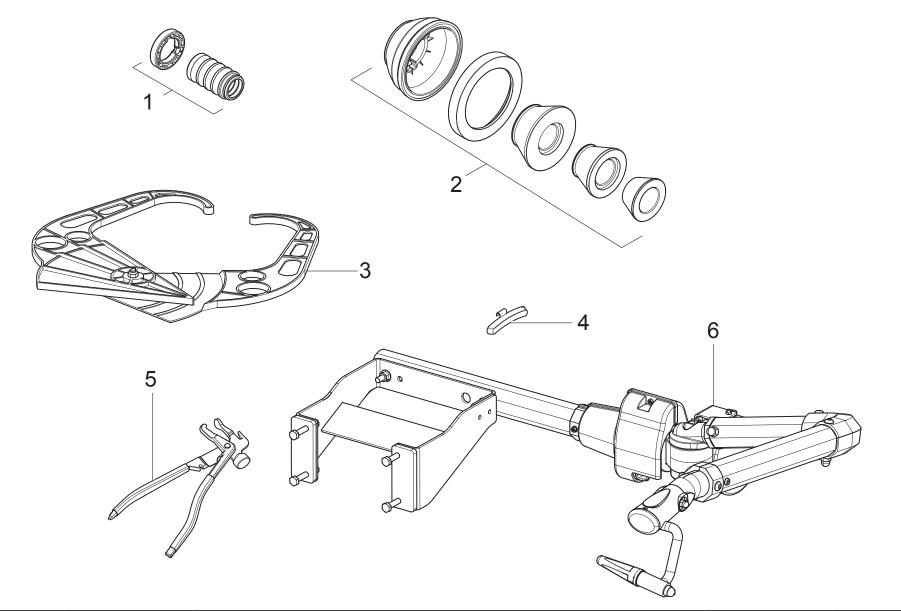
LIBRAK380	LIE	BRAK380P	LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380WS	LIBRAK380PWS
•								
Butler			COMPONENTI - LIST TE DES PIECES DETA			DOTAZIONE A A EQUIPMENT AUSSTATTUNG A		Pag. 25 di 36
ENGINEERING and MARKETING	GS.P.A.	Tavola	N°17A - Rev. 1			DOTATION A DOTACION A		



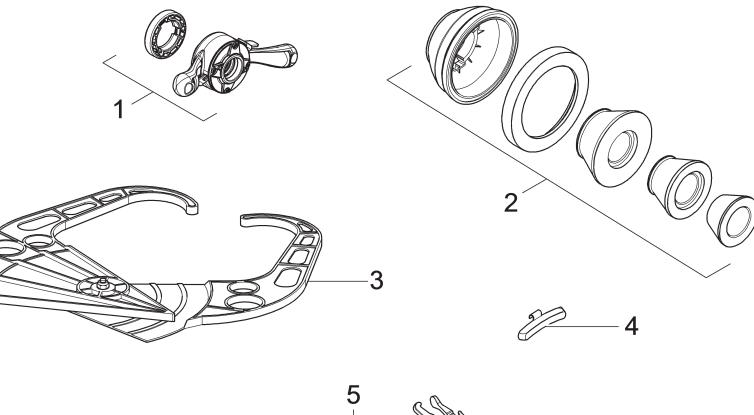
LIBRAK380	LIBRAK380P		LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380WS	LIBRAK380PWS
		•						
Butler '			COMPONENTI - LIST TE DES PIECES DETA			DOTAZIONE B B EQUIPMENT AUSSTATTUNG B	1	Pag. 26 di 36
ENGINEERING and MARKETIN	GS.P.A.	Tavola	N°17B - Rev. 1			DOTATION B DOTACION B		

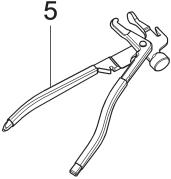


LIBRAK380	K380 LIBRAK380P		LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380WS	LIBRAK380PWS
			•					
ENGINEERING and MARKETING S.P.A.			COMPONENTI - LIST TE DES PIECES DETA			DOTAZIONE C C EQUIPMENT AUSSTATTUNG	C I	Pag. 27 di 36
		Tavola	N°17C - Rev. 1			DOTATION C DOTACION C		

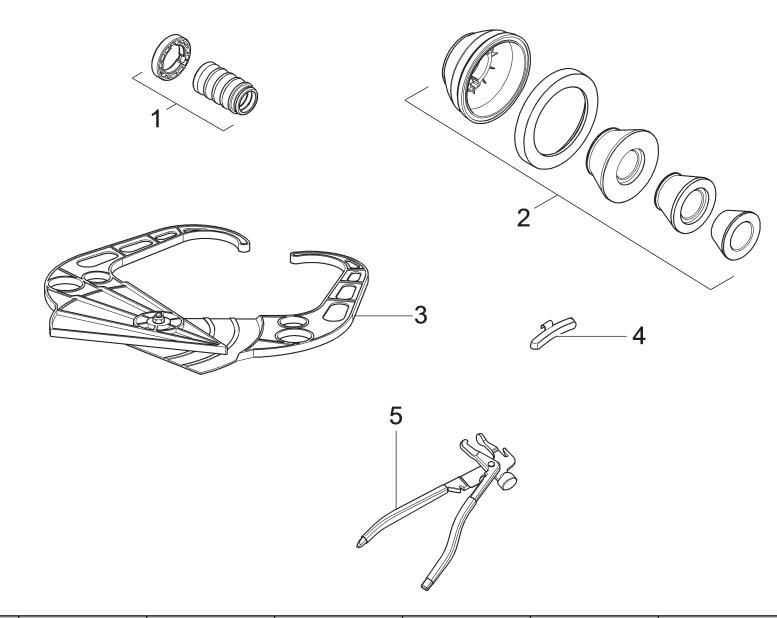


LIBRAK380	LIBRAK380P		LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380WS	LIBRAK380PWS
				•				
Butler			COMPONENTI - LIST TE DES PIECES DETA			DOTAZIONE D D EQUIPMENT AUSSTATTUNG D		Pag. 28 di 36
ENGINEERING and MARKETIN	GS.P.A.	Tavola	N°17D - Rev. 1			DOTATION D DOTACION D		

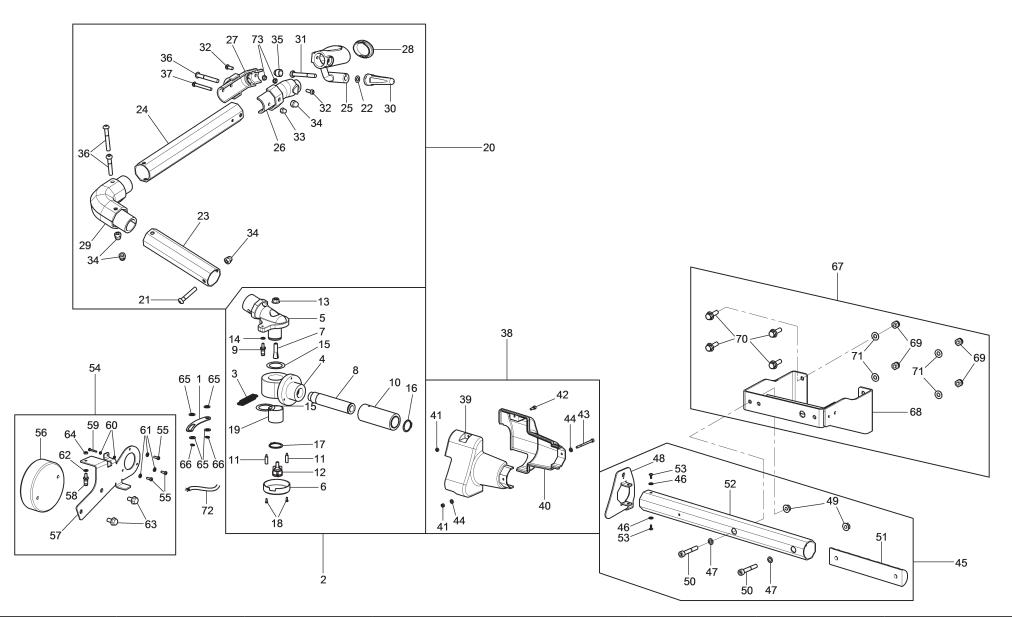




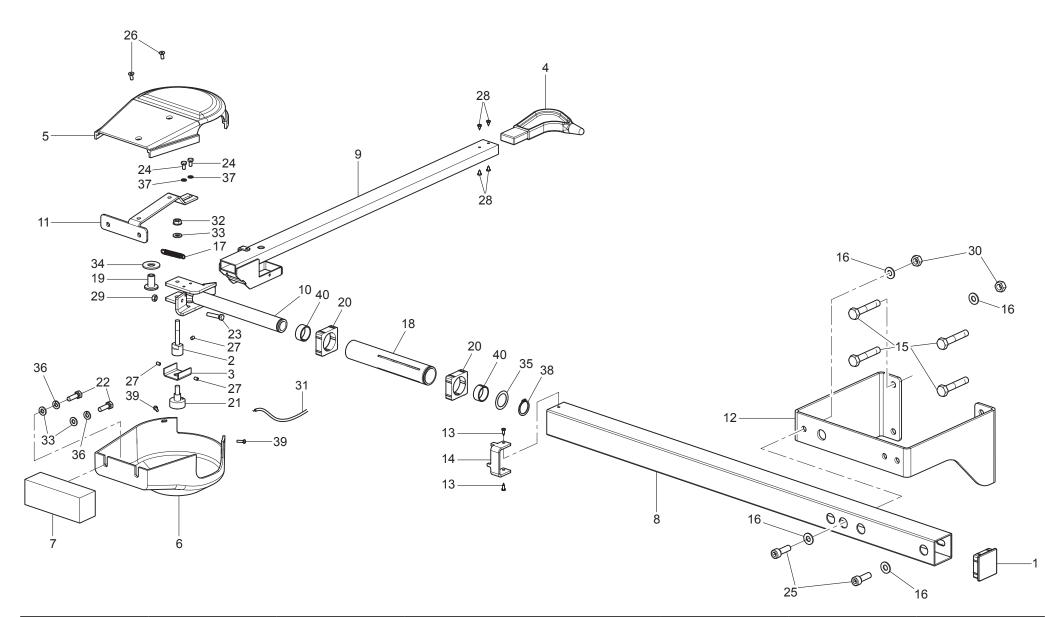
LIBRAK380	LIBRAK380P	LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380WS	LIBRAK380PWS
				•		•	
Butle	LISTA DI	XI COMPONENTI - LIST TE DES PIECES DETA			DOTAZIONE E E EQUIPMENT AUSSTATTUNG E		Pag. 29 di 36
ENGINEERING and MARKETING	GS.P.A. Tavol	a N°17E - Rev. 0			DOTATION E DOTACION E		



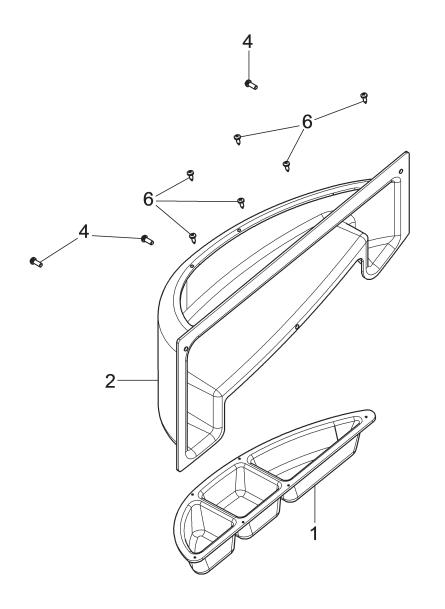
LIBRAK380	LIBRAK380P		LIBRAK380S	LIBRAK380PS	LIBRAK380W		LIBRAK380PW	LIBRAK380	VS	LIBRAK380PWS
							•			•
ENGINEERING and MARKETING S.P.A.		LISTA DEI COMPONENTI - LIST OF COMPONENTS - TEILELISTE LISTE DES PIECES DETACHEES - LISTA DE PIEZAS				DOTAZIONE F F EQUIPMENT AUSSTATTUNG F			Pag. 30 di 36	
		Tavola	N°17F - Rev. 0				DOTATION F DOTACION F			

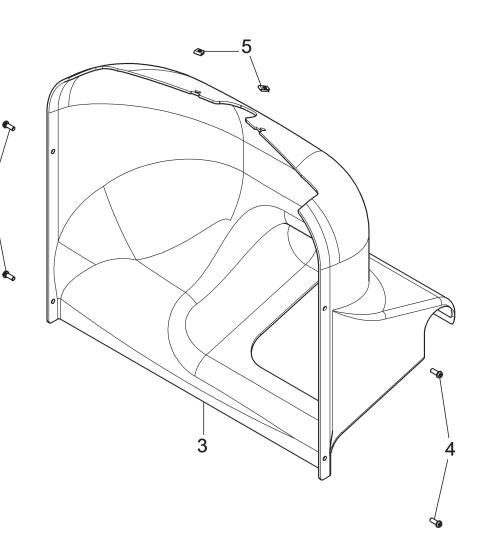


LIBRAK380	LI	BRAK380P	LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380W	S LIBRAK380PWS	
OPT		OPT	•	•					
ENGINEERING and MARKETING S.P.A.		LISTA DEI COMPONENTI - LIST OF COMPONENTS - TEILELISTE LISTE DES PIECES DETACHEES - LISTA DE PIEZAS				CALIBRO LARGHEZZA PROFESSIONALE PROFESSIONAL EXTERNAL DATA GAUGE BERUFLICHE BREITENLEHRE		Pag. 31 di 36	
		Tavola	N°18 - Rev. 1	GAR3	05	CALIBRE LARGEUR PROFE CALIBRE ANCHO PROFE			

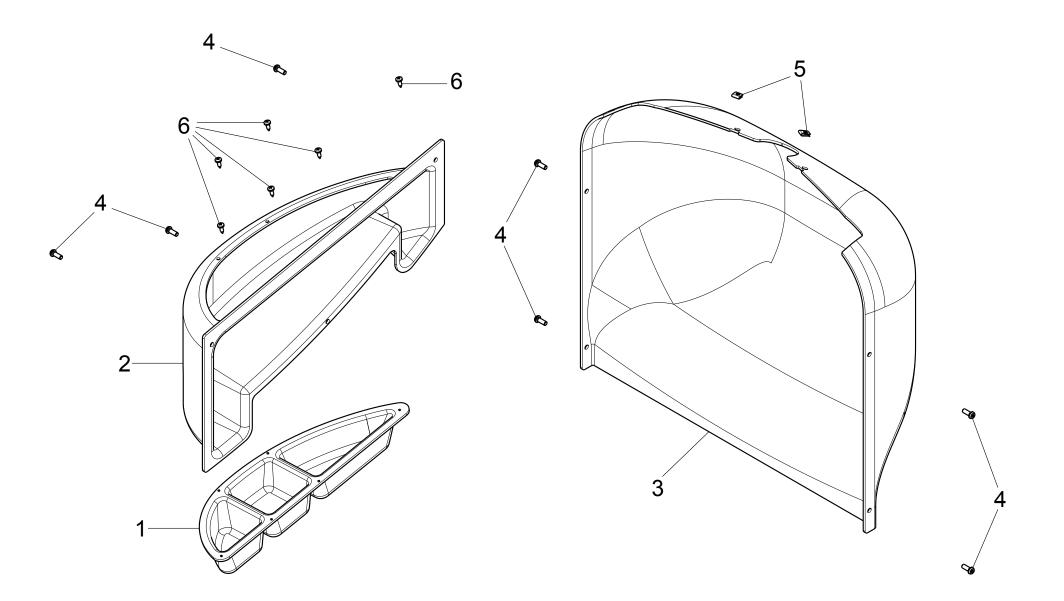


LIBRAK380	LIBRAK380P		LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380WS		LIBRAK380PWS
•		•							
ENGINEERING and MARKETING S.P.A.		LISTA DEI COMPONENTI - LIST OF COMPONENTS - TEILELISTE LISTE DES PIECES DETACHEES - LISTA DE PIEZAS				CALIBRO LARGHEZZA RUOTE WHEEL WIDTH EXTERNAL DATA GAUGE BREITENTASTER		Pag. 32 di 36	
		Tavola	N°19 - Rev. 1	GAR3	07	TIGE EXTERNE LARGEUI PALPADOR ANCHURA R			

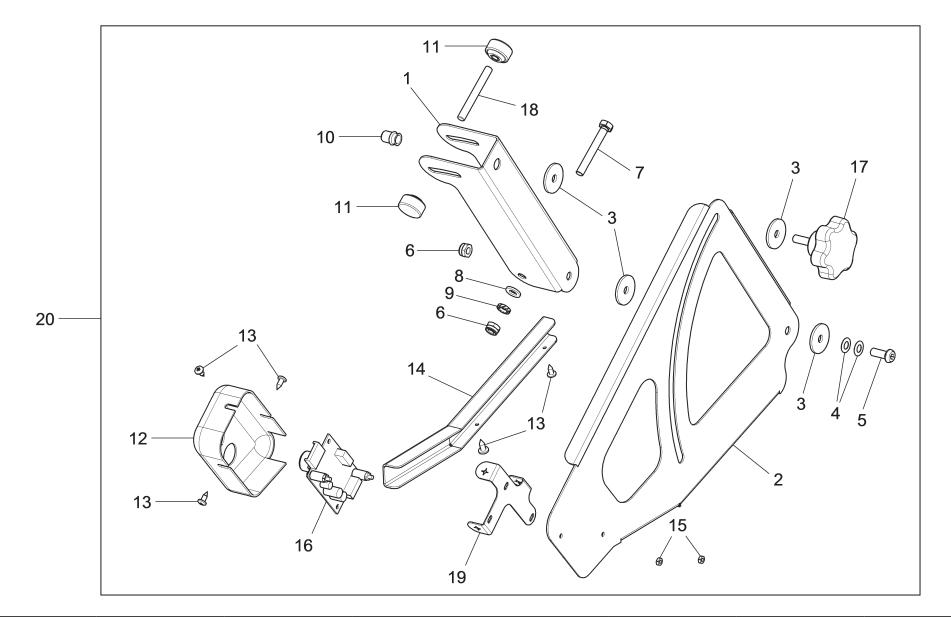




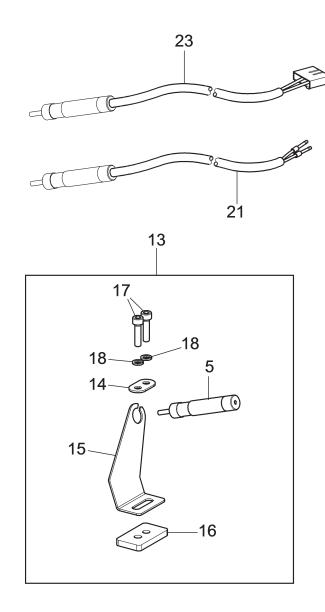
LIBRAK380		BRAK380P	LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380WS	LIBRAK380PWS
•		•	•	•				
ENGINEERING and MARKETING S.P.A.		LISTA DEI COMPONENTI - LIST OF COMPONENTS - TEILELISTE LISTE DES PIECES DETACHEES - LISTA DE PIEZAS			GRUPPO COMPLETAMENTO PLANCIA BOARD COMPLETION UNIT BRETTAUSBAUSATZ		Pag. 33 di 36	
		Tavola	N°20A - Rev. 0	129791	.741	GROUPE D'ACHÈVEMENT . GRUPO DE ACEBADO TA		

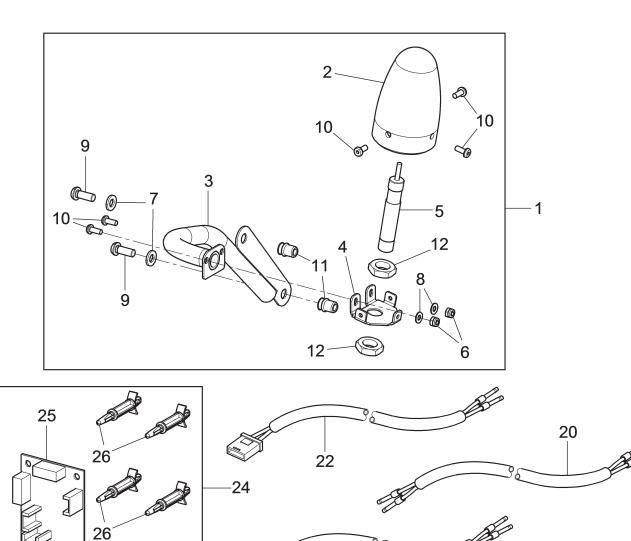


LIBRAK380	LIBRAK380H	LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380V	WS LIBRAK380PWS	
				•	•	•	•	
Butle		DEI COMPONENTI - LIST LISTE DES PIECES DETA		GRUPPO COMPLETAM FRAME COMPLETION AUSBAUSATZ	Pag. 34 di 36			
ENGINEERING and MARKETING	GS.P.A. Ta	vola N°20B - Rev. 0	129794	440	GROUPE D'ACHÈVEM GRUPO DE ACEBAI			



LIBRAK380	LIBRAK380P		LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380PW LIBRAK380W		LIBRAK380PWS
					•	•	•		•
			COMPONENTI - LIST TE DES PIECES DETA			GRUPPO MISURATORE LARGHEZ AUTOMATIC MEASURING D. AUTOMATISCHE BREITEN-MESS	EVICE UNIT SVORRICHTUNG	P	ag. 35 di 36
		Tavola	N°21 - Rev. 0	GAR3	32	GROUPE MESUREUR AUTOMATIQUE DE LA LARGEUR GRUPO MEDIDOR ANCHO AUTOMÁTICO			





19

LIBRAK380	LIBRAK380P	LIBRAK380S	LIBRAK380PS	LIBRAK380W	LIBRAK380PW	LIBRAK380WS	LIBRAK380PWS
OPT	OPT	OPT	OPT	OPT	OPT	OPT	OPT
Butle		CI COMPONENTI - LIST STE DES PIECES DETA		DISPOSITIVO LASER O LASER DEVICE AT 12 O LASERVORRICHTUNG AU	CLOCK F 12 UHR	Pag. 36 di 36	
ENGINEERING and MARKETIN	GS.P.A. Tavo	a N°22 - Rev. 0	GAR3	34	DISPOSITIF LASER À MIDI DISPOSITIVO LÁSER A LAS 12		