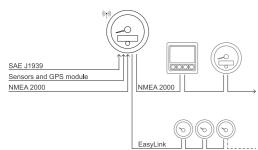
INTRODUCTION

Description

The GPS speedometer is a master gateway that collects data received from analog sensors and CAN bus network and makes them available on NMEA 2000 bus and OceanLink 52 mm gauges. In addition to indicate the speed (over ground, SOG or through water, STW), it displays real-time engine, environment and navigation values. A built-in GPS module accurately calculates the position and automatically reads the date/time.



Received signal priority

If the same data is available from more than one source, the received signal priority is the following:

GPS position

Built-in GPS module

Sensors and engine

- Analog sensor
- NMEA 2000
- SAE J1939
- 2. NMEA 2000 Note: the speed source can be manually set.

Battery (for power voltage) Self counting (for engine operating hours)

Transmission via EasyLink

Data transmission to 52 mm gauges is automatic every 20 ms, no settings are required.

On/Off

The on/off mode depends on the power line connection. Typically, it is sufficient to simply turn the engine ignition key or turn on the service switchboard. The VDO logo and software version are displayed when turned on.

DATA PAGES

Description



	Part	Description	
	Α	Data symbol	
B Current value measure		Current value with relevant unit of measure	
	С	"AL": indication that at least one	

alarm was triggered. The current alarm list is available after the last data page, see "Managing alarms".

List of managed data

		Input signal			Output signal		Unit of
lcon	Information	NMEA 2000	SAE J1939	Analog sensor	NMEA 2000	EasyLink	measure
	Total engine operating hours	х	х	х	х	-	h
	Engine coolant temperature	х	х	-	Х	х	°C/°F
Q	Engine coolant pressure	х	х	-	Х	-	bar / psi/ kPa
0	Transmission oil temperature	х	Х	-	Х	-	bar / psi/ kPa
0	Transmission oil pressure	х	х	-	Х	х	bar / psi/ kPa
© !	Engine oil temperature	х	х	-	Х	х	°C/°F
Ø	Engine oil pressure	х	х	-	Х	х	bar / psi/ kPa
Ø	Engine oil level	-	х	-	-	-	%
®	Boost pressure	х	Х	-	Х	х	bar / psi/ kPa
Öl	Exhaust gas temperature	х	х	-	х	Х	°C/°F

Customer service and warranty

In the event of malfunction, fault or for information on the warranty, contact a VDO partner. To find a partner, visit www.vdo-partner.com.

Instructions available in multiple languages

These instructions are available in several languages at www.marine.vdo.com.

Continental Automotive Switzerland AG reserves the right to make modifications or improvements to the relative documentation without notice.

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Displaying pages

When turned on the device displays the last page selected before it was turned off. Briefly press the button

Note: the page with the total engine operating hours is displayed by default the first time the device is turned

Select the pages to be displayed

All pages are displayed by default. You can select which pages to be displayed/hidden in the settings menu in **Show screen**.

			Input signal		Output signal		Unit of
lcon	Information	NMEA 2000	SAE J1939	Analog sensor	NMEA 2000	EasyLink	measure
∏n∠min	Engine rpm	Х	х	х	Х	-	rpm
₽ ì	Fuel consumption	х	-	-	-	-	gal/h or I/h
ď	Fuel level	х	х	х	х	х	%
FRESH	Fresh water level	Х	-	х	х	х	%
WASTE	Waste water level	х	-	-	х	х	%
= +	Battery voltage	х	х	х	х	х	V
- +	Battery current	Х	х	-	Х	х	A
⊈	Speed through water (STW)	х	-	-	-	-	mph / kn or km/h
<u>4</u>	Speed over ground (SOG)	Х	-	x *	х	-	mph / kn or km/h
HDG	Magnetic heading	х	-	-	-	-	°M (magnetic North)
COG	Course over ground (COG)	Х	-	x*	х	-	°T (true North)
\$	Depth below transducer **	х	-	-	-	-	m / ft
‡ ⊆	Trim	х	-	х	х	х	%
Ď	Rudder angle	х	-	х	х	х	°S (starboard) / °P (port)
AIR	Room temperature	Х	-	-	-	-	°C/°F
	Sea water temperature	х	-	-	-	-	°C/°F
0	Time	х	-	x*	х	-	12h / 24h
⊕ ⊜	GPS module information ***	-	-	X *	х	-	-

Note*: data received by the built-in GPS module.

Note**: the displayed value depends on any set offset. It is the depth below transducer by default (offset = 0). Note***: data only displayed if GPS source = Int, see "Settings description".

GENERAL SETTINGS

CONFIG SPEED INPUT

CONFIG DEPTH

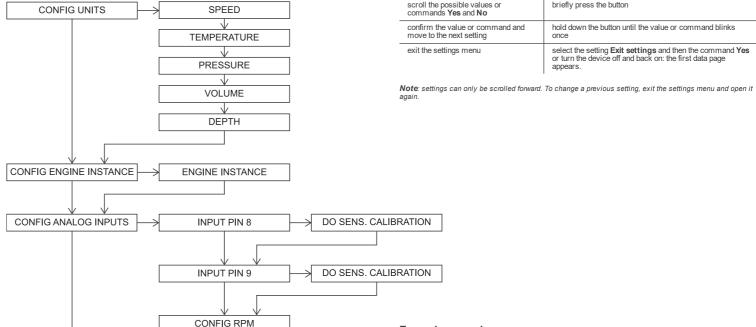
CONFIG CLOCK

SCREEN ON / OFF

SIMULATOR-MODE

EXIT SETTINGS

Settings menu description



GPS SOURCE

POINTER INDICATION

DEPTH OFFSET

UTC OFFSET h

TIME FORMAT

SHOW SCREEN

SHOW SCREEN

Example procedure

Using the settings menu

open the settings menu

To...

Following is the procedure to set **Engine instance** = 3

Then...

briefly press the button

turn on the device holding down the button until "Settings" appears: the Config units setting appears

hold down the button until the value or command blinks

select the setting **Exit settings** and then the command **Yes** or turn the device off and back on: the first data page appears.

Possible values/commands

- Turn on the device holding down the button until "Settings" appears: the Config units setting appears. Hold down the button until No blinks once: the Config engine instance setting appears. Briefly press the button to view Yes, then hold it down until Yes blinks once: the Engine instance setting appears with the current value. Briefly press the button to scroll values until 3 is displayed. Hold down the button until it blinks once: the Config analog inputs setting appears.

Description

Settings description

Setting

Speed	Speed units of measure	kmh/ mph/ kts
Temperature	Temperature units of measure	<u>°C</u> / °F
Pressure	Pressure units of measure	bar/ PSI/ kPA
Volume	Volume units of measure	Ltr/ gal
Depth	Depth units of measure	ft/ mtr
Engine instance	Displayed data engine, NMEA 2000 code.	0/ 1/ 2/ 3
Input pin 8	Type of sensor data on input 1	Off: no connected analog sensor Trim: trim, propeller tilt Fresh: fresh water level
Input pin 9	Type of sensor data on input 2	Fuel: fuel level Rudder: rudder angle
Do sens. calibration	Start sensor calibration	For information on sensor calibration, see "Sensors calibration".
Config RPM	Impulses per engine revolution	From 0.0 to 999.9 (default = 1.0)
GPS source	Speed source	Int: built-in GPS module Ext: via NMEA 2000
Pointer indication	Speed displayed by the device pointer	SOG: speed over ground STW: speed through water
Offset	Value to be added/subtracted from the depth to compensate for the transducer position compared to the waterline or keel	From -99.9 to + 99.9
UTC offset	Time zone	From -12 to +12 h
TimeFormat	Time format	• 12 h • 24 h
Show screen	Data to hide/show	For each data: • Yes • No
Simulator- mode	Simulation mode	Yes: the device displays random values. Data is also transmitted to connected 52 mm gauges. No: turn off simulation mode NOTICE: simulation mode remains enabled even after the device is turned off and back on until set to No.
Exit settings	Exiting the settings menu	Yes No

Note*: the underlined value/command is the default value/command.

SENSORS CALIBRATION

Calibration types

Analog sensors calibration can be:

- standard: for VDO sensors only. The type of sensor is set and the device reads the sensor value with good approximation without requiring calibration.
 manually: for non VDO sensors or to obtain more accurate indication from a VDO sensor. A three step procedure instructs the system to read the sensor value.

Starting calibration

CONFIG ANALOG INPUTS **INPUT PIN 8/9**

To start calibration, select the Do sens. calibration setting and then Yes: the Set default cal setting

Running manual calibration

- In Set default cal, select No.
- Run the operation displayed on the first row on the display.

 Select No: the device reads the sensor value and updates the last row on the display with the value
- 4. If the value read is correct, select **Yes**: the cursor moves on to the next calibration point. Otherwise
- select No to take another reading and obtain a correct value.

 5. Repeat steps 2-3-4 for the other two calibration points.

 6. To confirm changes, in Save changes, select Yes: a message confirms that calibration settings have

DISPLAY SETTINGS

Introduction

Display brightness and contrast can be adjusted. The display brightness applies to all masters on the NMEA 2000 bus and on connected 52 mm gauges.

ALARMS

Alarm signal

When an alarm is triggered, "New alarm" briefly appears on the display followed by the specific alarm message and buzzer (if connected). The message remains on the screen and the buzzer sounds until the alarm is acknowledged.

Note: alarms are not signaled when setting up the device.

If, after acknowledgment, at least one alarm is still active, "AL" blinks in the data pages.

Managed alarms list

NMEA2000 - Engine Parameters, Dynamic (PGN 127489)

- Check engine Hot engine
- Low oil presLow oil level
- Low fuel pres
- Low voltage
 Low cool level
- Water flow Water in fuel
- Charge indicat
- Preheat indic Boost pressure
- Over rev EGR system
- Main throttle
- Emergency stop General warn 1
- General warn 2 Pwr reduction
- Maintenance
- Eng com error Sub throttle
- Neutral prot Eng shut down

- NMEA2000 Transmission Parameters, Dynamic (PGN 127493)
- Check gearGear oil temp Gear oil pres
- Sail drive
- SAE J1939 Active Diagnostic Trouble Codes (DM1)
- Water in fuel indication
- Engine speed
- Engine speed Engine Turbocharger boost pressure Exhaust gas temperature Engine oil pressure
- Engine Coolant Pressure Engine Coolant Temperature
- Engine oil temperature
- Transmission oil temperature Transmission oil pressure
- Fuel Level

Running standard calibration

DO SENS, CALIBRATION

- Scroll the possible values and select the required one: the selected value blinks once.

 To confirm changes, in **Save changes**, select **Yes**: a message confirms that calibration settings have

SET DEFAULT CAL.

- In Set default cal, select Yes.

Adjusting display brightness and contrast

- From any data page, hold down the button until "Light" appears. If necessary, adjust the brightness level by briefly pressing the button.

Note: if "Light off" appears, brightness cannot be changed since the external lighting is off.

- To confirm the brightness level, hold down the button until the bar blinks once: "Contrast" appears.
- If necessary, adjust the contrast level by briefly pressing the button.
- To confirm the contrast level, hold down the button until the bar blinks once: the last page displayed

Managing alarms

- To acknowledge an alarm, briefly press the button: if other alarms were triggered (new or already acknowledged), the next alarm message appears. For the alarm display order, see "Managed alarms"

- IIST.

 2. To scroll alarms, briefly press the button: "Exit alarms" appears after the last alarm in the list.

 3. To scroll the alarm list again, select No. To exit the alarm list, select Yes: the data page displayed before the new alarm was triggered appears.

 4. To scroll the alarm list, scroll all data pages until "Alarm" appears and hold down the button for 3 seconds.

APPENDIX

Supported NMEA 2000 messages

PGN	Description
126992	System time
127250	Vessel heading
127488	Engine Parameters, Rapid Update
127489	Engine Parameters, Dynamic
127493	Transmission Parameters, Dynamic
127505	Fluid level
127508	Battery status
128259	Speed: Water referenced
128267	Water depth
129026	COG and SOG: Rapid update
129033	Local Time Offset
130310	Environmental parameters
130311	Environmental parameters
130312	Temperature
130316	Temperature, Extended Range
127245	Rudder
129025	Position: Rapid update

Electrical specifications

Rated voltage	12 / 24 V
Voltage tolerance	9-32 V
Working current	< 100 mA @ 12 V
Absorption (LEN)	2

Conformity

Conformity	CE Example 1
Directives	2014/30/EU (Electromagnetic compatibility) 2011/65/EU (Electrical-electronic equipment hazardous substances)
Reference standards	IEC 60945: 2002-08 (Environmental class: exposed)

SPARE PARTS, SENSORS AND ACCESSORIES

Available spare parts

Environmental specifications

Product	Part number
Pigtail cable with MX150 connector	A2C1433330001
White bezel	A2C1352140001
Black bezel	A2C1111380001
Chrome bezel	A2C1141580001
Spin lock	A2C13760900
EasyLink extension cable	A2C1650700001

Available accessories

To view available accessories, visit www.marine.vdo.com.

TECHNICAL SPECIFICATIONS

PBT and plastic lens

gauges output alarm (500 mA)

Built-in, 10 Hz

From -20 to +70 °C

From -30 to +85 °C

IP65

NMFA 2000 Micro-C M12

 1 frequency input (0-4 kHz) 1 built-in GPS module

via CAN bus (NMEA 2000)

0–14 / 0–35 / 0–70 kn / km/h / mph

Dot matrix LCD 132 x 33 px

Molex MX150 (with EasyLink connector built into the

via EasyLink (VDO proprietary protocol) to 52 mm

 via CAN bus (NMEA 2000 and SAE J1939) • 2 resistive analog inputs (0–400 Ω)

General features

Material

Connectors

Input data

Output data

Display

GPS antenna

Protection grade

Available variations

Working temperature

Storage temperature

Available analog sensors

Data type	Sensor type	Part number
Trim (Trim)	10–167 Ω	-
Fresh water level (Fresh)	3–180 Ω	226-828-001-001K
Fuel level 3–180 Ω (Fuel)		226-801-015-001G, 226-801-015-001C, A2C59510162, A2C59510168
	240–33 Ω	A2C59510166, A2C59510172, A2C1364580001
Rudder angle (Rudder)	10–180 Ω	A2C1102950001
(Nuudei)	5–90 Ω	A2C1102960001

Supported SAE J1939 messages

PGN SPN

		•
61444	190	Engine Speed
65253	247	Engine Total Hours of Operation
65262	110	Engine Coolant Temperature
65262	175	Engine Oil Temperature 1
65263	98	Engine Oil Level
65263	100	Engine Oil Pressure
65263	109	Engine Coolent Pressure
65266	183	Engine Fuel Rate
65270	102	Engine Turbocharger Boost Pressure
65270	173	Engine Exhaust Gas Temperature
65271	114	Net Battery Current
65271	115	Alternator Current
65271	158	Battery Potential (Voltage), Switched
65271	167	Charging System Potential (Voltage)
65271	168	Electrical Potential (Voltage)
65272	177	Transmission Oil Temperature
65272	127	Transmission Oil Pressure
65276	96	Fuel Consumption
65279	97	Water In Fuel Indicator

Description

TROUBLESHOOTING

Display problems

Problem	Cause	Solution
The displayed values	Incorrect sensor configuration	Check parameter settings in the settings menu, in Config analog inputs
are not	Incorrectly connected sensor	Check the connection, see installation instructions
those expected	The NMEA 2000 network backbone was incorrectly created	Check connections and make sure there is a termination at the beginning and end of the backbone
"" and not the	Data not available on the network	Wait
expected value	Sensor not connected	Connect the sensor, see installation instructions
appears on the display	The NMEA 2000 network backbone was incorrectly created	Check connections and make sure there is a termination at the beginning and end of the backbone

Problems on connected 52 mm gauges

Problem	Cause	Solution	
The gauge is backlit but the pointer does not move	Data not received from master	Check whether the 52 mm gauge is compatible with the master	
The pointer does not move and the gauge is not backlit	Master not powered	Check master connections Connect the power supply	
	No 52 mm chain gauge is connected to the master	Connect a 52 mm gauge to the master	

Problems with GPS (GPS speedometer only)

Problem	Cause	Solution
The displayed speed is ""	GPS module searching (GPS search)	Wait. The search takes about one minute, then the GPS is ready (GPS valid).

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