

A **Nidec** Group Company

**Nidec**  
Motors & Actuators

All for dreams™

**TURN** ADJUST  
*tilt* **RAISE**  
**OPEN** ROTATE  
MOVE  
close **SPIN**



**DRIVE TECHNOLOGY** 2011/12

# THE NIDEC MOTORS & ACTUATORS DC MOTOR RANGE

## MOTORS WITHOUT GEARING

GMP



→ Smaller diameter motors with single & double output shafts

- Nominal torque ..... 0.05 – 0.1 Nm
- No load speed ..... 2700 – 3250 min<sup>-1</sup>

GMK  
GML



→ Higher torque single output shaft motors

- Nominal torque ..... 0.12 – 0.4 Nm
- No load speed ..... 2200 – 5250 min<sup>-1</sup>

## MOTORS WITH SPUR GEAR

GMAG  
GMPI



→ Motors that can address all your in-line drive requirements where you need higher torque, lower speed rotation

- Nominal torque ..... 0.2 – 4 Nm
- No load speed ..... 17 – 200 min<sup>-1</sup>

## MOTORS WITH WORM GEAR

GMPD  
GMPG



→ Low/medium torque with perpendicular output shafts

- Nominal torque ..... 0.5 – 4 Nm
- No load speed ..... 21 – 540 min<sup>-1</sup>

GMPS



→ Actuators fitted with a lead-screw to drive your linear motion needs

- Nominal axial force ..... 1 – 2 kN
- No load speed ..... 6 mm/s

DCK31  
DCK35



→ Cost competitive medium torque range worm drive motors

- Nominal torque ..... 3 – 6 Nm
- No load speed ..... 14 – 270 min<sup>-1</sup>

SWMK  
SW2K  
SW2L



→ Weight optimized medium torque range

- Nominal torque ..... 0.8 – 8 Nm
- No load speed ..... 48 – 350 min<sup>-1</sup>

SWMV  
SWMG

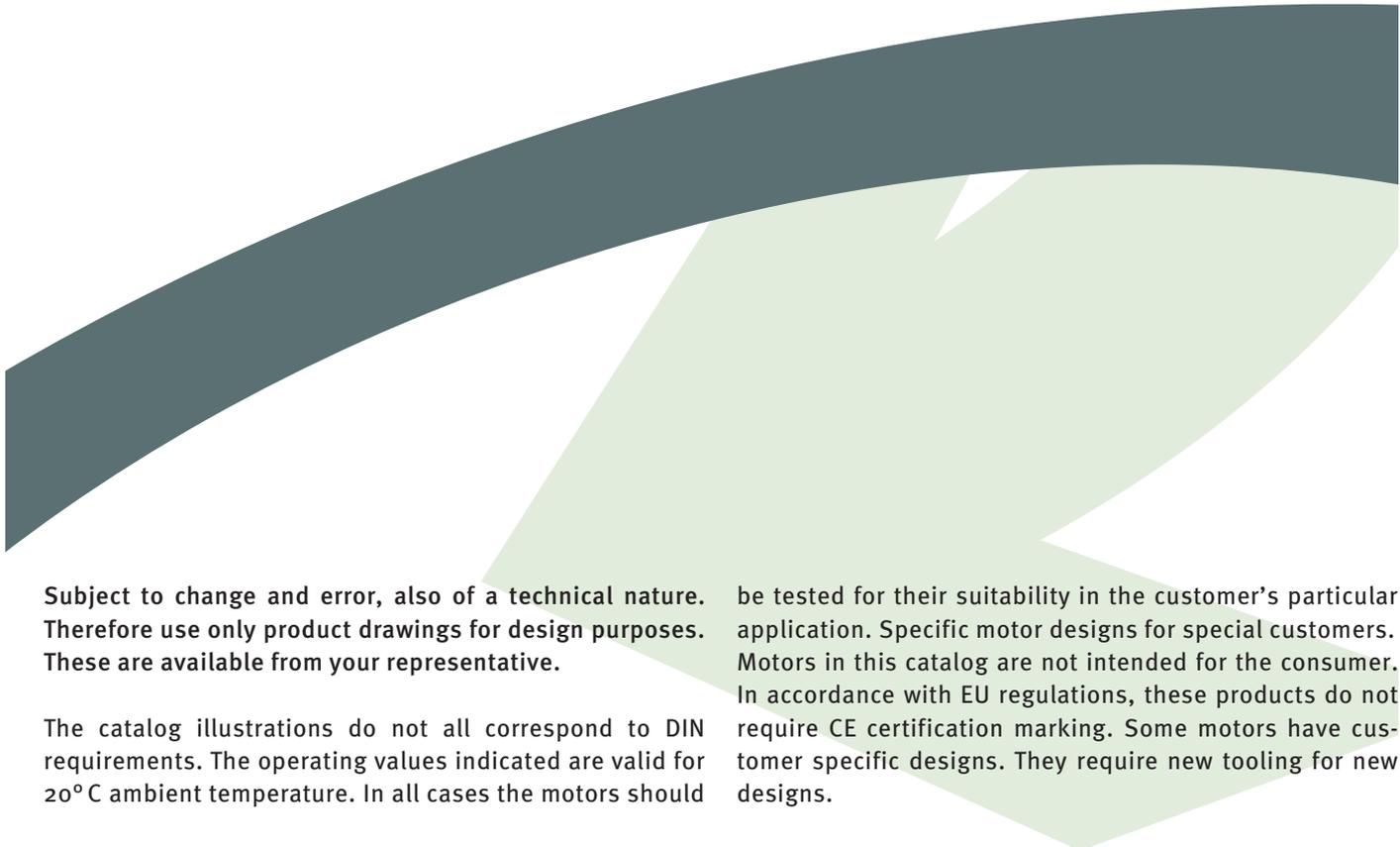


→ Powerful medium & high torque worm gear motors

- Nominal torque ..... 3 – 20 Nm
- No load speed ..... 27 – 220 min<sup>-1</sup>



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Subject to change and error, also of a technical nature. Therefore use only product drawings for design purposes. These are available from your representative.

The catalog illustrations do not all correspond to DIN requirements. The operating values indicated are valid for 20° C ambient temperature. In all cases the motors should

be tested for their suitability in the customer's particular application. Specific motor designs for special customers. Motors in this catalog are not intended for the consumer. In accordance with EU regulations, these products do not require CE certification marking. Some motors have customer specific designs. They require new tooling for new designs.

..... **TERMS, SYMBOLS AND UNITS ACCORDING TO DIN**

Symbol	Unit	Term
$U_N$	[V]	Rated voltage
$n_o$	[min <sup>-1</sup> ]	No-load speed ± 10%
$M_N$	[Nm]	Nominal torque at the output shaft
$M_A$	[Nm]	Starting torque
$i$		Gear ratio
$J_R$	[kgm <sup>2</sup> ] x 10 <sup>-6</sup>	Armature load inertia
$R$	[mΩ]	Armature resistance, 2/4 commutator bars
$L$	[mH]	Armature inductance, 2/4 commutator bars

Drawing	dimensional drawing
Shaft	dimensions of shaft ends
Wiring diagram	motor wiring diagram
Connection	dimensions and positions of motor connections
Materials	BRZ = bronze, KST = plastic, ST = steel, HGW = resinbonded fabric

 **Direction of rotation when looking onto motor shaft**      The curves show the speed and the current as a function of the torque. These are average values at room temperature. Divergences of ± 10 % are possible in the series.

 **Preferred direction of rotation:** Worm gear motors have a preferred direction of rotation, indicated in the drawings by a larger arrow. If the motor rotates against the preferred rotation direction, power decreases by approx. 10 %.



❖❖❖ **CONVERSION OF TORQUE VALUES**

(VALUES ROUNDED FOR PRACTICAL USE)

	Nm	Ncm	pcm	kpcm	kpm	oz in	in lbs	ft lbs
Nm	1	100	10.2 x 10 <sup>3</sup>	10.2	0.102	141.6	8.85	0.738
Ncm	10 <sup>-2</sup>	1	102	1.02 x 10 <sup>-2</sup>	1.02 x 10 <sup>-3</sup>	1.42	8.85 x 10 <sup>-2</sup>	7.38 x 10 <sup>-3</sup>
pcm	9.8 x 10 <sup>-5</sup>	9.8 x 10 <sup>-3</sup>	1	10 <sup>-3</sup>	10 <sup>-5</sup>	1.39 x 10 <sup>-2</sup>	8.68 x 10 <sup>-4</sup>	7.23 x 10 <sup>-5</sup>
kpcm	9.8 x 10 <sup>-2</sup>	9.8	1000	1	10 <sup>-2</sup>	13.9	0.868	7.23 x 10 <sup>-2</sup>
kpm	9.8	980	10 <sup>5</sup>	100	1	1390	86.8	7.23
oz in	7.06 x 10 <sup>-3</sup>	0.706	72	7.2 x 10 <sup>-2</sup>	7.2 x 10 <sup>-4</sup>	1	6.25 x 10 <sup>-2</sup>	5.2 x 10 <sup>-3</sup>
in lbs	0.113	11.3	1152	1.15	1.15 x 10 <sup>-2</sup>	16	1	8.3 x 10 <sup>-2</sup>
ft lbs	1.36	135.58	13,825	13.8	0.138	192	12	1

❖❖❖ **CONVERSION OF FORCES**

(VALUES ROUNDED FOR PRACTICAL USE)

	N	kp	p	oz	lbf
N	1	0.102	102	3.6	0.225
kp	9.8	1	1000	35.27	2.2
p	9.8 x 10 <sup>-3</sup>	10 <sup>-3</sup>	1	3.53 x 10 <sup>-2</sup>	2.2 x 10 <sup>-3</sup>
oz	0.278	2.83 x 10 <sup>-2</sup>	28.35	1	6.25 x 10 <sup>-2</sup>
lbf	4.45	0.445	453.6	16	1

❖❖❖ **CONVERSION OF POWER**

(VALUES ROUNDED FOR PRACTICAL USE)

	kW	PS	HP	kpm/s	kcal/s
kW	1	1.36	1.34	102	0.239
PS	0.735	1	0.986	75	0.176
HP	0.746	1.01	1	76	0.178
kpm/s	9.8 x 10 <sup>-3</sup>	1.33 x 10 <sup>-2</sup>	1.32 x 10 <sup>-2</sup>	1	2.34 x 10 <sup>-2</sup>
kcal/s	4.2	5.7	5.6	427	1

❖❖❖ **CONVERSION OF TEMPERATURES**

$t_c$ [°C] Celsius	$t_f$ [°F] Fahrenheit	$T_k$ [K] Kelvin	$T_r$ [°R] Rankine
$t_c = \frac{5}{9} (t_f - 32)$	$t_f = \frac{9}{5} t_c + 32$	$T_k = t_c + 273$	$T_r = \frac{9}{5} (t_c + 273)$
$t_c = \frac{5}{9} T_r - 273$		$T_k = \frac{5}{9} T_r$	
		$T_k = \frac{5}{9} (t_f + 255)$	

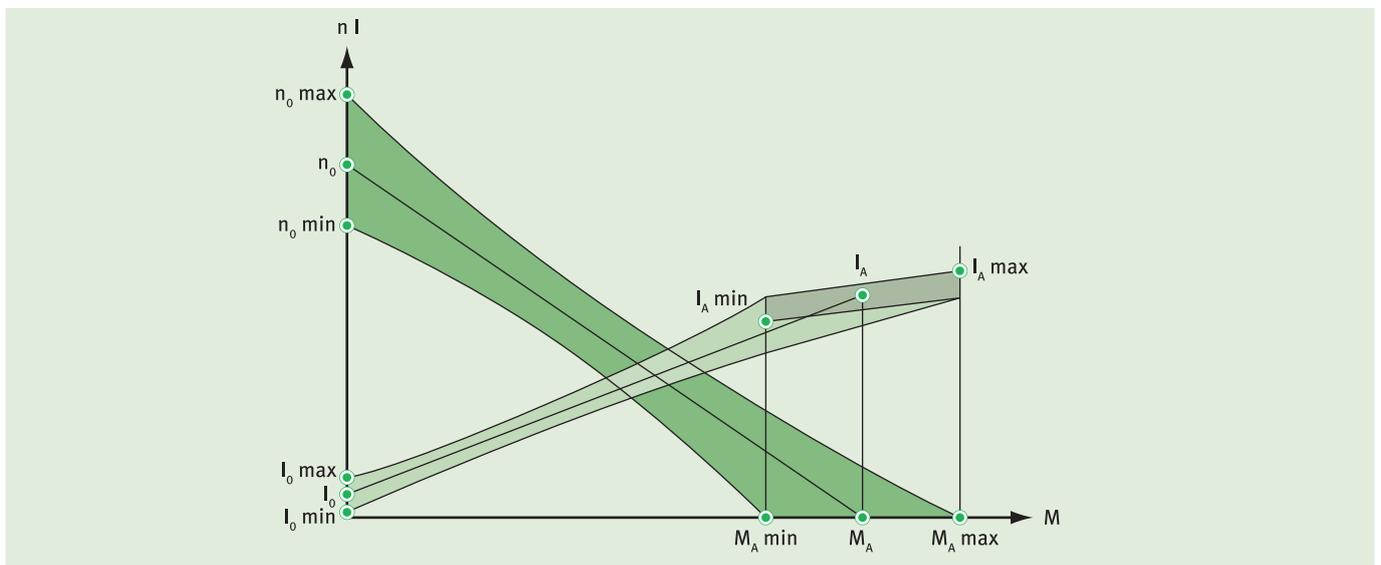


❖❖❖ **TOLERANCE ZONES TO ISO/R 286**

(DIN 7150, 7151, 7152, 7154, 7155)

1,1 H 13:	+0.140 / 0 mm	5,1 H 11:	+0.075 / 0 mm	9 k 5:	+0.007 / +0.001mm
1,6 H 13:	+0.140 / 0 mm	5,1 H 12:	+0.120 / 0 mm	9,4 h 11:	0 / -0.090 mm
2,5 H 12:	+0.100 / 0 mm	5,5 h 11:	0 / -0.075 mm	9,5 js 11:	+0.045 / -0.045 mm
2,7 H 12:	+0.100 / 0 mm	5,5 H 13:	+0.180 / 0 mm	9,6 h 11:	0 / -0.090 mm
3 H 9:	+0.025 / 0 mm	5,8 g 6:	-0.004 / -0.012 mm	9,75 g 5:	-0.006 / -0.014 mm
3 H 12:	+0.100 / 0 mm	5,9 c 9:	-0.070 / -0.100 mm	10 f 6:	-0.013 / -0.022 mm
3 N 9:	-0.004 / -0.029 mm	5,9 h 10:	0 / -0.048 mm	10 f 7:	-0.013 / -0.028 mm
3 P 8:	-0.006 / -0.020 mm	6 f 9:	-0.010 / -0.040 mm	10 f 8:	-0.013 / -0.035 mm
3 P 9:	-0.006 / -0.031 mm	6 fg 9:	-0.006 / -0.014 mm	10 g 5:	-0.005 / -0.011 mm
3 P 10:	-0.006 / -0.046 mm	6 h 6:	0 / -0.008 mm	10 g 6:	-0.005 / -0.014 mm
3,1 JS 10:	+0.024 / -0.024 mm	6 h 8:	0 / -0.018 mm	10 h 5:	0 / -0.006 mm
3,5 H 12:	+0.120 / 0 mm	6 h 9:	0 / -0.030 mm	10 h 7:	0 / -0.015 mm
3,6 H 11:	+0.075 / 0 mm	6 m 6:	+0.012 / +0.004 mm	10 h 9:	0 / -0.036 mm
4 C 10:	+0.118 / -0.070 mm	6,3 H 12:	+0.150 / 0 mm	11 d 10:	-0.050 / -0.120 mm
4 h 6:	0 / -0.008 mm	6,5 H 8:	+0.022 / 0 mm	11,2 e 10:	-0.032 / -0.102 mm
4 h 8:	0 / -0.018 mm	6,8 h 8:	0 / -0.022 mm	11,5 h 11:	0 / -0.110 mm
4 h 9:	0 / -0.030 mm	7 h 8:	0 / -0.022 mm	12 f 7:	-0.016 / -0.034 mm
4 h 10:	0 / -0.048 mm	7,6 h 11:	0 / -0.090 mm	12 g 5:	-0.006 / -0.014 mm
4 h 11:	0 / -0.075 mm	8 f 6:	-0.013 / -0.022 mm	12 h 6:	0 / -0.011 mm
4 H 12:	+0.120 / 0 mm	8 g 6:	-0.005 / -0.014 mm	12 h 7:	0 / -0.018 mm
4 P 9:	-0.012 / -0.042 mm	8 g 7:	-0.005 / -0.020 mm	12 h 9:	0 / -0.036 mm
4,1 h 10:	0 / -0.048 mm	8 g 9:	-0.005 / -0.041 mm	12 h 11:	0 / -0.110 mm
4,1 H 11:	+0.075 / 0 mm	8 h 9:	0 / -0.036 mm	13,4 h 11:	0 / -0.110 mm
4,2 H 7:	+0.012 / 0 mm	8 H 9:	+0.036 / 0 mm	14 f 6:	-0.016 / -0.027 mm
4,2 H 12:	+0.120 / 0 mm	8 h 10:	0 / -0.058 mm	14 f 7:	-0.016 / -0.034 mm
4,5 H 13:	+0.180 / 0 mm	8 h 11:	0 / -0.090 mm	14 H 7:	+0.018 / 0 mm
5 c 11:	-0.070 / -0.145 mm	8 k 5:	+0.007 / +0.001 mm	15 f 7:	-0.016 / -0.034 mm
5 h 6:	0 / -0.008 mm	8,5 h 9:	0 / -0.036 mm	15,2 h 11:	0 / -0.110 mm
5 h 9:	0 / -0.030 mm	8,7 h 11:	0 / -0.090 mm	16 f 6:	-0.016 / -0.027 mm
5 h 10:	0 / -0.048 mm	9 D 9:	+0.076 / +0.040 mm	18 H 8:	+0.027 / 0 mm
5 h 12:	0 / -0.120 mm	9 h 6:	0 / -0.009 mm	20 h 9:	0 / -0.052 mm
5 P 9:	-0.012 / -0.042 mm	9 h 11:	0 / -0.090 mm	26 g 6:	-0.007 / -0.020 mm

❖❖❖ **TOLERANCE ZONES**



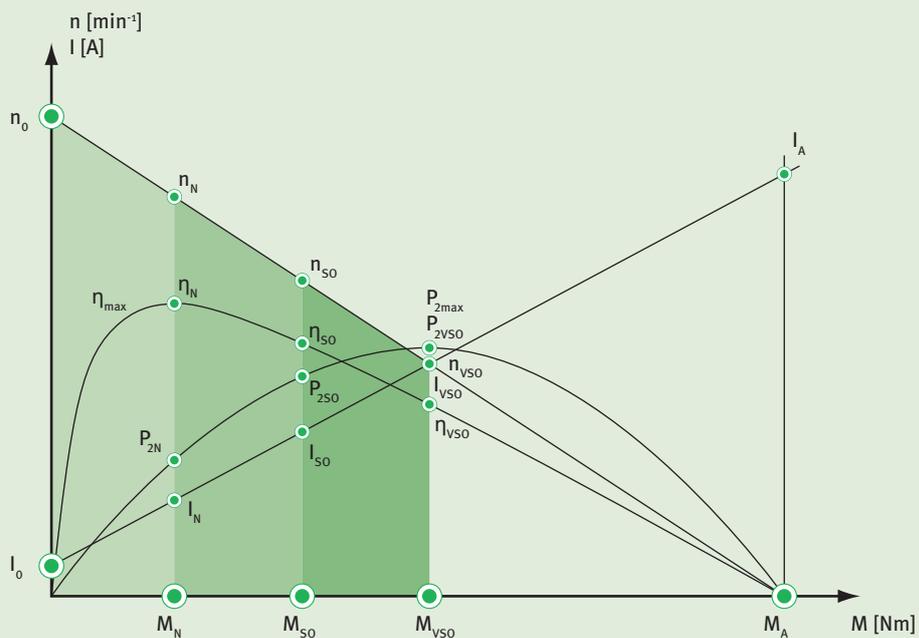


**CHARACTERISTIC CURVES**

CR	Continuous running	$n_0$	No-load speed in $\text{min}^{-1}$
SO	Short operation	$n_N$	Rated speed in $\text{min}^{-1}$
VSO	Very short operation	$n_{SO}$	Speed for short operation in $\text{min}^{-1}$
P	Power in W	$n_{VSO}$	Speed for very short operation in $\text{min}^{-1}$
$P_{2N}$	Nominal output power in W	I	Current in A
$P_{2max}$	Maximum output power in W	$I_0$	No-load current in A
$P_{2SO}$	Output power for short operation in W	$I_A$	Starting current in A
$P_{2VSO}$	Output power for very short operation in W	$I_N$	Rated current in A
M	Torque in Nm	$I_{SO}$	Current for short operation in A
$M_A$	Starting torque in Nm	$I_{VSO}$	Current for very short operation in A
$M_N$	Nominal output torque in Nm	$\eta$	Efficiency in %
$M_{SO}$	Output torque for short operation in Nm	$\eta_N$	Rated efficiency in %
$M_{VSO}$	Output torque for very short operation in Nm	$\eta_{SO}$	Efficiency for short operation in %
n	Rotational speed in $\text{min}^{-1}$	$\eta_{VSO}$	Efficiency for very short operation in %

**RANGE OF OPERATION**

- Continuous running
- Short operation
- Very short operation

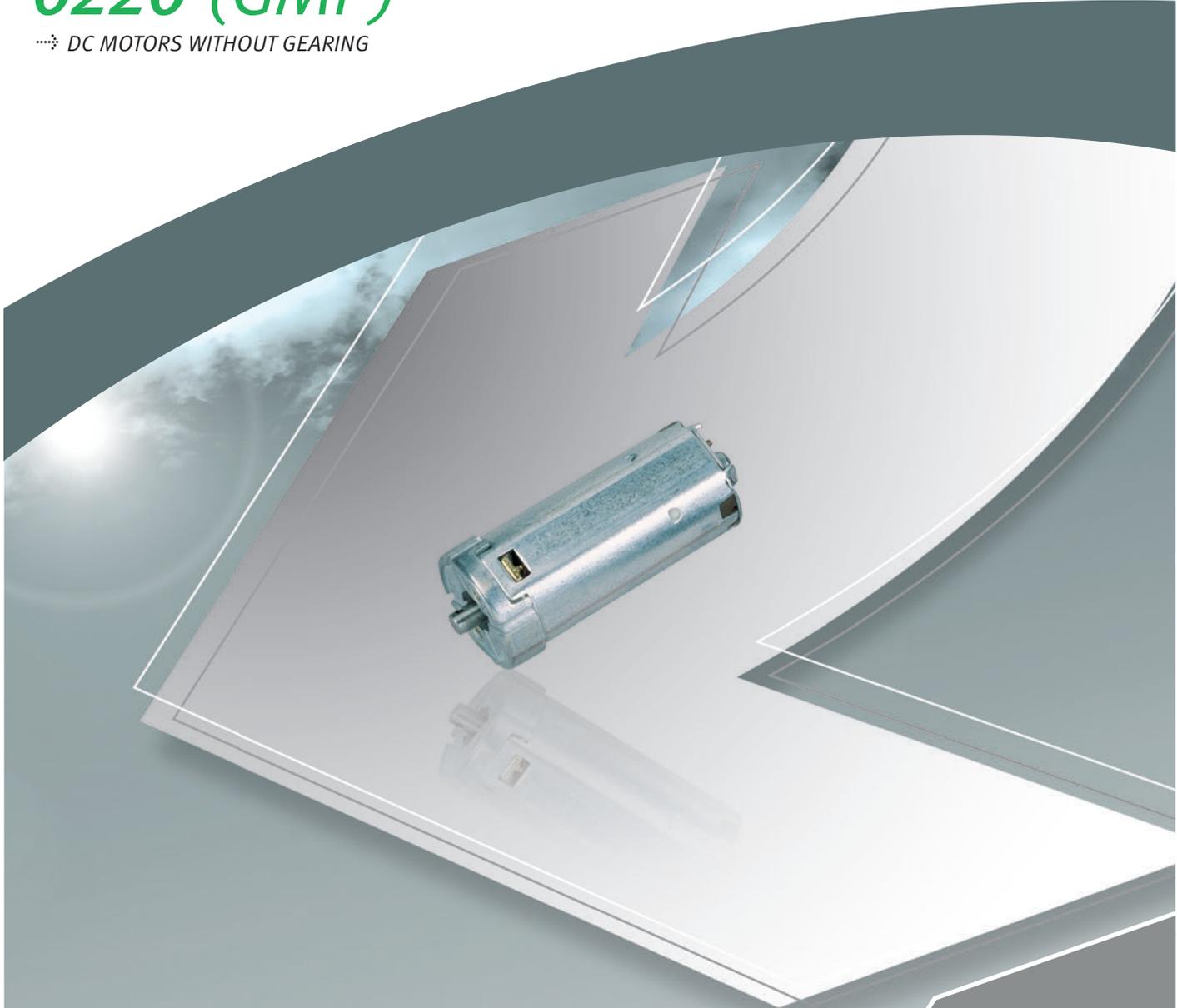




NIDEC MOTORS & ACTUATORS ❖❖❖ MOTOR SERIES

# 0220 (GMP)

❖❖❖ DC MOTORS WITHOUT GEARING



## ❖❖❖ TECHNICAL DESCRIPTION

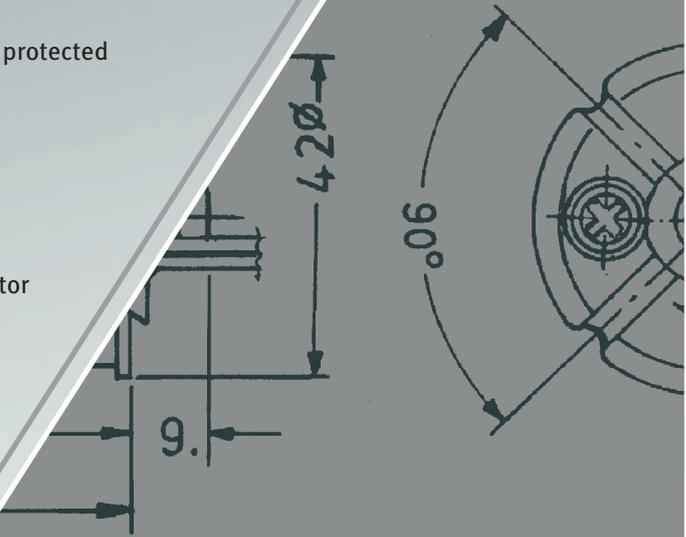
Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	-
Gear housing:	-
Gear wheel material:	-
Lubrication:	-
Mechanical interface:	steel shaft
Electric interface:	connector or leads with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

## ❖❖❖ INDUSTRIAL APPLICATION

Linear drives, machine construction

## ❖❖❖ AUTOMOTIVE APPLICATION

Seat track drive



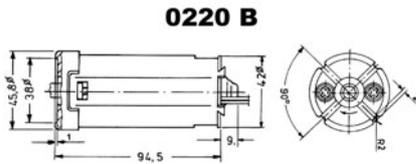
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	0.08
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	2,700.0
Nominal power [W]	$P_N$	16.2
Nominal current [A]	$I_N$	2.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	
Gear wheel material	
Suppression components	7,5 $\mu$ H
Enclosure class	IP 30
Weight [kg]	0.550

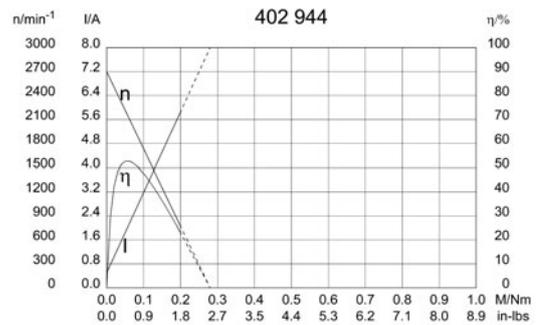
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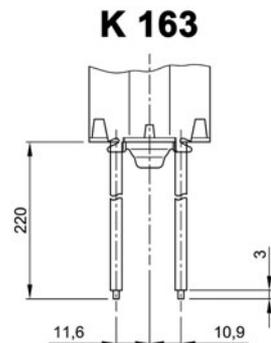
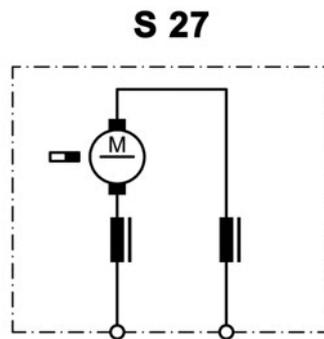
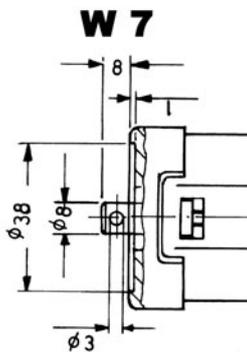
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



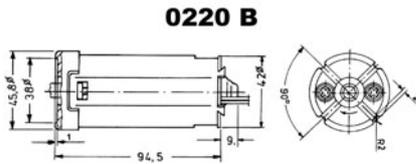
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Ball

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	0.08
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	2,800.0
Nominal power [W]	$P_N$	17.6
Nominal current [A]	$I_N$	1.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	
Gear wheel material	
Suppression components	7.5 $\mu$ H, 47nF
Enclosure class	IP 30
Weight [kg]	0.550

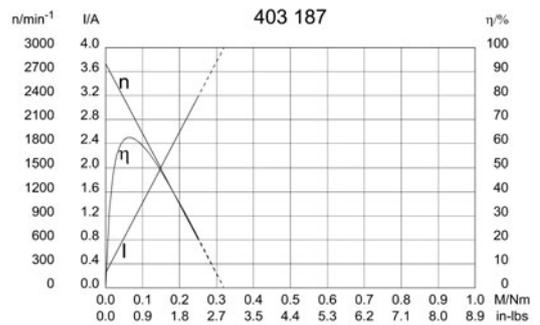
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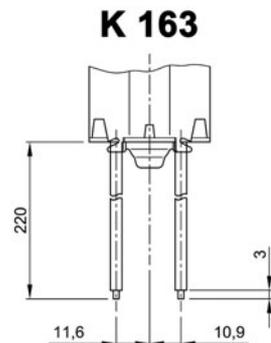
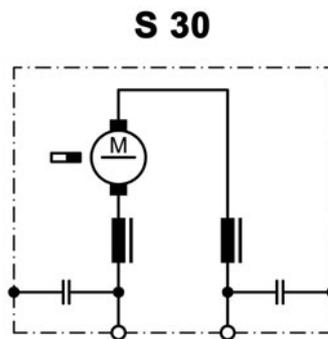
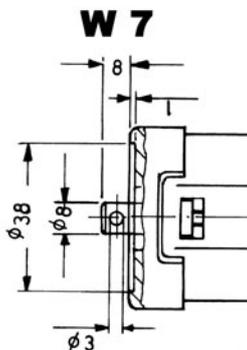
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

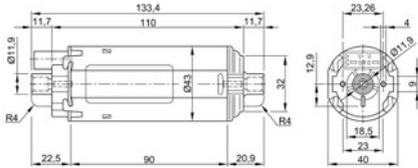






Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

**0220 F**



Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	0.10
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	2,700.0
Nominal power [W]	$P_N$	21.2
Nominal current [A]	$I_N$	3.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

Sensor data	
Pulses	0
Output channels	0

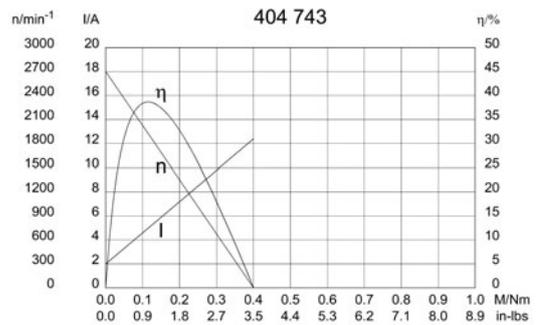
Other data	
Gear ratio	
Gear wheel material	
Suppression components	2,5 $\mu$ H, 47nF ( )
Enclosure class	IP 40
Weight [kg]	0.560

Remarks:

**Motor picture**

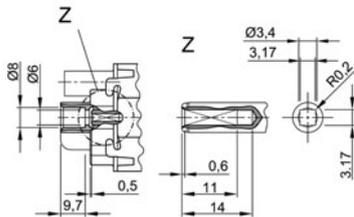


**Characteristic curves**

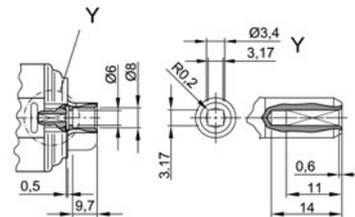


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

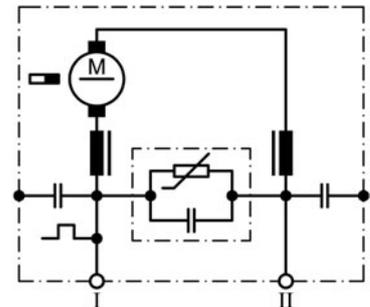
**W 266**



**W 267**



**S 93**

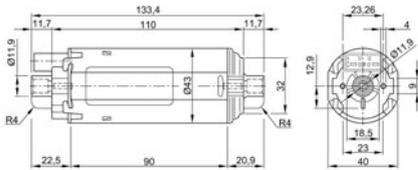


I Terminal 1  
 II Terminal 5



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

**0220 F**



Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	0.10
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	2,700.0
Nominal power [W]	$P_N$	21.2
Nominal current [A]	$I_N$	4.5
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

Sensor data	
Pulses	1
Output channels	1

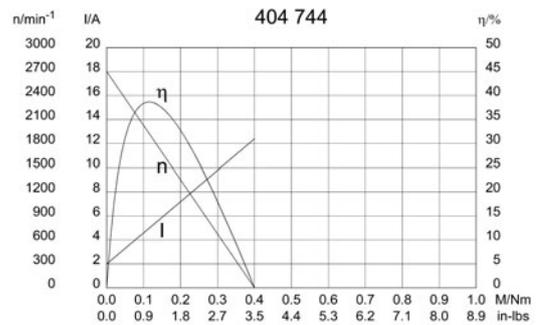
Other data	
Gear ratio	
Gear wheel material	
Suppression components	2,5 $\mu$ H, 47nF
Enclosure class	IP 40
Weight [kg]	0.560

Remarks:

**Motor picture**

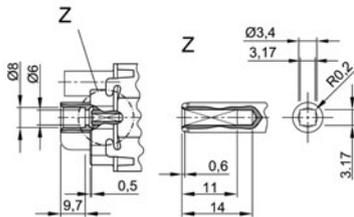


**Characteristic curves**

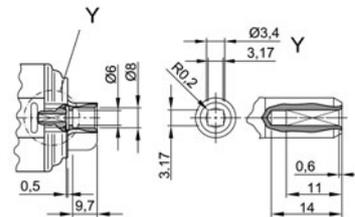


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

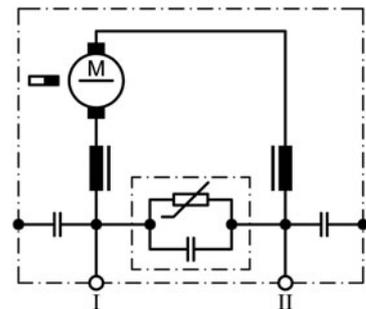
**W 266**



**W 267**



**S 86**



I Terminal 1  
 II Terminal 5

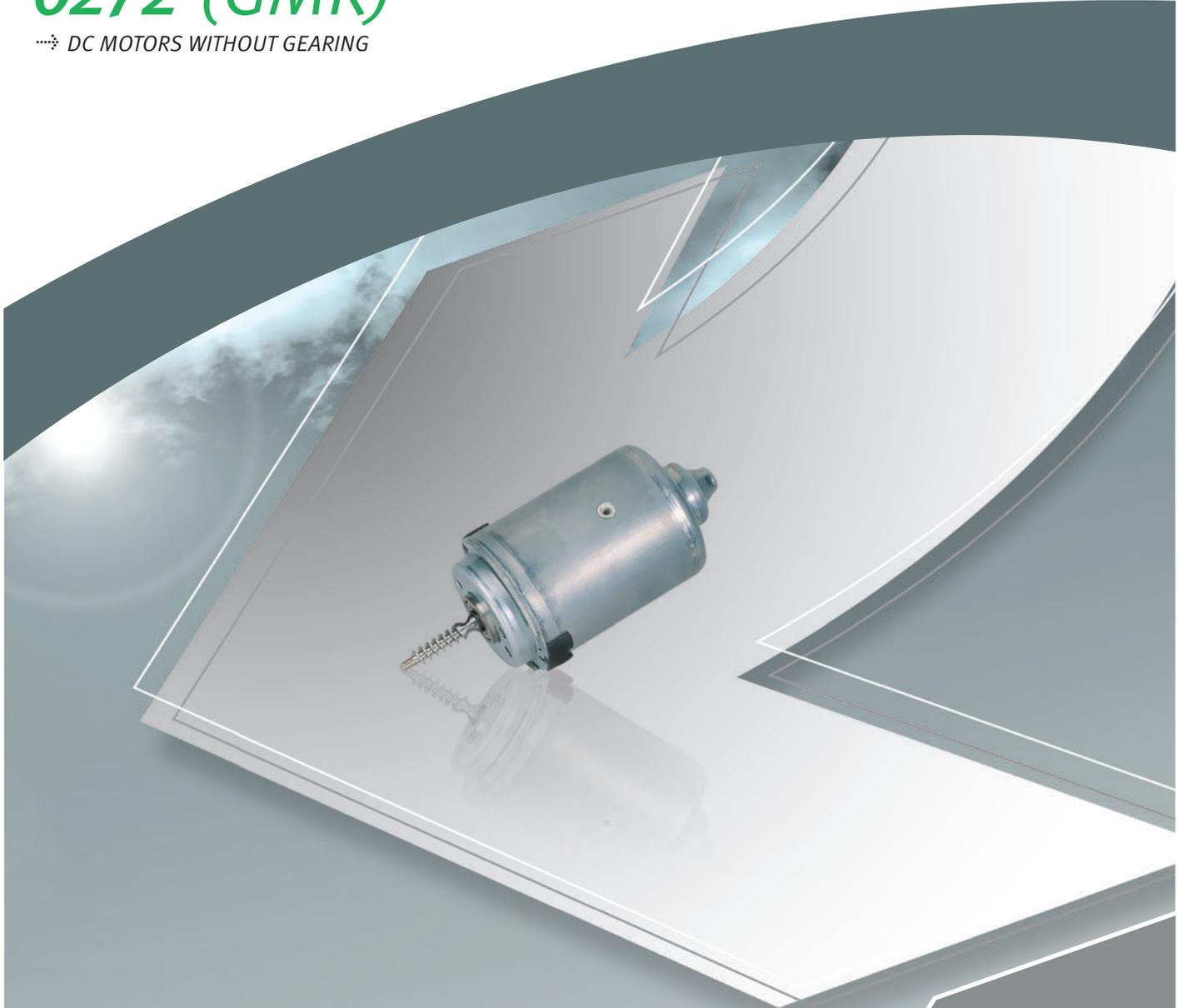






# 0272 (GMK)

❖❖❖ DC MOTORS WITHOUT GEARING



## ❖❖❖ TECHNICAL DESCRIPTION

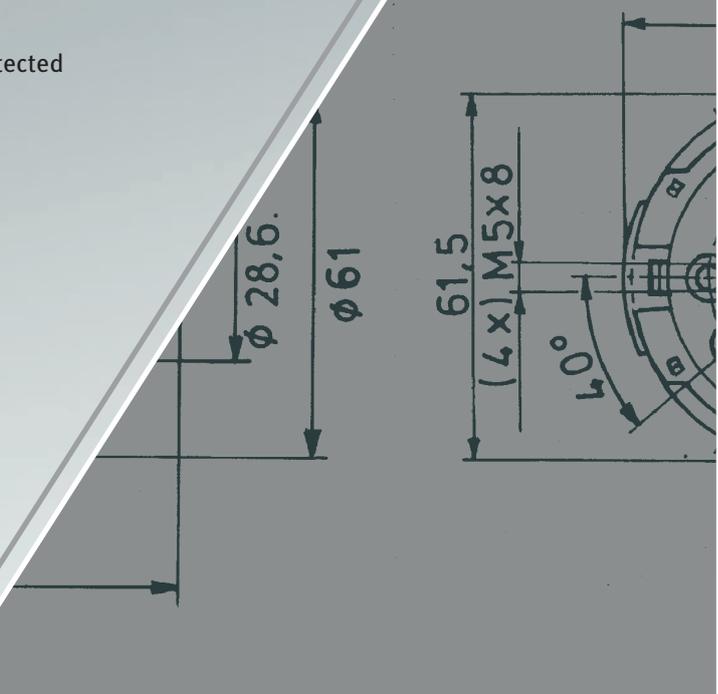
Motorhousing:	deep drawn & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	-
Gear housing:	-
Gear wheel material:	-
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	leads with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

## ❖❖❖ INDUSTRIAL APPLICATION

Linear drives

## ❖❖❖ AUTOMOTIVE APPLICATION

Electric torque management,  
Automated manual transmission











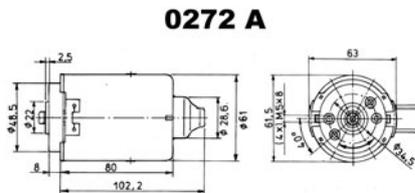
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	0.30
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	2,200.0
Nominal power [W]	$P_N$	53.2
Nominal current [A]	$I_N$	3.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	
Gear wheel material	
Suppression components	5 $\mu$ H, 10nF
Enclosure class	IP 30
Weight [kg]	0.890

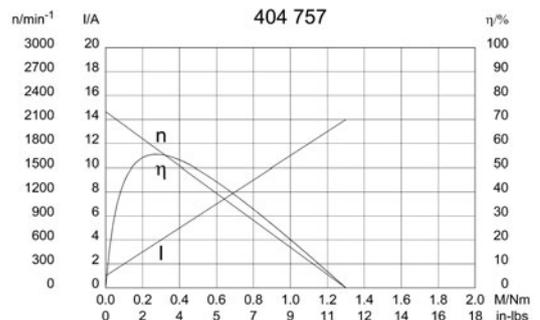
Remarks:



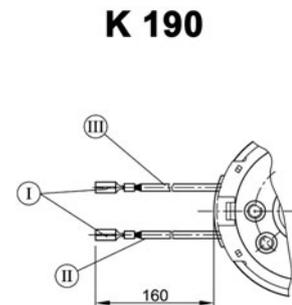
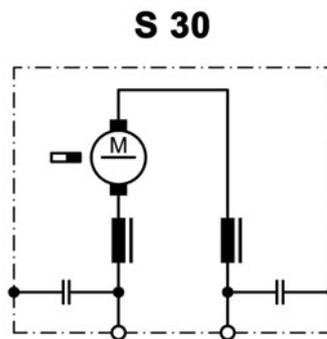
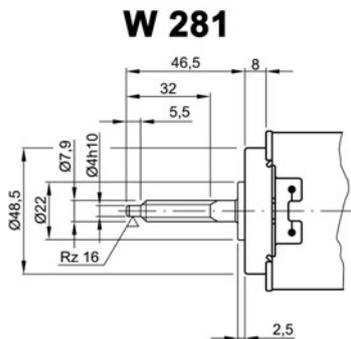
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



no of starts 2 , lead angle 19°48'54" , pressure angle 15° , pitch 3,141 mm (0,124") , module 1

I Receptacles for tabs 2,8 x 0,8 DIN 46 247  
 II black  
 III red

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

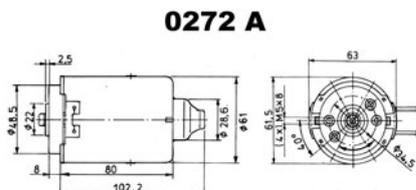
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	0.15
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	2,200.0
Nominal power [W]	$P_N$	30.9
Nominal current [A]	$I_N$	2.5
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

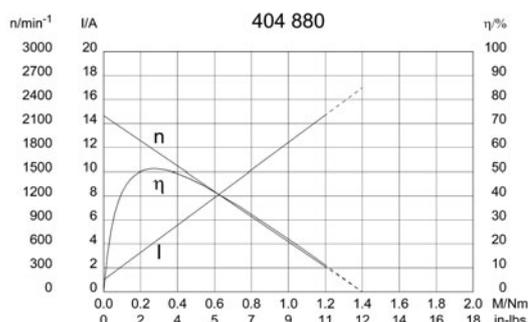
Other data	
Gear ratio	
Gear wheel material	
Suppression components	5 $\mu$ H
Enclosure class	IP 30
Weight [kg]	0.900

Remarks: 3 start worm

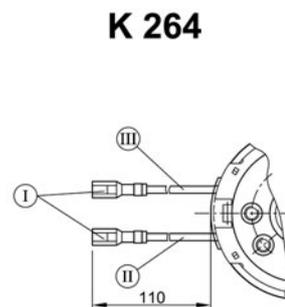
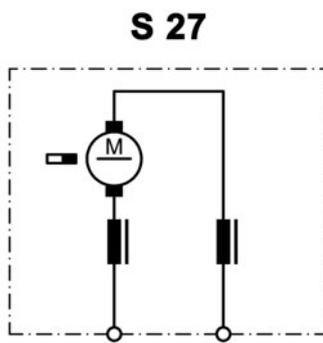
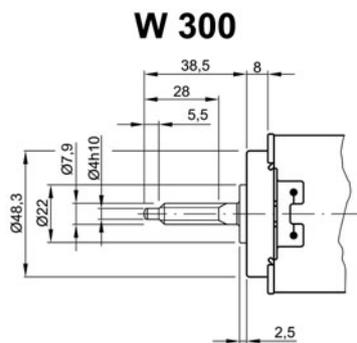
**Characteristic curves**



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



no of starts 3, lead angle 30°33'44", pressure angle 15°, module 1, pitch 3,141 mm (0,124")

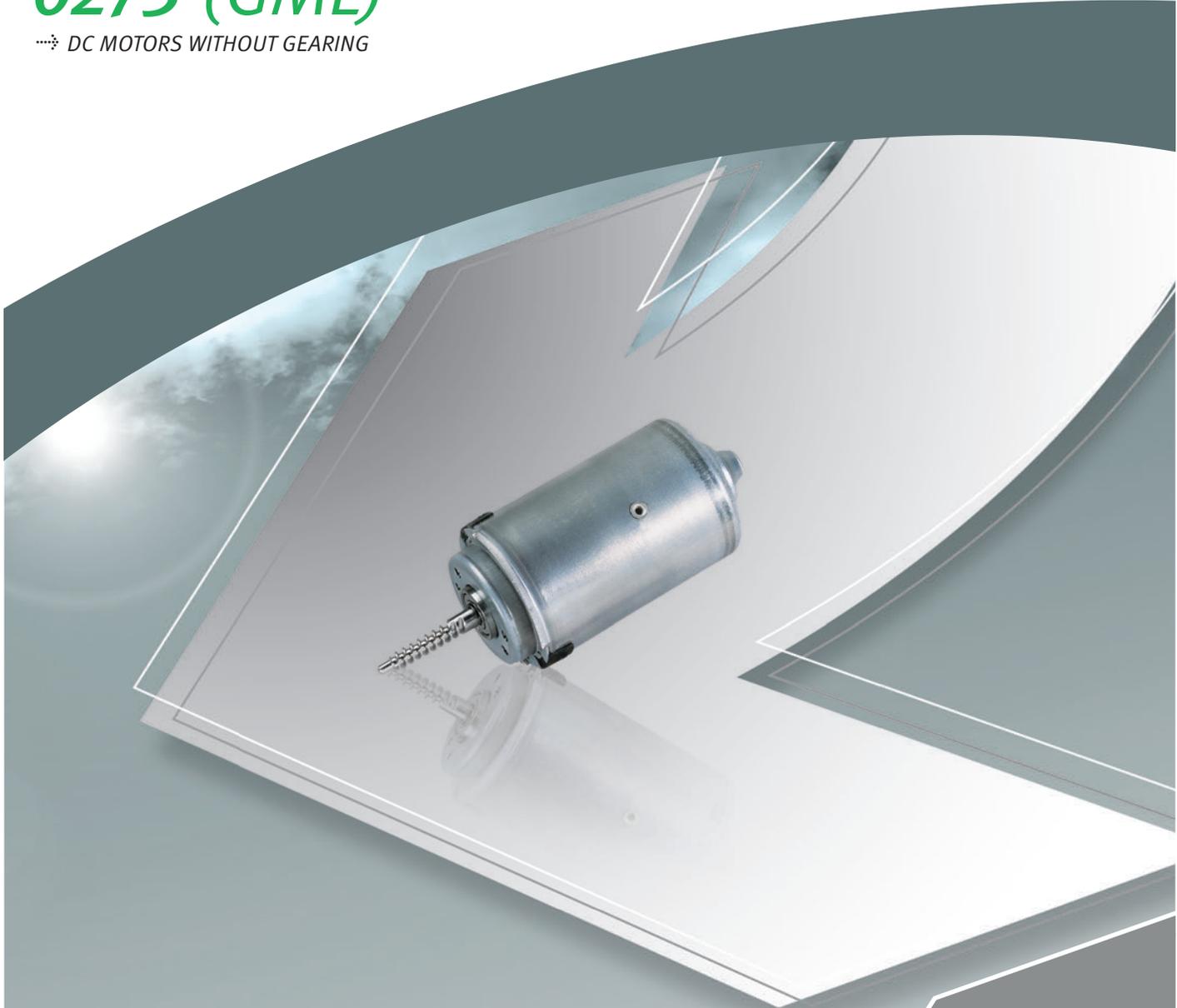
I Receptacle for tabs 2,8 x 0,8 DIN 46 247  
 II green  
 III red





# 0273 (GML)

❖❖❖ DC MOTORS WITHOUT GEARING



## ❖❖❖ TECHNICAL DESCRIPTION

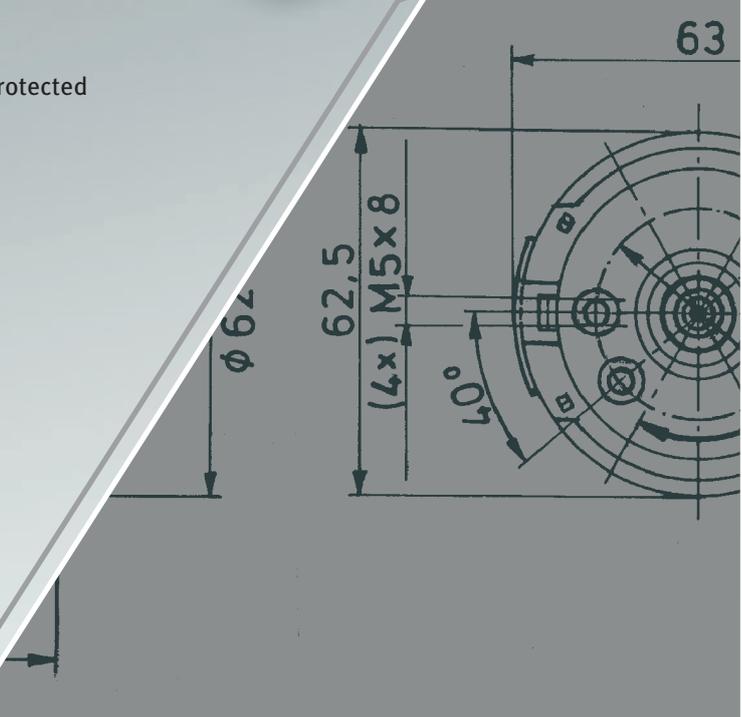
Motorhousing:	deep drawn & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	-
Gear housing:	-
Gear wheel material:	-
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	leads with connector
Sensor:	-
Thermal protection:	optional
EMC suppression:	optional

## ❖❖❖ INDUSTRIAL APPLICATION

Linear drives

## ❖❖❖ AUTOMOTIVE APPLICATION

Electric torque management,  
Automated manual transmission



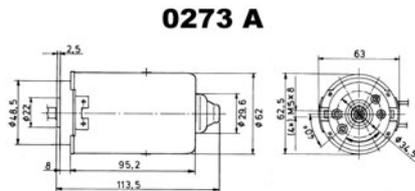
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B-Sleeve

Performance data		
Rated voltage [V]	$U_N$	36
Nominal torque [Nm]	$M_N$	0.20
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	4,100.0
Nominal power [W]	$P_N$	79.7
Nominal current [A]	$I_N$	3.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

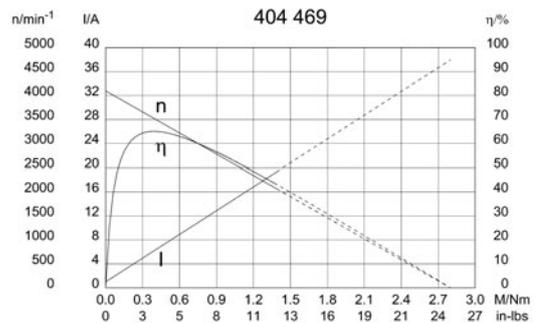
Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	
Gear wheel material	
Suppression components	5 $\mu$ H, 10nF
Enclosure class	IP 30
Weight [kg]	1.150

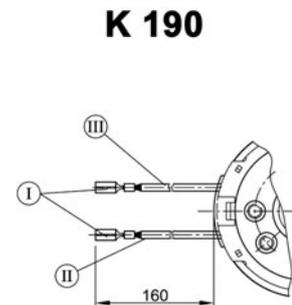
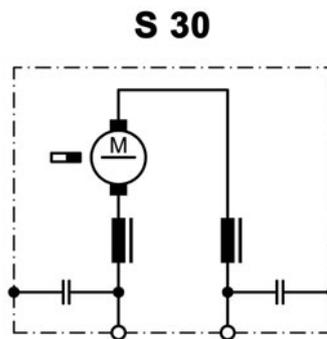
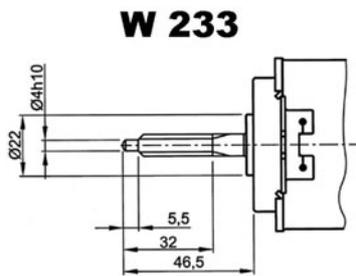
Remarks:



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



no of starts 2, lead angle 19°48'54", pressure angle 15°, module 1, pitch 3,141 mm (0,124")

I Receptacles for tabs 2,8 x 0,8 DIN 46 247  
 II black  
 III red

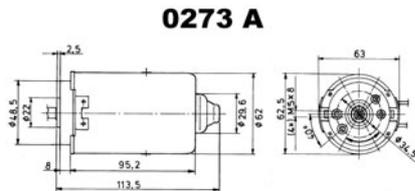
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	0.30
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	4,000.0
Nominal power [W]	$P_N$	107
Nominal current [A]	$I_N$	7.5
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

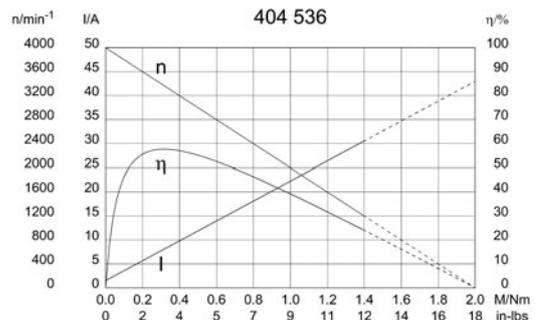
Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	
Gear wheel material	
Suppression components	5 $\mu$ H, 10nF
Enclosure class	IP 30
Weight [kg]	1.150

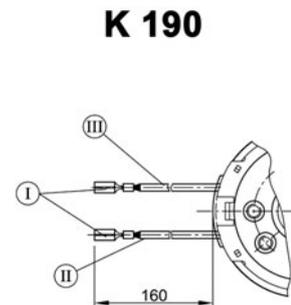
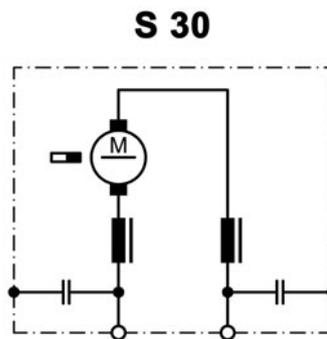
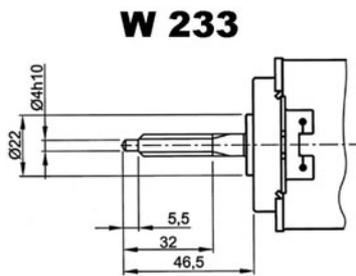
Remarks:



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



no of starts 2, lead angle 19°48'54", pressure angle 15°, module 1, pitch 3,141 mm (0,124")

I Receptacles for tabs 2,8 x 0,8 DIN 46 247  
 II black  
 III red

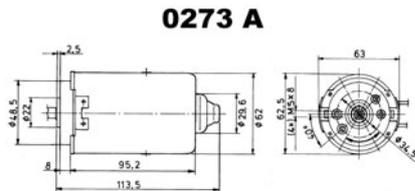
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	0.20
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	3,750.0
Nominal power [W]	$P_N$	67.3
Nominal current [A]	$I_N$	7.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

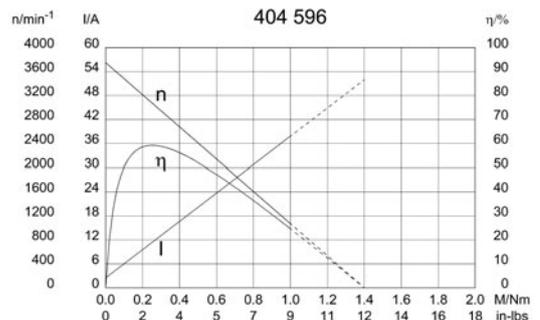
Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	
Gear wheel material	
Suppression components	5 $\mu$ H, 10nF
Enclosure class	IP 30
Weight [kg]	1.150

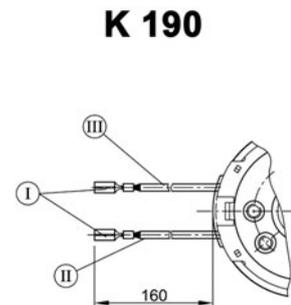
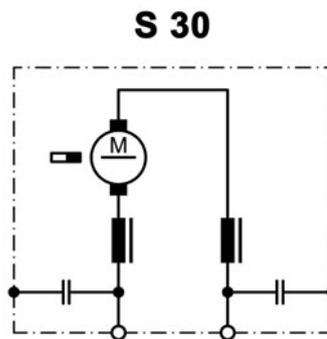
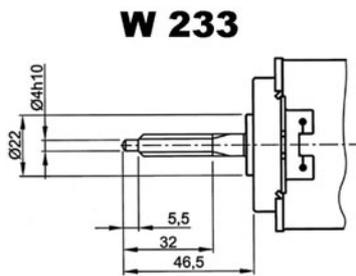
Remarks:



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



no of starts 2, lead angle 19°48'54", pressure angle 15°, module 1, pitch 3,141 mm (0,124")

I Receptacles for tabs 2,8 x 0,8 DIN 46 247  
 II black  
 III red





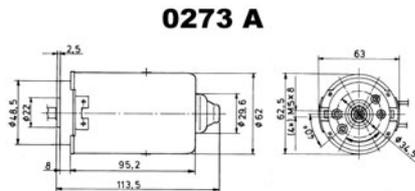
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	0.30
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	3,800.0
Nominal power [W]	$P_N$	105
Nominal current [A]	$I_N$	5.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	
Gear wheel material	
Suppression components	5 $\mu$ H, 10nF
Enclosure class	IP 30
Weight [kg]	1.100

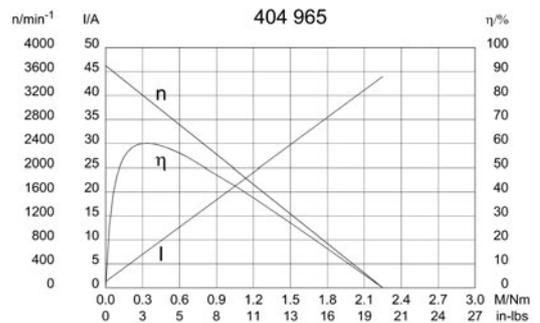
Remarks:



**Motor picture**

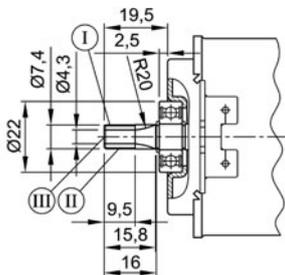


**Characteristic curves**

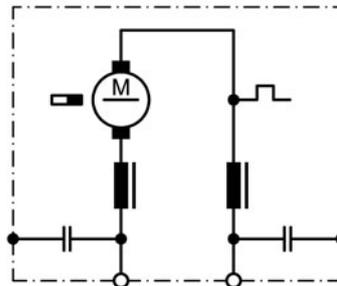


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

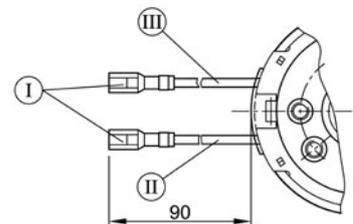
**W 325**



**S 74**



**K 317**



no of starts 7, lead angle 20°, pressure angle 20°, module 0,7, pitch 2,1991 mm (0,087"), induction hardened surface,

- I Receptacle for tabs 6,3 x 0,8  
G&H 35040.213.011
- II red
- III green

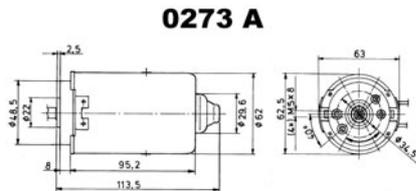
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	0.30
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	3,730.0
Nominal power [W]	$P_N$	99.2
Nominal current [A]	$I_N$	16.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

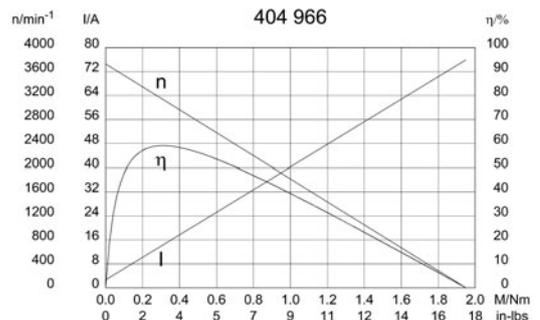
Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	
Gear wheel material	
Suppression components	5 $\mu$ H, 10nF
Enclosure class	IP 30
Weight [kg]	1.100

Remarks:

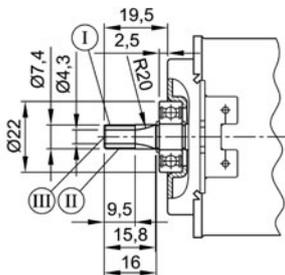


**Motor picture**

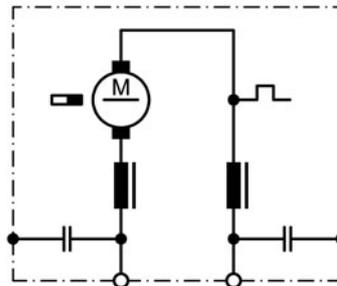


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

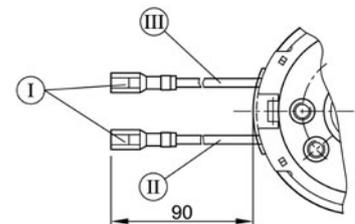
**W 325**



**S 74**



**K 317**



no of starts 7, lead angle 20°, pressure angle 20°, module 0,7, pitch 2,1991 mm (0,087"), induction hardened surface,

- I Receptacle for tabs 6,3 x 0,8  
G&H 35040.213.011
- II red
- III green



**Notes**

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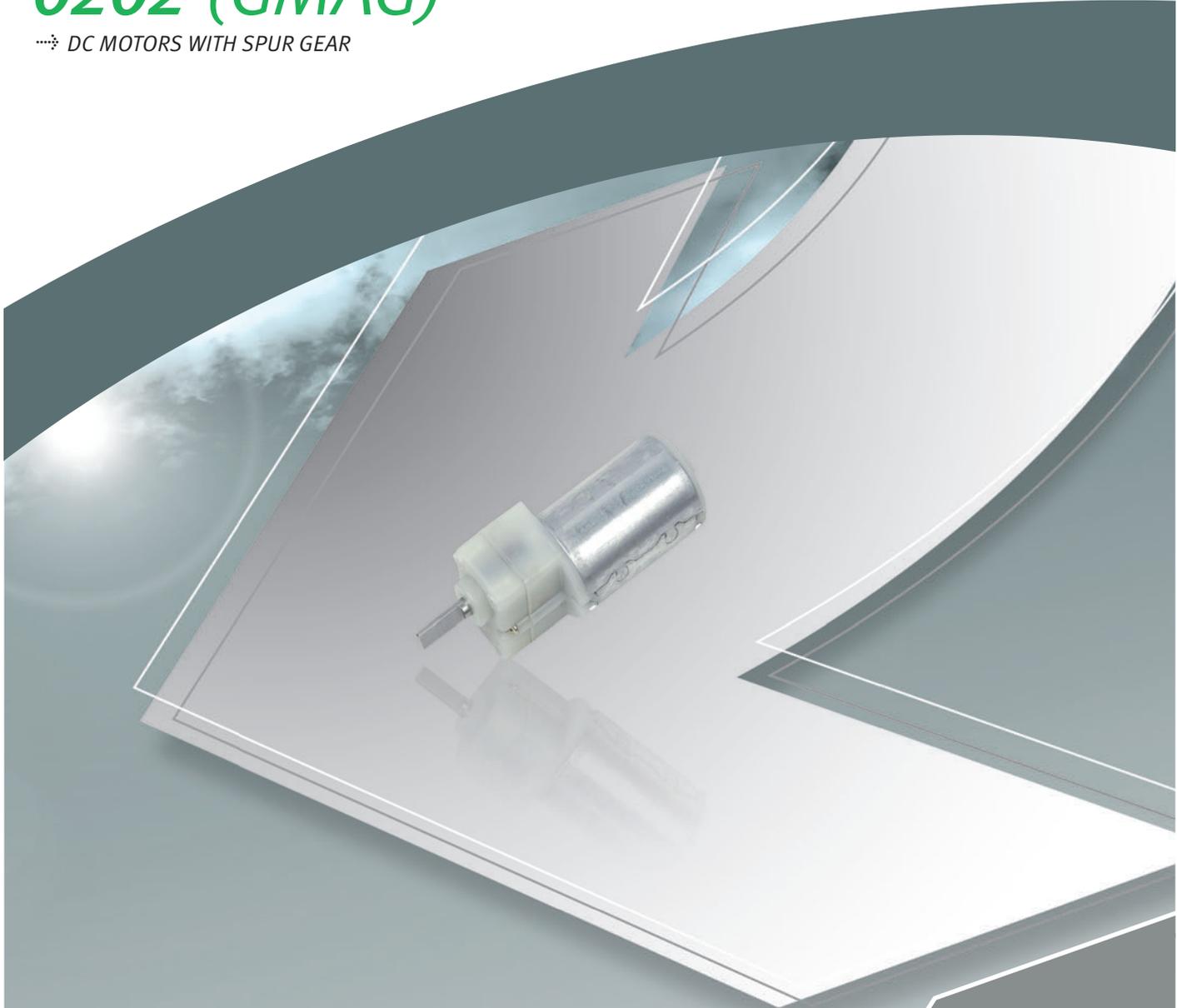
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# 0202 (GMAG)

DC MOTORS WITH SPUR GEAR

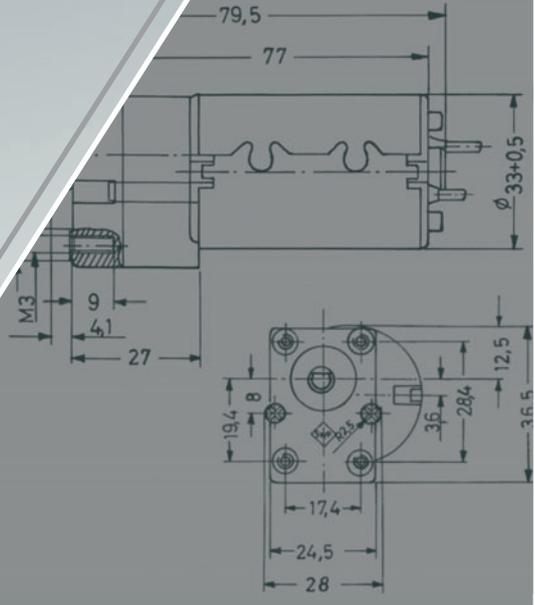


### TECHNICAL DESCRIPTION

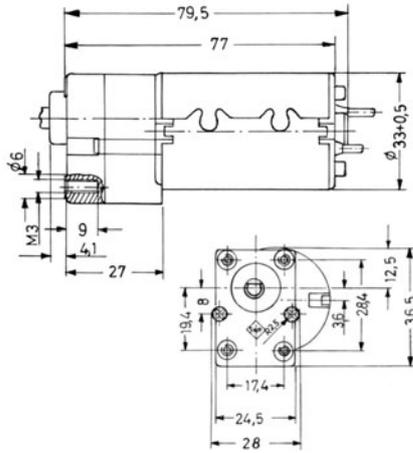
Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	spur gear
Gear housing:	plastic
Gear wheel material:	steel or plastic
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	tinned leads or with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

### APPLICATION

Automatic machines, Constructional engineering  
 Business machines, Laboratory appliances  
 Medical appliances, Traffic & communications  
 technology, Photographic/optical equipment



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	0.24
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	17.0
Nominal power [W]	$P_N$	0.37
Nominal current [A]	$I_N$	0.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

Sensor data	
Pulses	0
Output channels	0

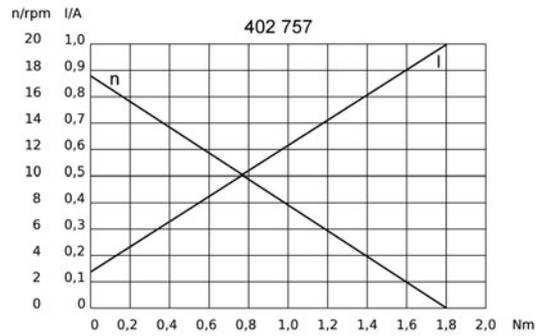
Other data	
Gear ratio	109/1
Gear wheel material	
Suppression components	
Enclosure class	IP40
Weight [kg]	0.180

Remarks:

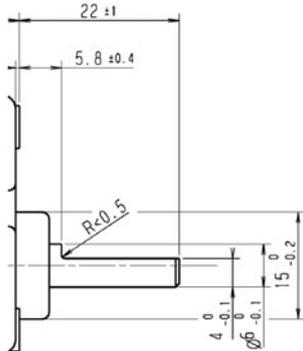
**Motor picture**



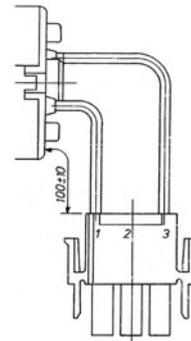
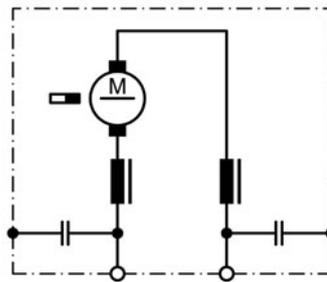
**Characteristic curves**



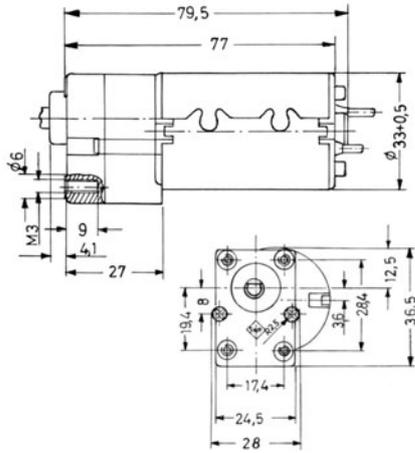
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 30**



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	0.50
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	55.0
Nominal power [W]	$P_N$	2.56
Nominal current [A]	$I_N$	0.5
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

Sensor data	
Pulses	0
Output channels	0

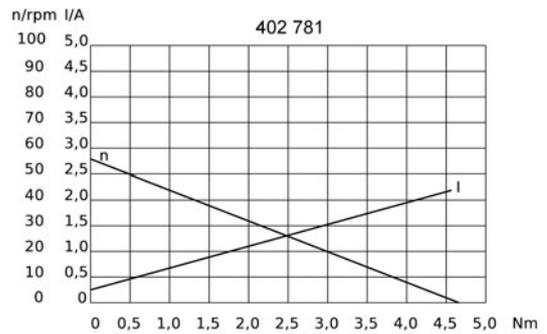
Other data	
Gear ratio	109/1
Gear wheel material	
Suppression components	
Enclosure class	IP40
Weight [kg]	0.180

Remarks:

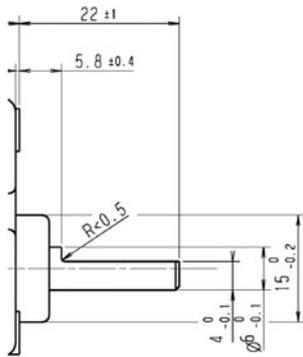
**Motor picture**



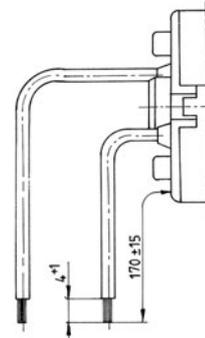
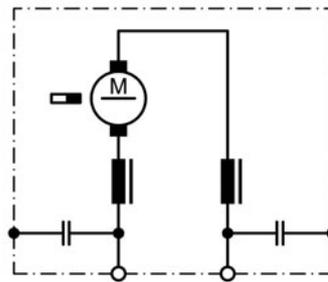
**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 30**



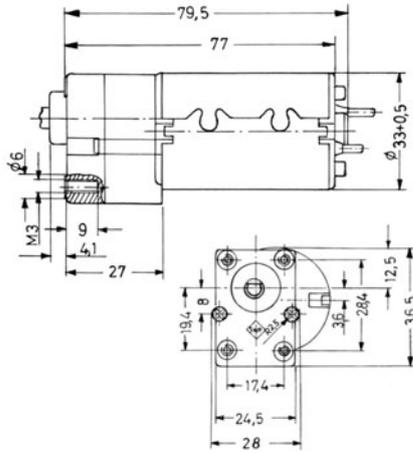
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	0.04
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	300.0
Nominal power [W]	$P_N$	1.07
Nominal current [A]	$I_N$	0.2
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	9.7/1
Gear wheel material	
Suppression components	
Enclosure class	IP40
Weight [kg]	0.180

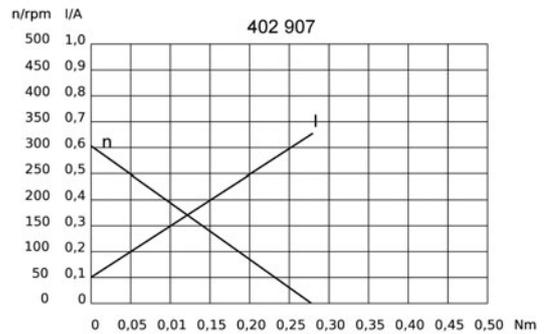
Remarks:



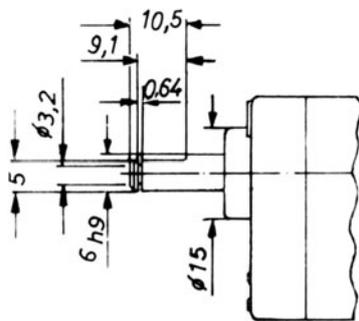
**Motor picture**



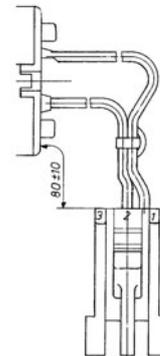
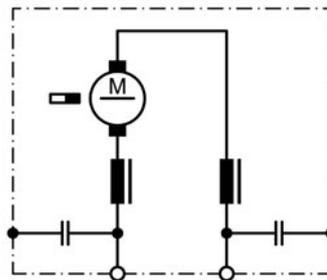
**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



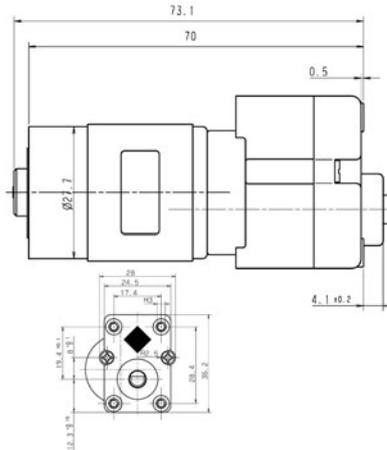
**S 30**



Connector Burndy  
 Pins: SWM 1EF TV2  
 Housing: SMS 2p-1

**Design Data**

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



**Motor picture**



**Performance data**

Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	0.20
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	135.0
Nominal power [W]	$P_N$	2.26
Nominal current [A]	$I_N$	0.3
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

**Sensor data**

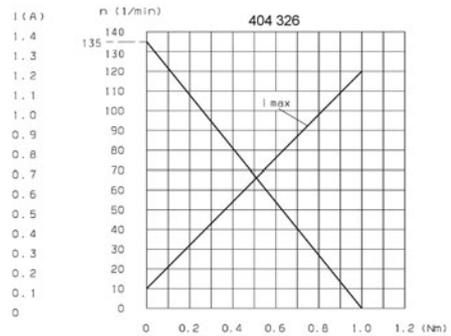
Pulses	0
Output channels	0

**Other data**

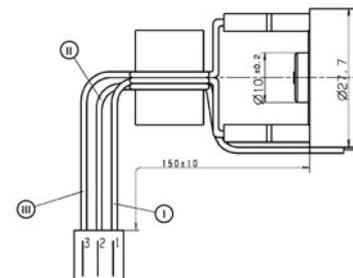
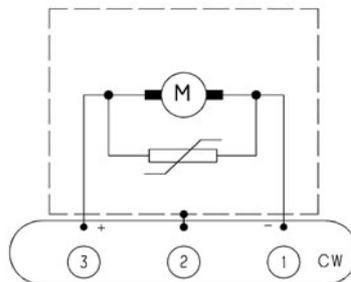
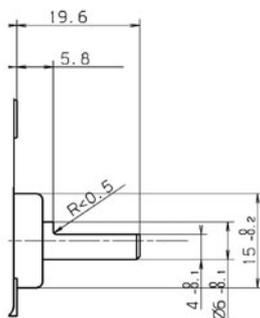
Gear ratio	43/1
Gear wheel material	
Suppression components	
Enclosure class	IP40
Weight [kg]	0.180

Remarks:

**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**Housing:** AMP-Nr.: 1-480 700-0  
**Pins:** AMP-Nr.: 350 570-1  
**I:** black  
**II:** yellow/green  
**III:** red

**Design Data**

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

**Performance data**

Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	0.50
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	65.0
Nominal power [W]	$P_N$	2.84
Nominal current [A]	$I_N$	0.4
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

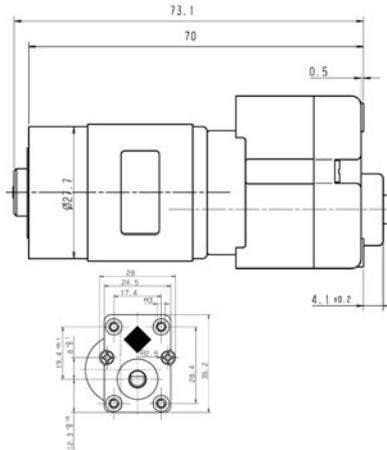
**Sensor data**

Pulses	0
Output channels	0

**Other data**

Gear ratio	109/1
Gear wheel material	
Suppression components	
Enclosure class	IP40
Weight [kg]	0.180

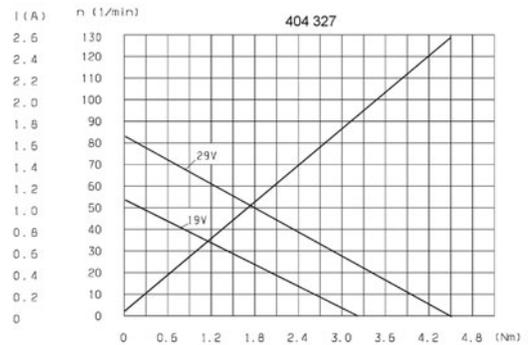
Remarks:



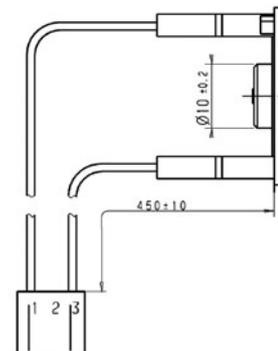
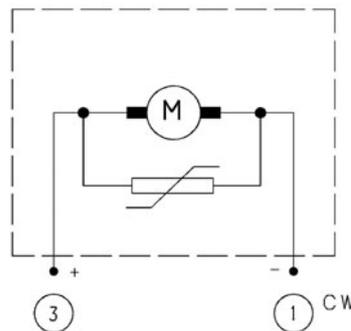
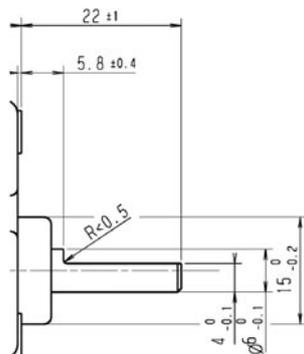
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



Housing: AMP-Nr. 1-480 700-0  
 Pins: AMP-Nr. 350 687-1



NIDEC MOTORS & ACTUATORS ❖❖❖ MOTOR SERIES

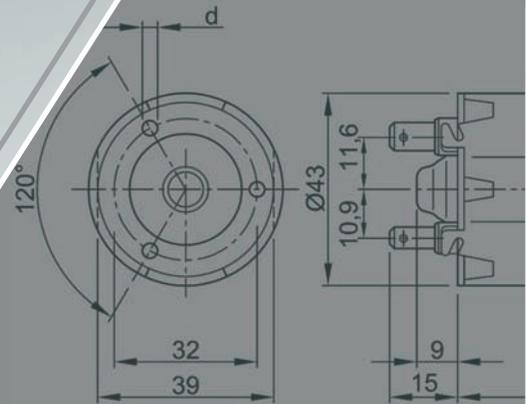
# 0231 (GMPI)

❖❖❖ DC MOTORS WITH SPUR GEAR



## ❖❖❖ TECHNICAL DESCRIPTION

Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	spur gear
Gear housing:	plastic
Gear wheel material:	plastic
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	connector or leads with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional



## ❖❖❖ INDUSTRIAL APPLICATION

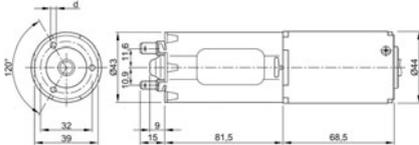
Linear actuators, home automation

## ❖❖❖ AUTOMOTIVE APPLICATION

Spoiler adjustment

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

**0231 A**



Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	210.0
Nominal power [W]	$P_N$	72.0
Nominal current [A]	$I_N$	7.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

Sensor data	
Pulses	0
Output channels	0

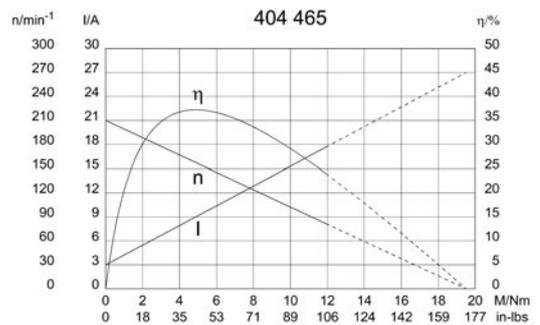
Other data	
Gear ratio	39.7/1
Gear wheel material	plastic
Suppression components	7,5 $\mu$ H, 1nF
Enclosure class	IP30
Weight [kg]	0.630

Remarks: d = 3,3mm, for selftapping screw 4mm (shape Remform)

**Motor picture**

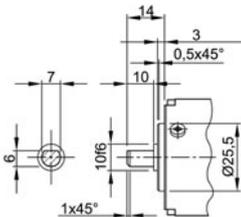


**Characteristic curves**

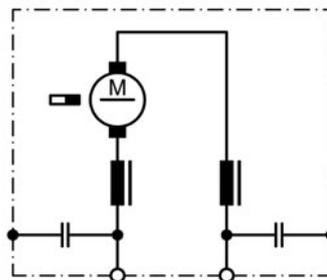


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

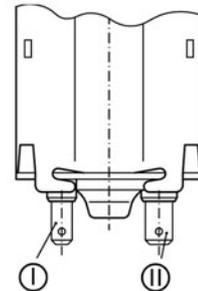
**W 268**



**S 30**



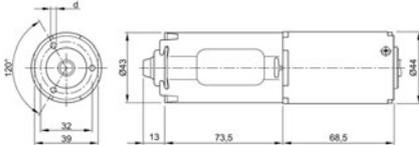
**K 117**



I Blade terminal ends 4,8 x 0,8 DIN 46 244  
 II Blade terminal ends 6,3 x 0,8 DIN 46 244

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

**0231 C**



Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	1.50
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	178.0
Nominal power [W]	$P_N$	20.0
Nominal current [A]	$I_N$	3.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

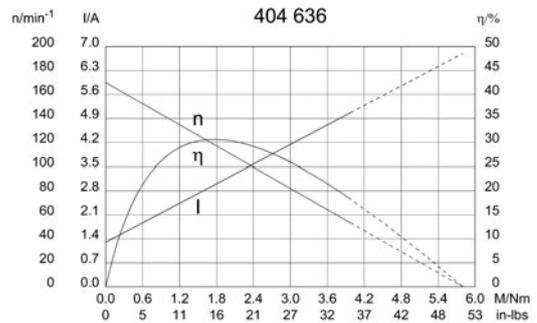
Sensor data	
Pulses	20
Output channels	2

Other data	
Gear ratio	20/1
Gear wheel material	plastic
Suppression components	4 $\mu$ H, 1nF
Enclosure class	IP 30
Weight [kg]	0.750

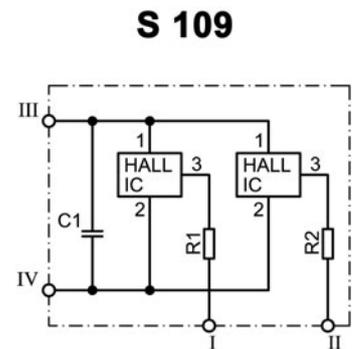
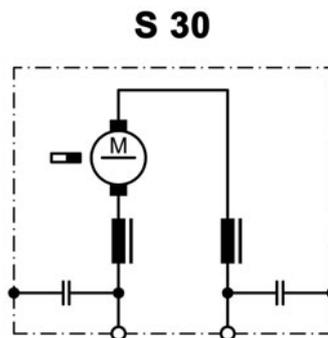
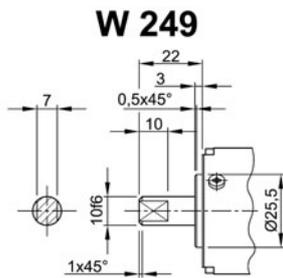
Remarks: d = 3,3mm, for self-cutting screw 4mm (shape Remform)

**Characteristic curves**

**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

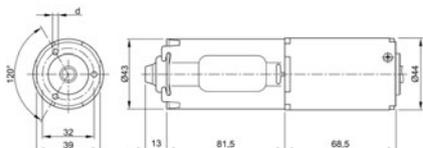


- I Terminal 1, OUT A1, grey
- II Terminal 2, OUT A2, black
- III Terminal 3, +, white
- IV Terminal 4, -, red



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	sleeve bearing

**0231 B**



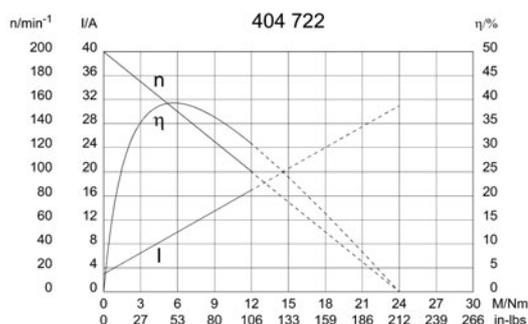
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	200.0
Nominal power [W]	$P_N$	69.8
Nominal current [A]	$I_N$	8.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s2

Sensor data	
Pulses	39
Output channels	2

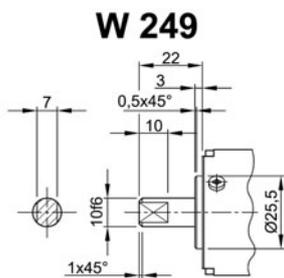
Other data	
Gear ratio	39.7/1
Gear wheel material	plastic
Suppression components	4,0 $\mu$ H, 1nF
Enclosure class	IP 30
Weight [kg]	0.650

Remarks: d = 3,3mm, for self-cutting screw 4mm

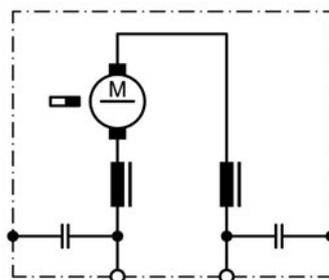
**Motor picture**



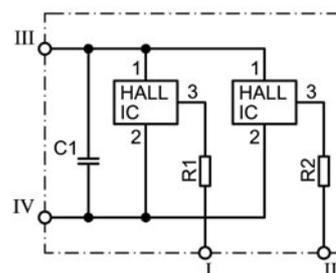
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 30**



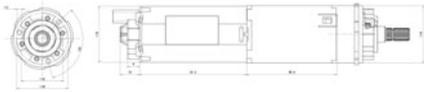
**S 109**



- I Terminal 1, OUT A1, grey
- II Terminal 2, OUT A2, black
- III Terminal 3, +, white
- IV Terminal 4, -, red



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve



Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	10.0
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	40.0
Nominal power [W]	$P_N$	34.4
Nominal current [A]	$I_N$	8.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

Sensor data	
Pulses	116
Output channels	1

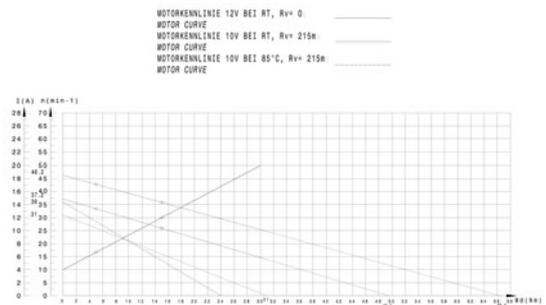
Other data	
Gear ratio	116/1
Gear wheel material	plastic
Suppression components	2,5 $\mu$ H, 47nF, ( )
Enclosure class	IP 30
Weight [kg]	0.800

Remarks:

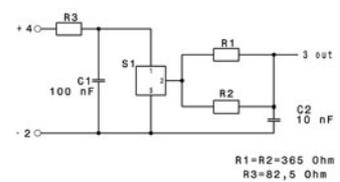
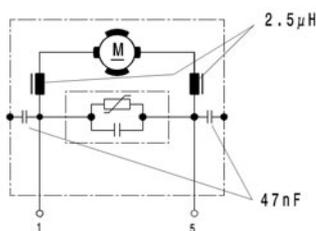
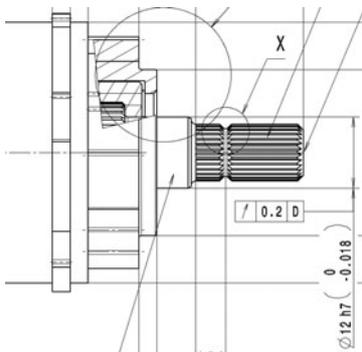
### Motor picture



### Characteristic curves

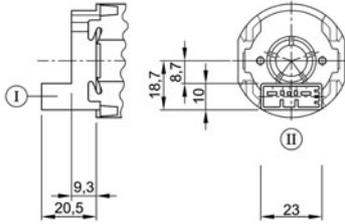


### Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

**K 220**



Connector TYCO C-208-15621 (Z) mating with:  
**Connector housing 1379217-3 & cover**  
1379218-2  
[www.tycoelectronics.com](http://www.tycoelectronics.com)

**Notes**

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NIDEC MOTORS & ACTUATORS ❖❖❖ MOTOR SERIES

# 0320 (GMPD)

❖❖❖ DC MOTORS WITH WORM GEAR



## ❖❖❖ TECHNICAL DESCRIPTION

Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	combination of worm and spur gear
Gear housing:	plastic
Gear wheel material:	plastic
Lubrication:	grease
Mechanical interface:	hollow shaft with profile
Electric interface:	connector or leads with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

## ❖❖❖ INDUSTRIAL APPLICATION

Machine construction

## ❖❖❖ AUTOMOTIVE APPLICATION

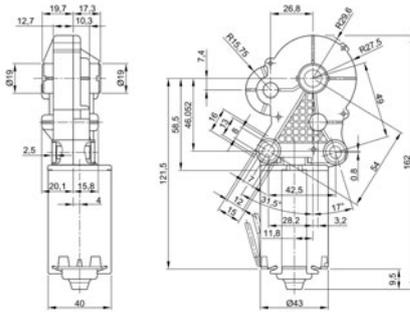
Seat Recline Adjustment



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	40.0
Nominal power [W]	$P_N$	14.8
Nominal current [A]	$I_N$	3.5
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

### 0320 AR



Sensor data	
Pulses	0
Output channels	0

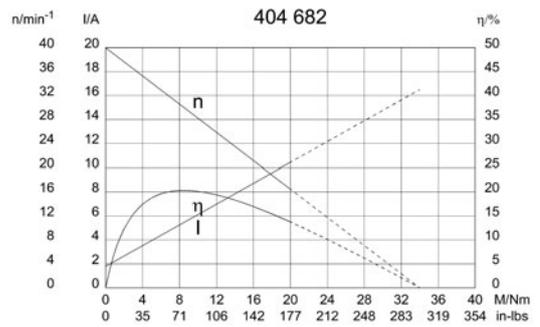
Other data	
Gear ratio	210/1
Gear wheel material	plastic
Suppression components	7,5 $\mu$ H, 1nF
Enclosure class	IP 40
Weight [kg]	0.440

Remarks:

### Motor picture

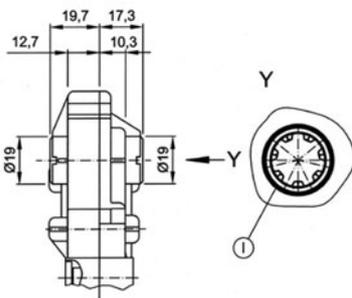


### Characteristic curves

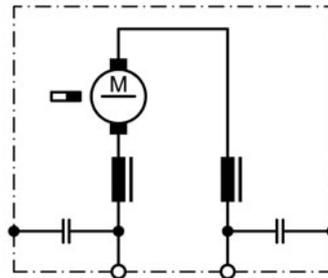


### Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

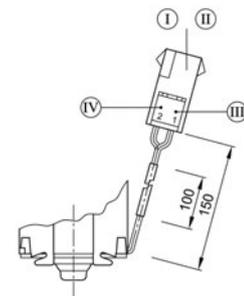
#### W 224



#### S 30



#### K 206



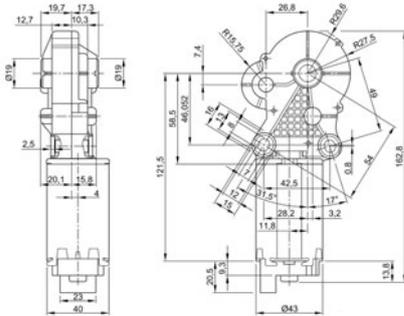
I through Profile KRC 316928 AEIZ 01

tap housing 365057-3, timer contacts 928781-5  
mating with receptacle housing 365058-3,  
timer contacts 927768-1  
1 black motor, 2 blue motor

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	3.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	21.0
Nominal power [W]	$P_N$	5.59
Nominal current [A]	$I_N$	3.5
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

**0320 BR**



Sensor data	
Pulses	0
Output channels	0

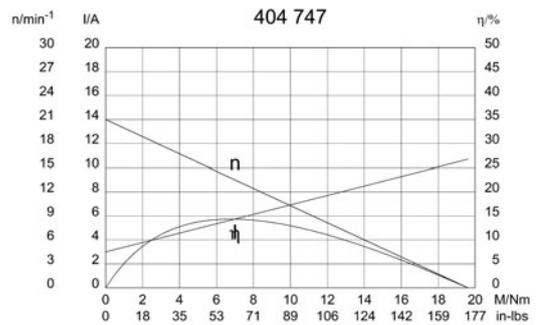
Other data	
Gear ratio	210/1
Gear wheel material	plastic
Suppression components	5,5 $\mu$ H, 47nF, (0,47 $\mu$ F)
Enclosure class	IP 40
Weight [kg]	0.440

Remarks:

**Motor picture**

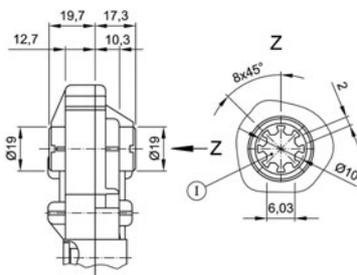


**Characteristic curves**



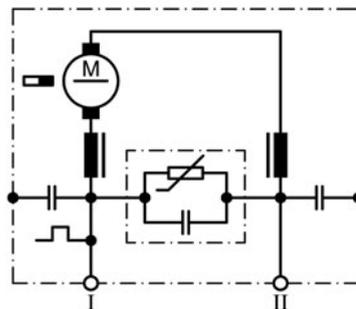
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

**W 270**



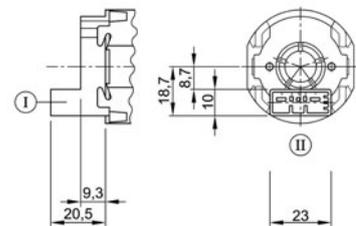
I through profile

**S 93**



I Terminal 1  
 II Terminal 5

**K 220**

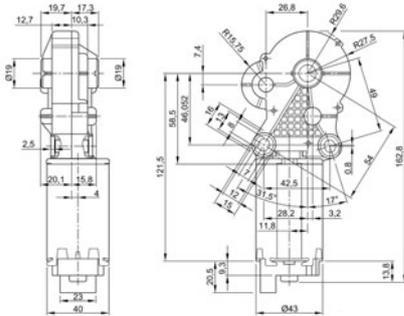


Connector TYCO C-208-15621 (Z) mating with:  
**Connector housing 1379217-3 & cover**  
 1379218-2  
[www.tycoelectronics.com](http://www.tycoelectronics.com)

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	3.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	21.0
Nominal power [W]	$P_N$	5.59
Nominal current [A]	$I_N$	3.5
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

**0320 BR**



Sensor data	
Pulses	210
Output channels	1

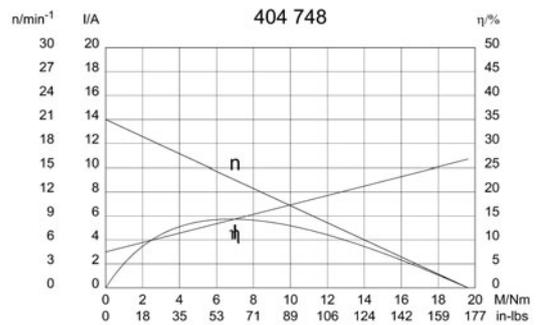
Other data	
Gear ratio	210/1
Gear wheel material	plastic
Suppression components	5,5 $\mu$ H, 47nF, (0,47 $\mu$ F)
Enclosure class	IP 40
Weight [kg]	0.440

Remarks:

**Motor picture**

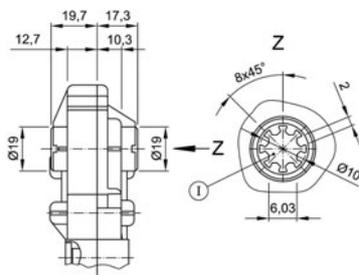


**Characteristic curves**



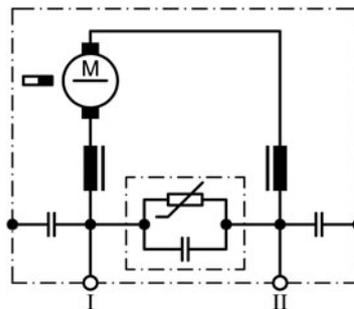
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

**W 270**



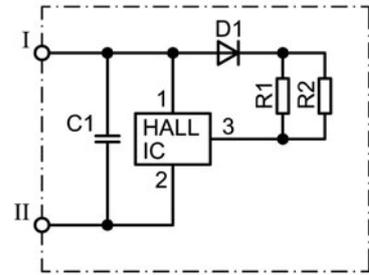
I through profile

**S 86**



I Terminal 1  
 II Terminal 5

**S 85**



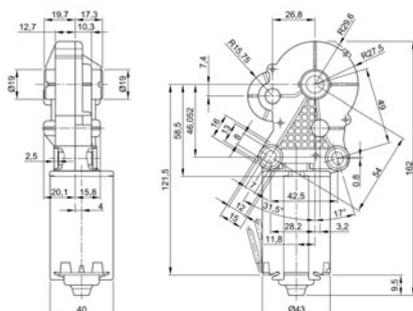
I Terminal 4, Hall-IC +  
 II Terminal 2, Hall-IC -



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	22.0
Nominal power [W]	$P_N$	7.54
Nominal current [A]	$I_N$	1.8
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

**0320 AR**



Sensor data	
Pulses	0
Output channels	0

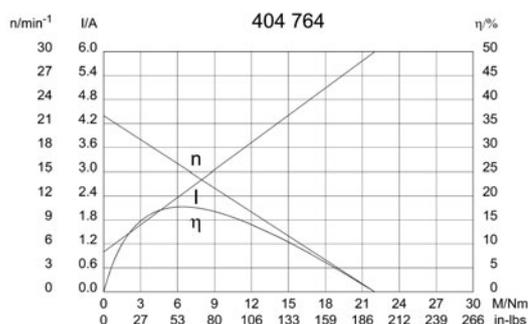
Other data	
Gear ratio	210/1
Gear wheel material	plastic
Suppression components	7,5 $\mu$ H, 47nF, (0,47 $\mu$ F)
Enclosure class	IP 40
Weight [kg]	0.440

Remarks:

**Motor picture**

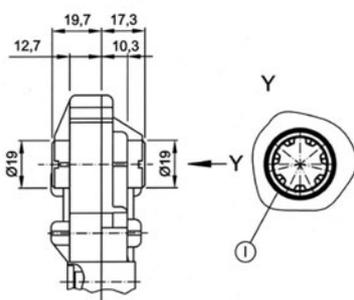


**Characteristic curves**



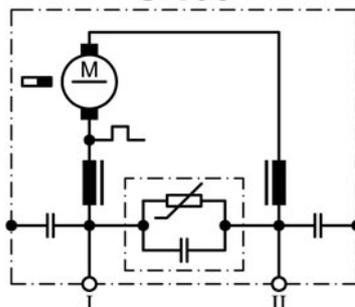
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

**W 224**



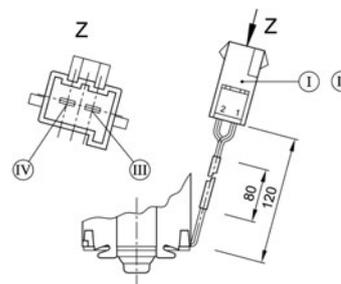
I through Profile KRC 316928 AEIZ 01

**S 103**



I Terminal 1, black  
 II Terminal 2, blue

**K 227**



tap housing 365057-1, timer contacts 928781-5  
 mating with receptacle housing 365058-1,  
 timer contacts 927768-1  
 1 black motor, 2 blue motor



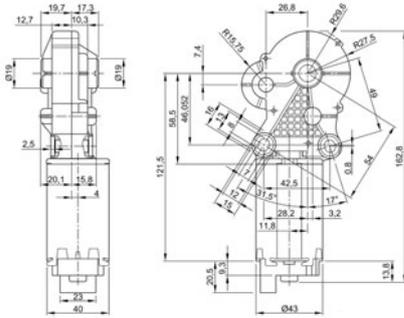




Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	21.0
Nominal power [W]	$P_N$	3.92
Nominal current [A]	$I_N$	3.5
Nominal force [kN]	$F_N$	0.00
Duty cycle		s3

**0320 BR**

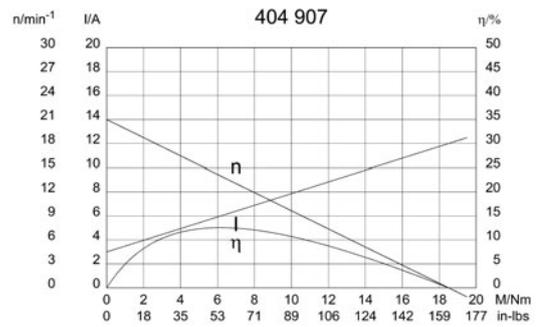


Sensor data	
Pulses	210
Output channels	1

Other data	
Gear ratio	210/1
Gear wheel material	plastic
Suppression components	""
Enclosure class	IP 40
Weight [kg]	0.440

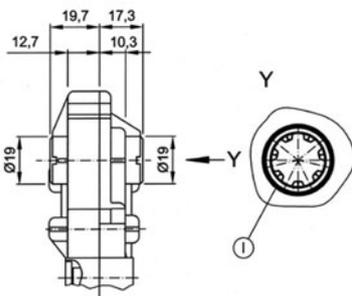
Remarks: Plastic gearbox

**Motor picture**



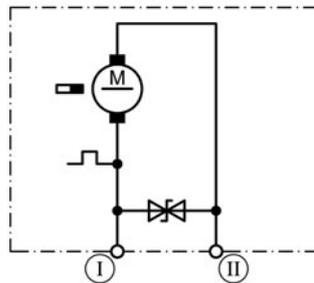
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

**W 224**



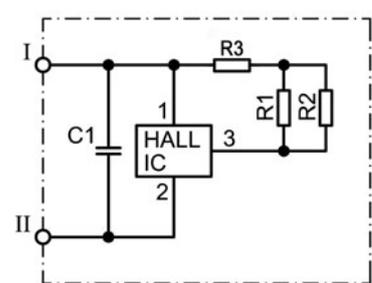
I through Profile KRC 316928 AEIZ 01

**S 138**



I Terminal 1  
 II Terminal 5

**S 140**



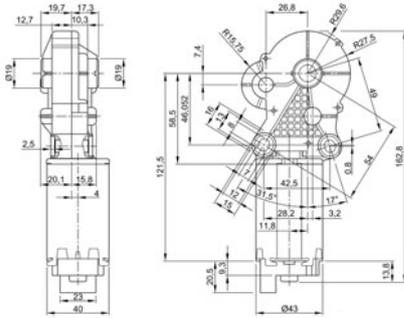
I Terminal 4; Hall-IC +  
 II Terminal 2; Hall-IC -



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	22.0
Nominal power [W]	$P_N$	4.10
Nominal current [A]	$I_N$	4.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s3	

**0320 BR**



Sensor data	
Pulses	0
Output channels	0

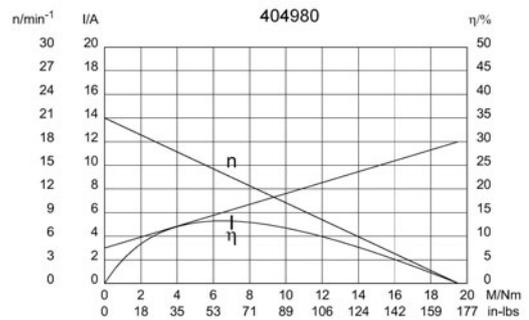
Other data	
Gear ratio	210/1
Gear wheel material	plastic
Suppression components	7,5 $\mu$ H, 1nF
Enclosure class	IP40
Weight [kg]	0.440

Remarks:

**Motor picture**

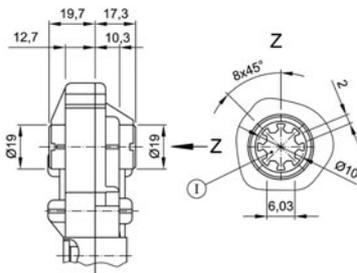


**Characteristic curves**



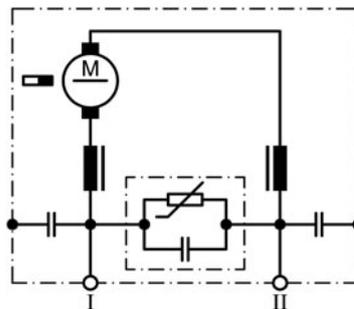
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

**W 270**



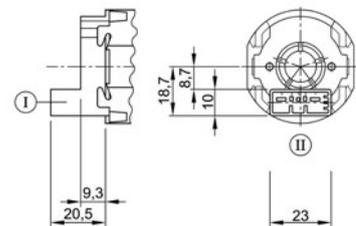
I through profile

**S 86**



I Terminal 1  
II Terminal 5

**K 220**



Connector TYCO C-208-15621 (Z) mating with:  
**Connector housing 1379217-3 & cover 1379218-2**  
[www.tycoelectronics.com](http://www.tycoelectronics.com)





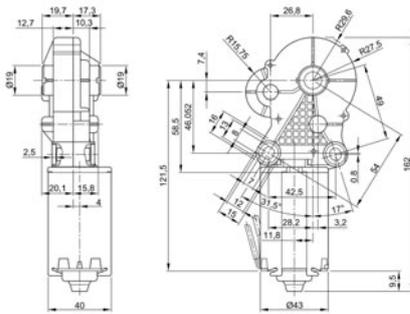




Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	20.0
Nominal power [W]	$P_N$	6.70
Nominal current [A]	$I_N$	2.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s3	

**0320 AR**



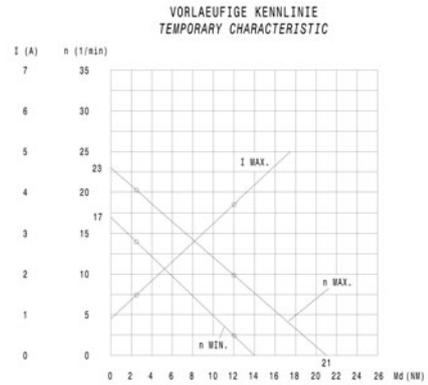
Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	246.75/1
Gear wheel material	plastic
Suppression components	7,5 $\mu$ , 47nF
Enclosure class	IP 40
Weight [kg]	0.440

Remarks:

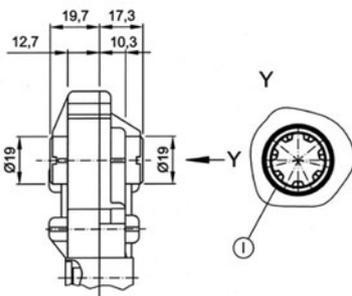
**Motor picture**

**Characteristic curves**

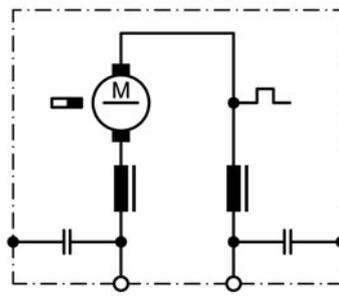


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

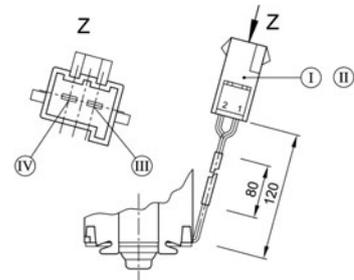
**W 224**



**S 74**



**K 227**



I through Profile KRC 316928 AEIZ 01

tap housing 365057-1, timer contacts 928781-5  
 mating with receptacle housing 365058-1,  
 timer contacts 927768-1  
 1 black motor, 2 blue motor





NIDEC MOTORS & ACTUATORS ❖❖❖ MOTOR SERIES

# 0225 (GMPG)

❖❖❖ DC MOTORS WITH WORM GEAR



## ❖❖❖ TECHNICAL DESCRIPTION

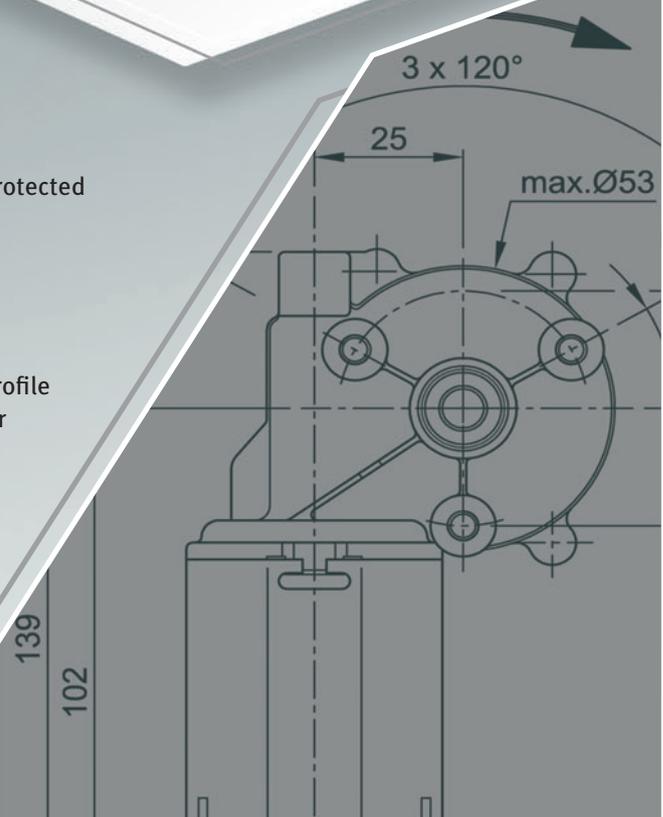
Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	zinc die cast
Gear wheel material:	plastic
Lubrication:	grease
Mechanical interface:	steel shaft or hollow shaft with profile
Electric interface:	connector or leads with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

## ❖❖❖ INDUSTRIAL APPLICATION

Catering, Office machines, Furniture Adjustment, Machine Construction

## ❖❖❖ AUTOMOTIVE APPLICATION

Sunroof adjustment



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

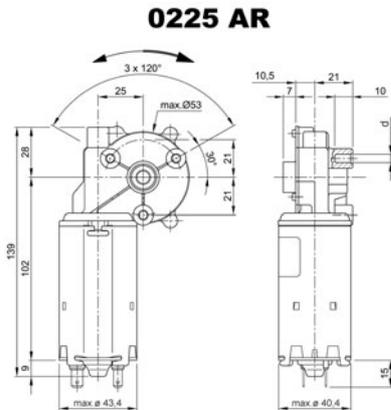
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	1.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	80.0
Nominal power [W]	$P_N$	7.33
Nominal current [A]	$I_N$	1.5
Nominal force [kN]	$F_N$	0.00
Duty cycle	s3	

Sensor data	
Pulses	0
Output channels	0

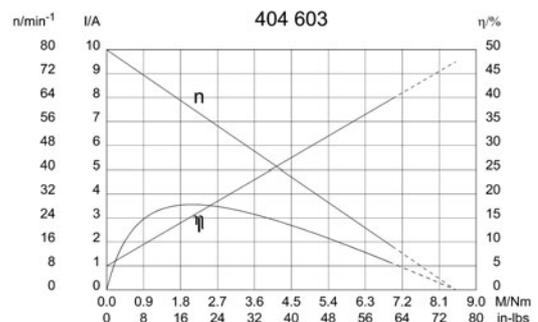
Other data	
Gear ratio	62/1
Gear wheel material	plastic
Suppression components	
Enclosure class	IP 30
Weight [kg]	0.610

Remarks: d=selftapping screw M5

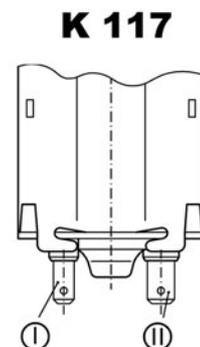
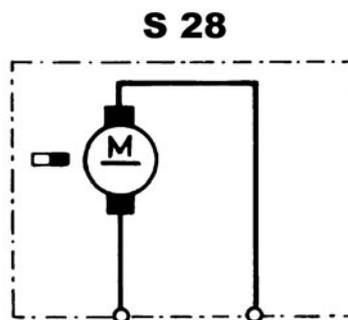
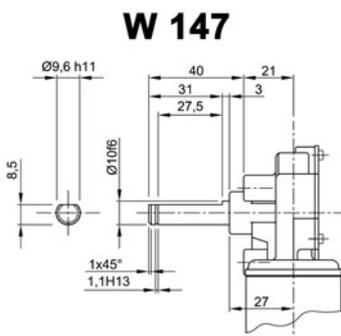
**Characteristic curves**



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



I - Blade terminal ends 4,8 x 0,8 DIN 46 244  
 II - Blade terminal ends 6,3 x 0,8 DIN 46 244

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

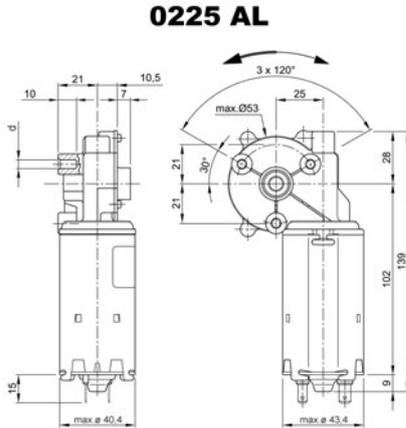
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	0.50
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	540.0
Nominal power [W]	$P_N$	24.7
Nominal current [A]	$I_N$	2.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s3	

Sensor data	
Pulses	0
Output channels	0

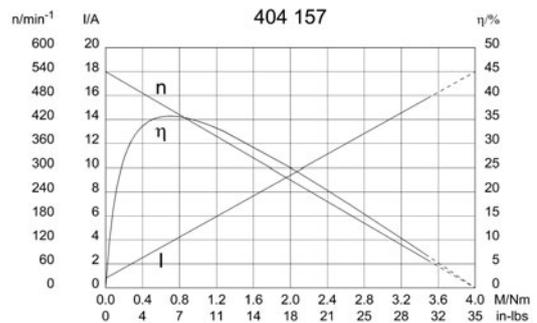
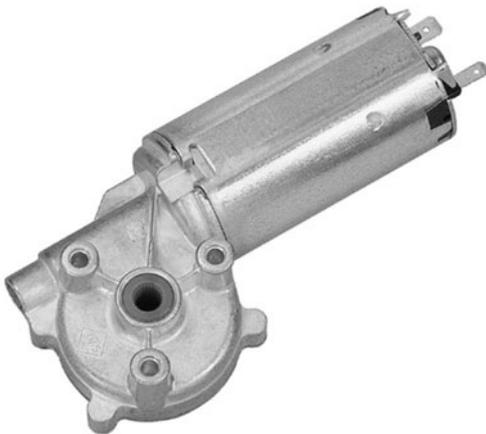
Other data	
Gear ratio	56/4
Gear wheel material	plastic
Suppression components	7,5 $\mu$ H, 1nF
Enclosure class	IP 30
Weight [kg]	0.710

Remarks: d = for thread-forming screw M 5 DIN 7500

**Characteristic curves**

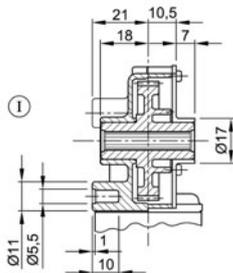


**Motor picture**



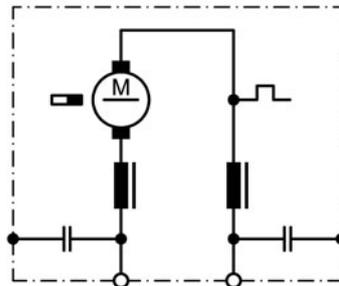
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

**W 148**

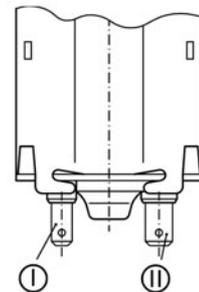


I Tapered splines 7 x 8 DIN 5481 continuous

**S 74**



**K 117**



I Blade terminal ends 4,8 x 0,8 DIN 46 244  
 II Blade terminal ends 6,3 x 0,8 DIN 46 244

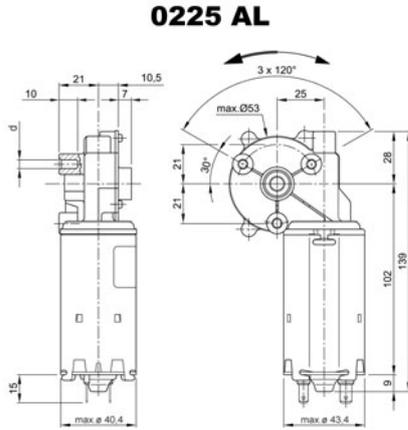
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	0.50
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	60.0
Nominal power [W]	$P_N$	2.83
Nominal current [A]	$I_N$	2.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	62/1
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	0.710

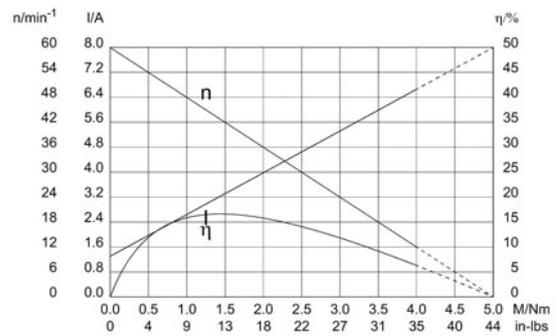
Remarks:



**Motor picture**

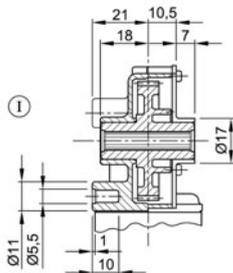


**Characteristic curves**



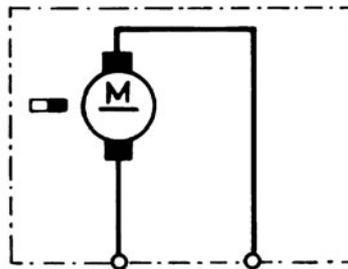
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

**W 148**

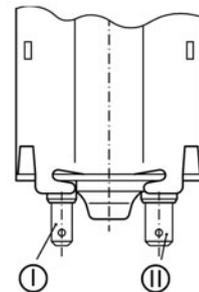


I Tapered splines 7 x 8 DIN 5481 continuous

**S 28**



**K 117**



I Blade terminal ends 4,8 x 0,8 DIN 46 244  
 II Blade terminal ends 6,3 x 0,8 DIN 46 244

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

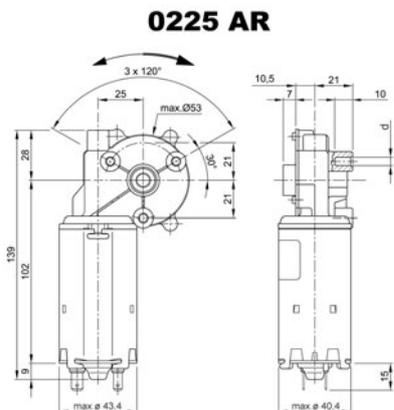
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	1.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	80.0
Nominal power [W]	$P_N$	7.39
Nominal current [A]	$I_N$	2.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s3	

Sensor data	
Pulses	0
Output channels	0

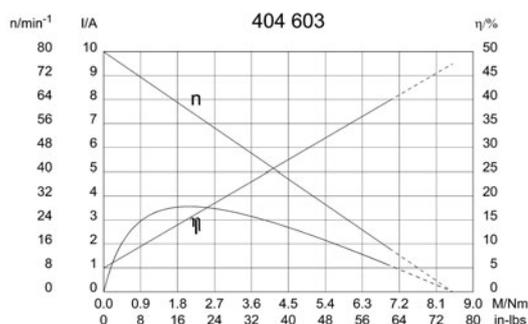
Other data	
Gear ratio	62/1
Gear wheel material	plastic
Suppression components	7,5 $\mu$ H, 1nF
Enclosure class	IP30
Weight [kg]	0.710

Remarks: d = for thread-forming screw M 5 DIN 7500

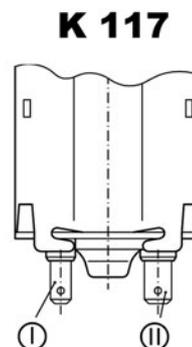
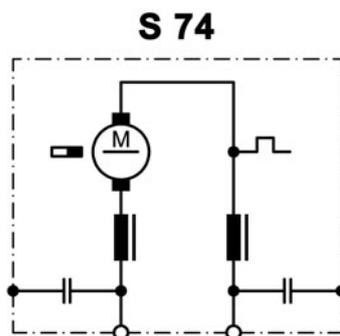
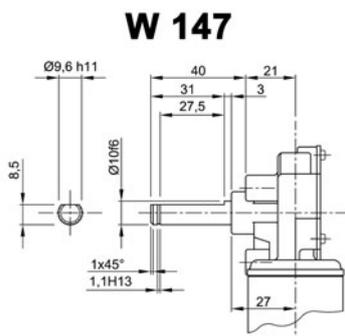
**Characteristic curves**



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



I - Blade terminal ends 4,8 x 0,8 DIN 46 244  
 II - Blade terminal ends 6,3 x 0,8 DIN 46 244

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

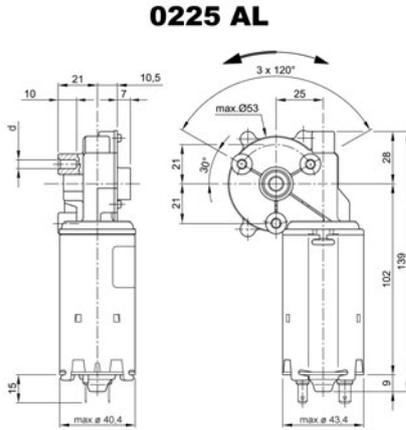
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	1.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	28.0
Nominal power [W]	$P_N$	2.48
Nominal current [A]	$I_N$	1.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s2	

Sensor data	
Pulses	0
Output channels	0

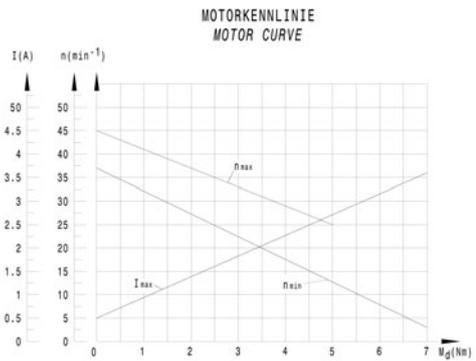
Other data	
Gear ratio	72/1
Gear wheel material	plastic
Suppression components	7,5 $\mu$ H, 1nF
Enclosure class	IP 30
Weight [kg]	0.710

Remarks: d=selftapping screw M5

**Characteristic curves**

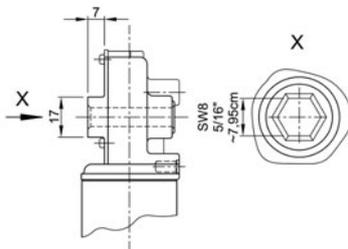


**Motor picture**

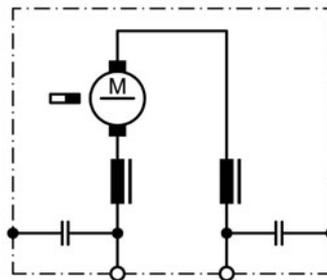


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

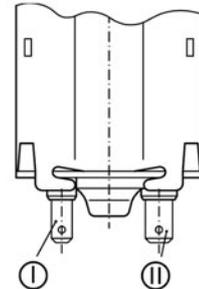
**W 229**



**S 30**



**K 117**



I - Blade terminal ends 4,8 x 0,8 DIN 46 244  
 II - Blade terminal ends 6,3 x 0,8 DIN 46 244

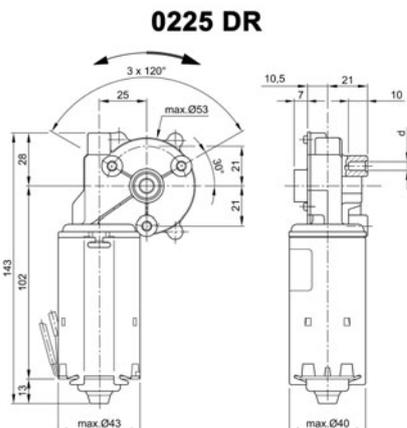
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	140.0
Nominal power [W]	$P_N$	25.1
Nominal current [A]	$I_N$	5.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s3	

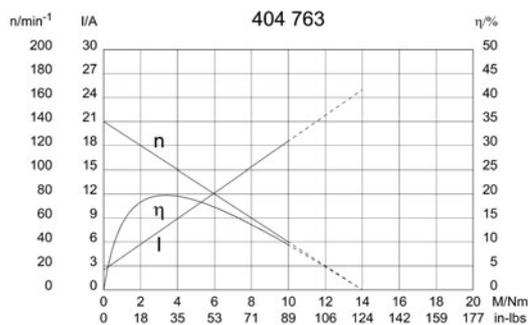
Sensor data	
Pulses	62
Output channels	2

Other data	
Gear ratio	62/1
Gear wheel material	plastic
Suppression components	$4\mu\text{H}$ , $1\text{nF}$
Enclosure class	IP 30
Weight [kg]	0.710

Remarks: d = for thread-forming screw M5 DIN 7500

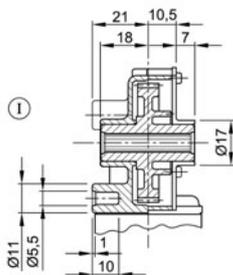


**Motor picture**



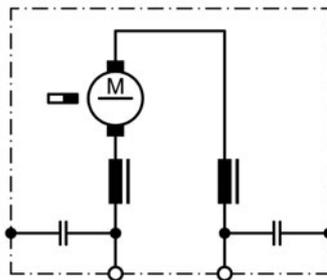
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

**W 148**

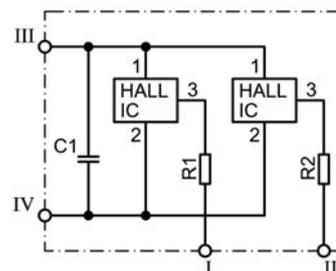


I Tapered splines 7 x 8 DIN 5481 continuous

**S 30**



**S 109**



I Terminal 1, OUT A1, grey  
 II Terminal 2, OUT A2, black  
 III Terminal 3, +, white  
 IV Terminal 4, -, red



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

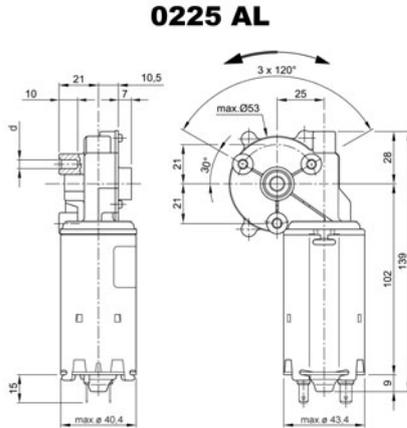
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	1.30
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	35.0
Nominal power [W]	$P_N$	3.94
Nominal current [A]	$I_N$	1.5
Nominal force [kN]	$F_N$	0.00
Duty cycle	s3	

Sensor data	
Pulses	0
Output channels	0

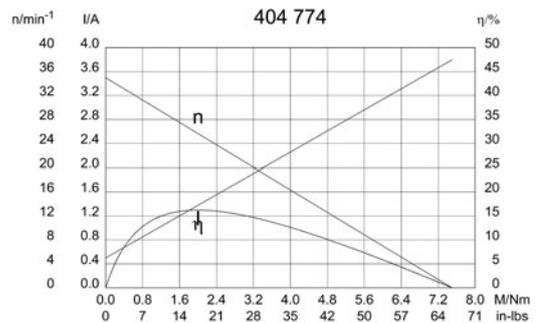
Other data	
Gear ratio	72/1
Gear wheel material	plastic
Suppression components	7,5 $\mu$ H, 1nF
Enclosure class	IP 30
Weight [kg]	0.570

Remarks: d = for self-tapping screw M5 DIN 7500

**Characteristic curves**

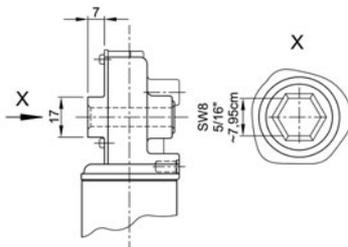


**Motor picture**

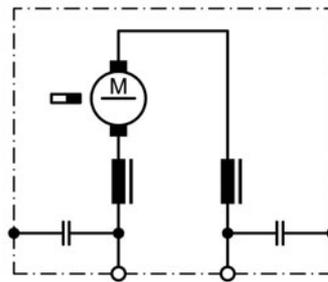


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

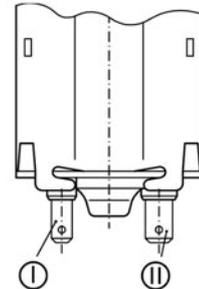
**W 229**



**S 30**



**K 117**



- I Blade terminal ends 4,8 x 0,8 DIN 46 244
- II Blade terminal ends 6,3 x 0,8 DIN 46 244

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

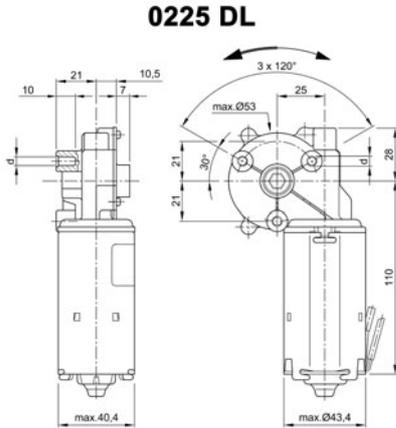
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	1.50
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	35.0
Nominal power [W]	$P_N$	4.47
Nominal current [A]	$I_N$	1.5
Nominal force [kN]	$F_N$	0.00
Duty cycle	s3	

Sensor data	
Pulses	288
Output channels	1

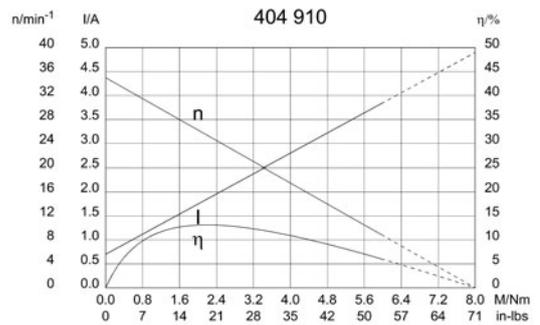
Other data	
Gear ratio	72/1
Gear wheel material	plastic
Suppression components	7,5 $\mu$ H
Enclosure class	IP 30
Weight [kg]	0.710

Remarks: d = for thread-forming screw M5 DIN 7500

**Characteristic curves**

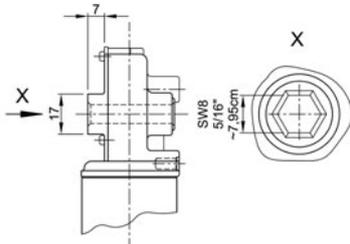


**Motor picture**

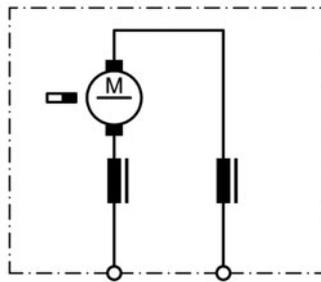


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

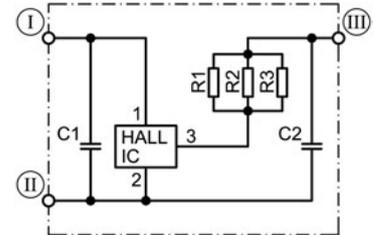
**W 229**



**S 27**



**S 125**



- I Terminal 3, +, white
- II Terminal 2, -, black
- III Terminal 6, OUT, red



**Notes**

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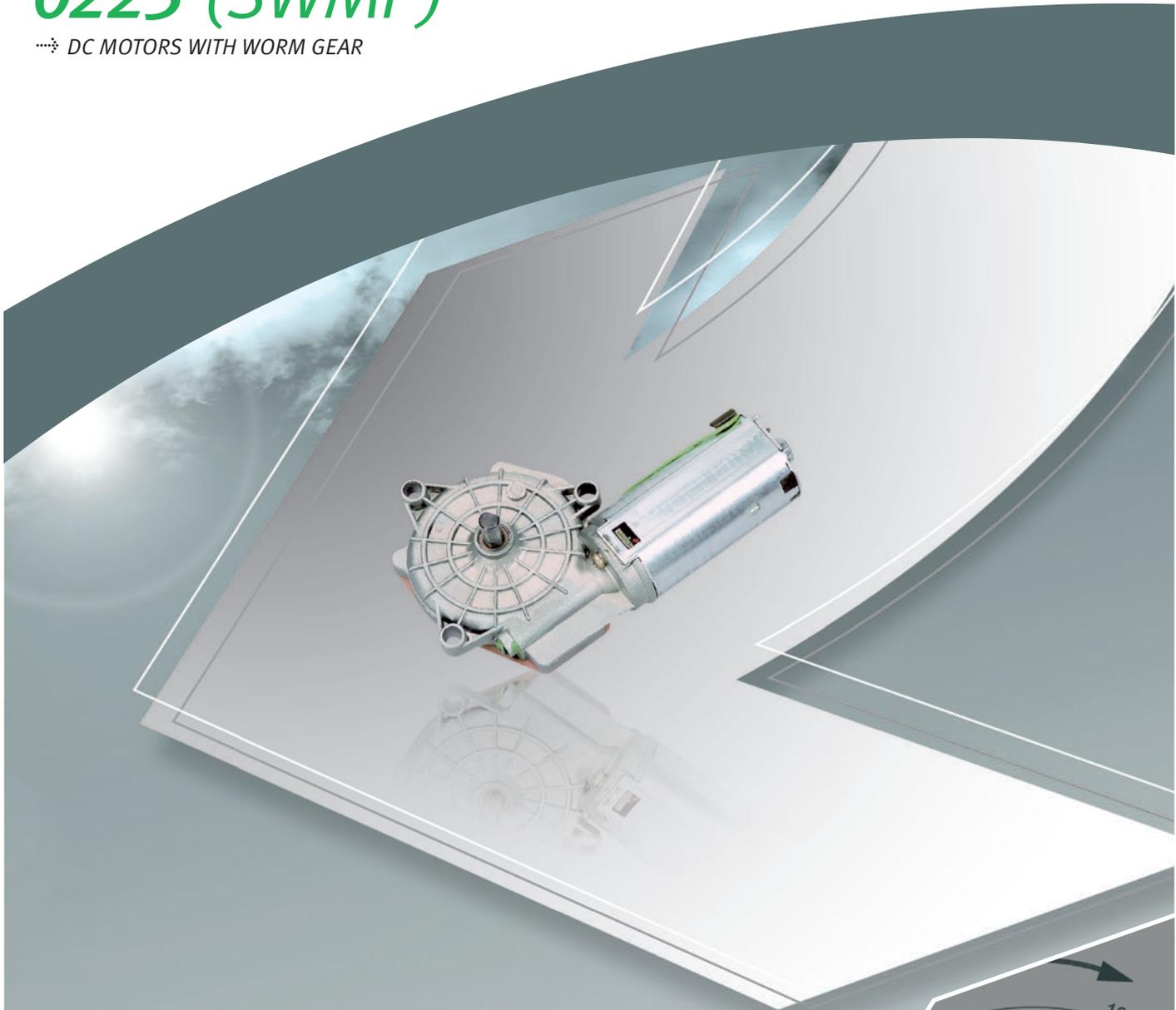
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NIDEC MOTORS & ACTUATORS ❖❖❖ MOTOR SERIES

# 0223 (SWMP)

❖❖❖ DC MOTORS WITH WORM GEAR



## ❖❖❖ TECHNICAL DESCRIPTION

Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	zinc die cast
Gear wheel material:	plastic or resinbonded fabric
Lubrication:	grease
Mechanical interface:	output shaft
Electric interface:	connector or leads with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

## ❖❖❖ APPLICATION

General machine construction, Automatic machines,  
 Agricultural technology, Business machines,  
 Laboratory appliances, Medical appliances,  
 Traffic & communications technology,  
 Photographic/optical equipment



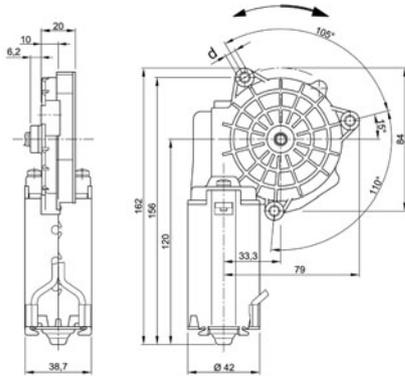
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	50.0
Nominal power [W]	$P_N$	8.73
Nominal current [A]	$I_N$	1.5
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	85/1
Gear wheel material	Resinbonded fabric
Suppression components	
Enclosure class	IP30
Weight [kg]	0.710

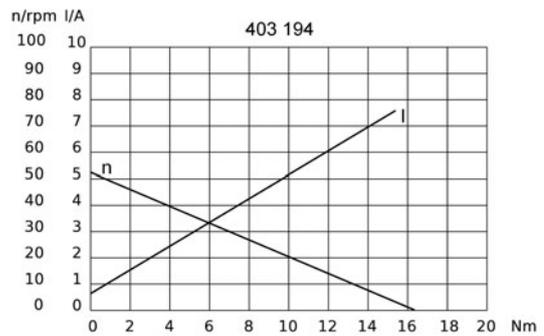
Remarks: d = M6



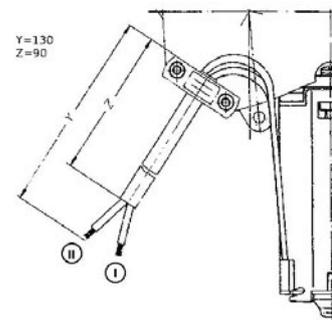
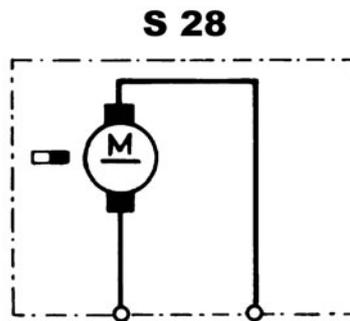
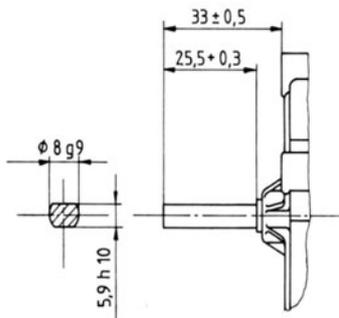
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



I: green  
 II: black

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

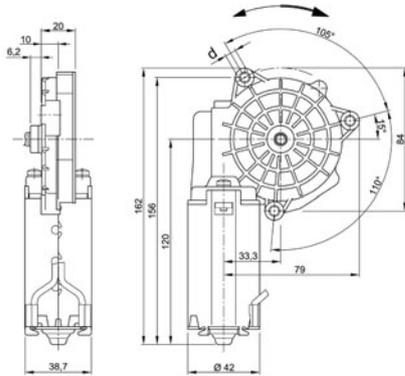
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	54.0
Nominal power [W]	$P_N$	9.94
Nominal current [A]	$I_N$	1.5
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

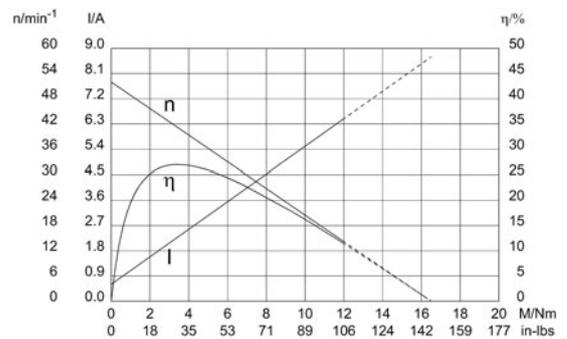
Other data	
Gear ratio	85/1
Gear wheel material	Plastic
Suppression components	7.5 $\mu\text{H}$ , 47nF
Enclosure class	IP30
Weight [kg]	0.710

Remarks: d = 7.5mm, Ball bearing

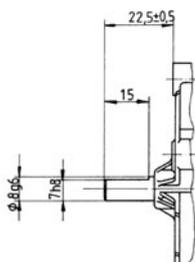
**Characteristic curves**



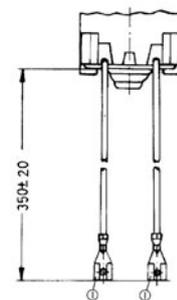
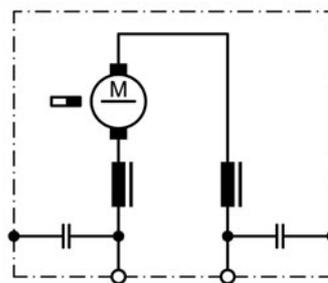
**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 30**



Spade connector 4.8 DIN 46 247

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

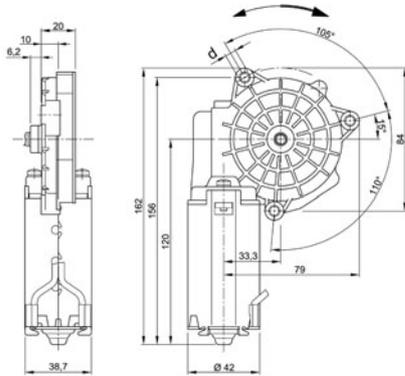
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	52.0
Nominal power [W]	$P_N$	9.57
Nominal current [A]	$I_N$	0.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

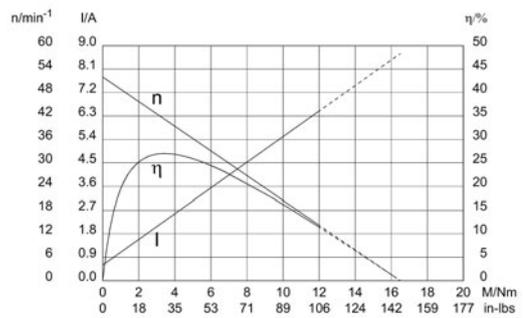
Other data	
Gear ratio	85/1
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	0.710

Remarks: d = 7.5mm, Ball bearing

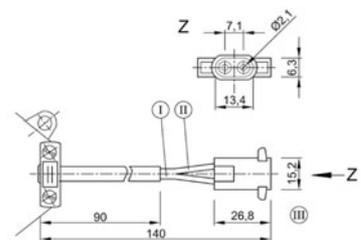
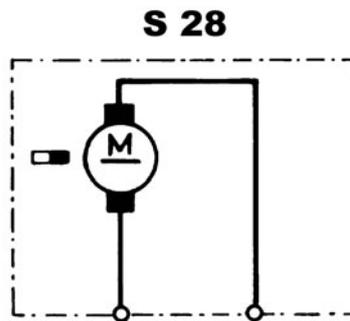
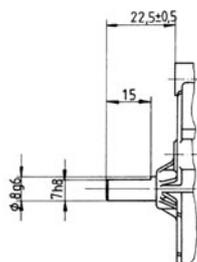
**Characteristic curves**



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



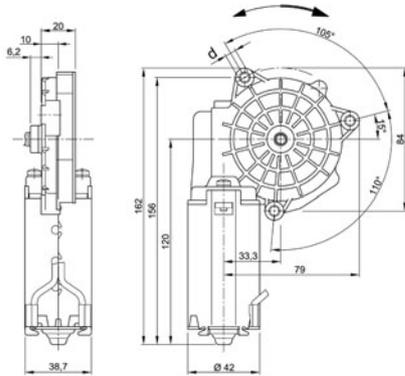
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	52.0
Nominal power [W]	$P_N$	9.34
Nominal current [A]	$I_N$	1.5
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	85/1
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	0.710

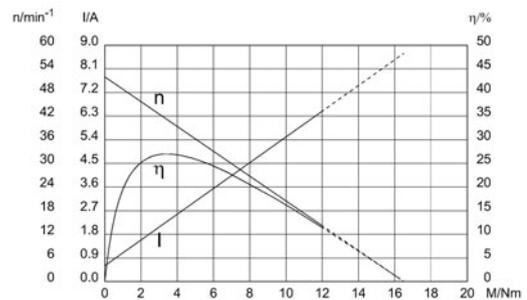
Remarks: d = M6, Ball bearing



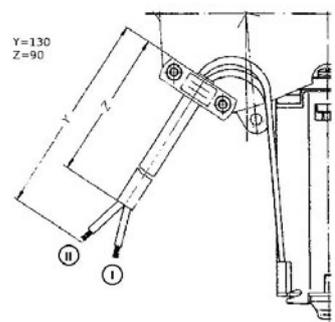
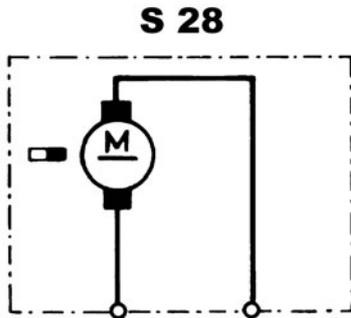
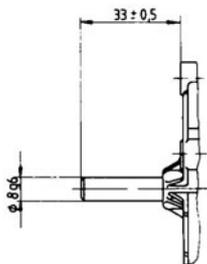
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



I: green  
 II: black

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

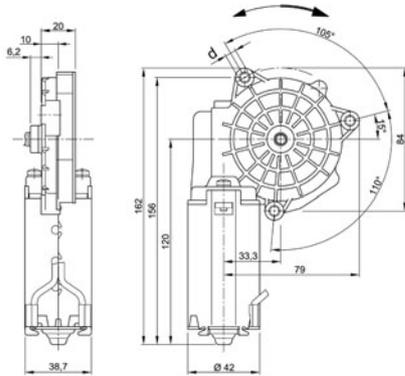
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	52.0
Nominal power [W]	$P_N$	9.34
Nominal current [A]	$I_N$	1.5
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

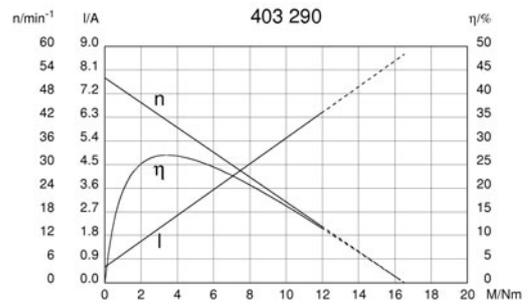
Other data	
Gear ratio	85/1
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	0.710

Remarks: d = M6, Ball bearing

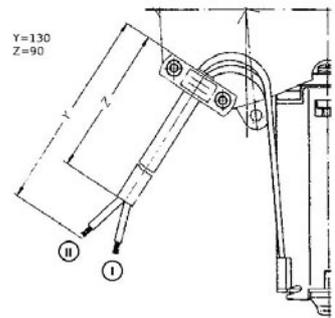
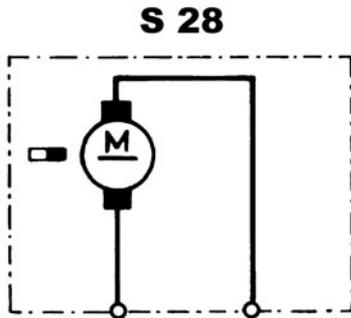
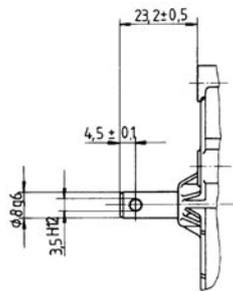
**Characteristic curves**



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



I: green  
 II: black

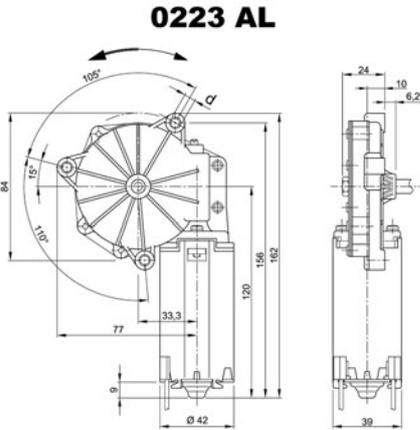
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	1.30
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	110.0
Nominal power [W]	$P_N$	12.2
Nominal current [A]	$I_N$	2.6
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

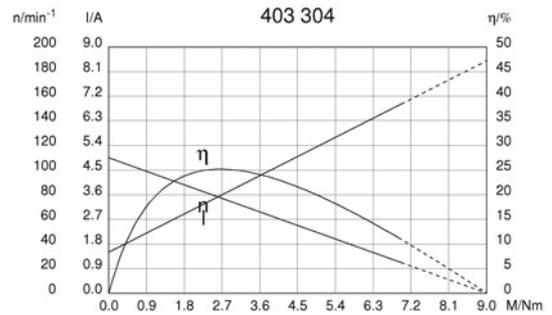
Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	83/2
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	0.710

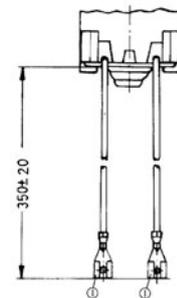
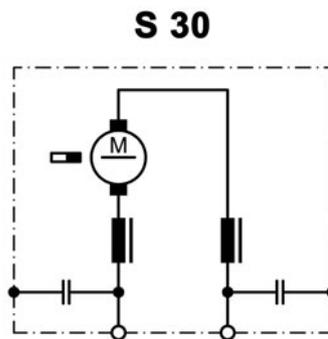
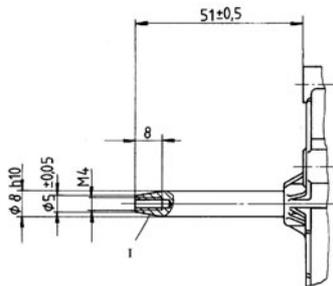
Remarks: d = M6, Ball bearing



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



I: Cone 1:4

Spade connector 4.8 DIN 46 247

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

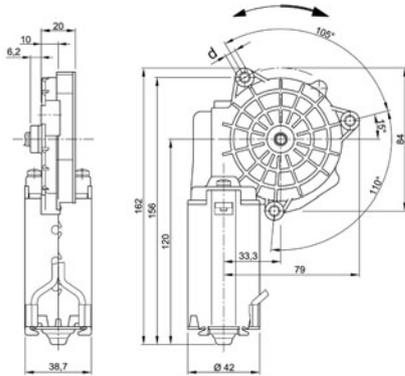
Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	1.30
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	100.0
Nominal power [W]	$P_N$	11.1
Nominal current [A]	$I_N$	3.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

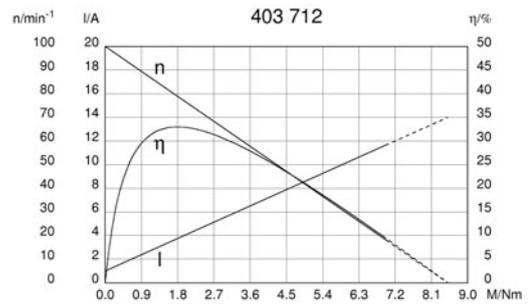
Other data	
Gear ratio	83/2
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	0.710

Remarks: d = M6, Ball bearing

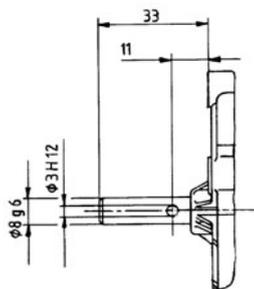
**Characteristic curves**



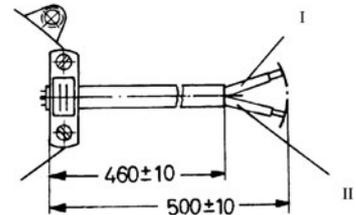
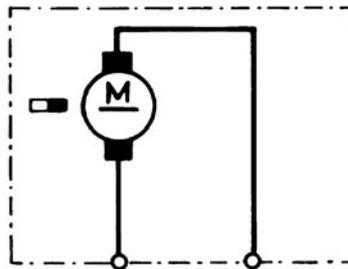
**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 28**



I: black  
 II: green

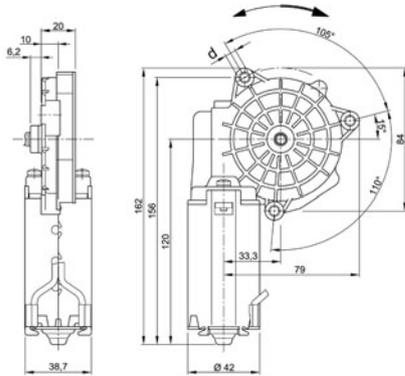
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	50.0
Nominal power [W]	$P_N$	8.98
Nominal current [A]	$I_N$	2.5
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	99/1
Gear wheel material	Resinbonded fabric
Suppression components	
Enclosure class	
Weight [kg]	0.710

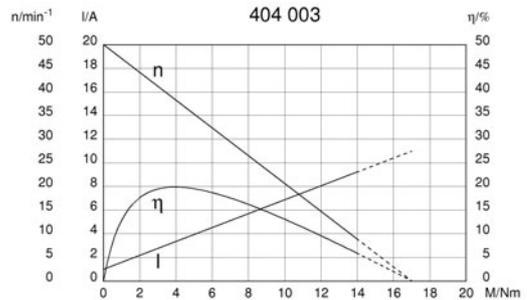
Remarks: d = M6, Ball bearing



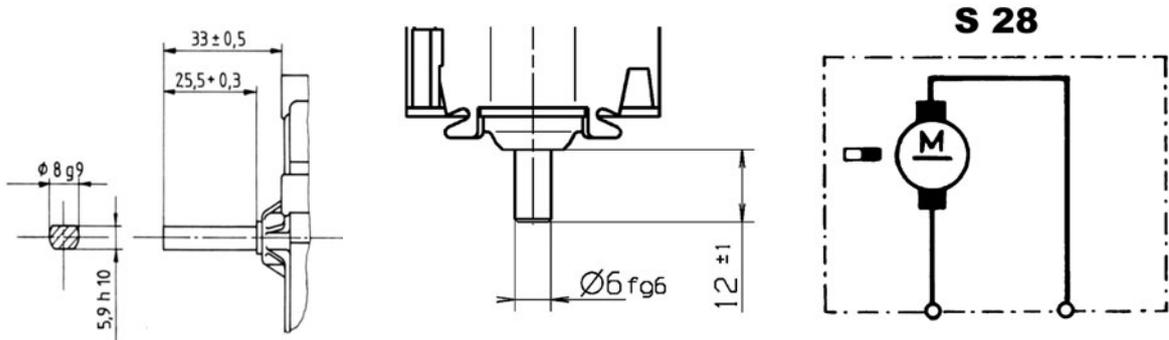
**Motor picture**



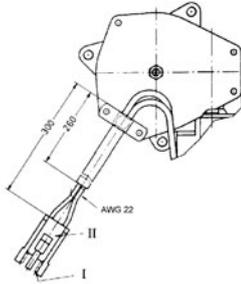
**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



I: Housing RDST OCE: 2645082

II: Pins RD OCE: 2642354

**Notes**

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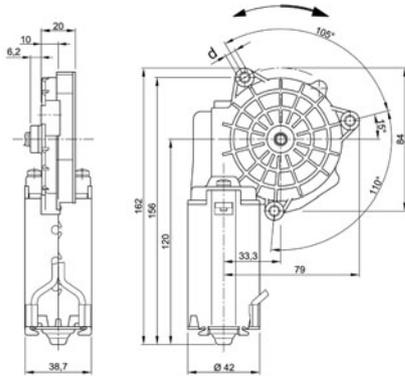
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Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	50.0
Nominal power [W]	$P_N$	8.38
Nominal current [A]	$I_N$	2.3
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	



Sensor data	
Pulses	0
Output channels	0

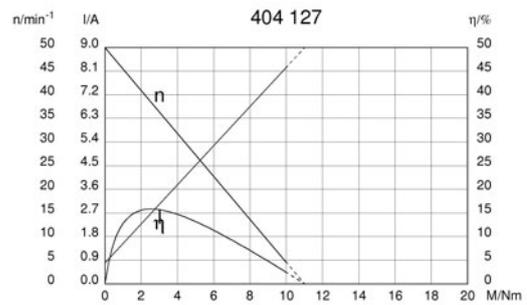
Other data	
Gear ratio	85/1
Gear wheel material	Resinbonded fabric
Suppression components	
Enclosure class	IP30
Weight [kg]	0.710

Remarks: d = M6, Ball bearing

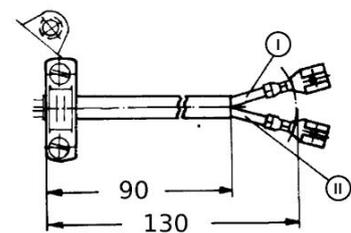
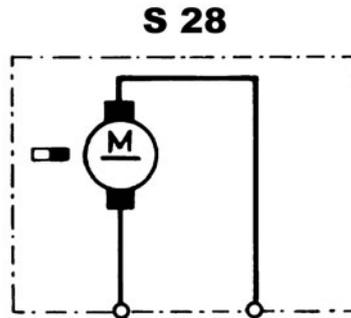
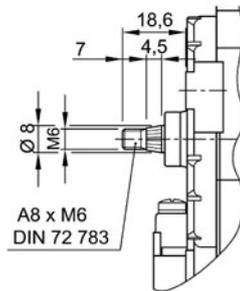
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



Spade connector 6.3 x 0.8 DIN 46 244  
 I: black  
 II: green

**Notes**

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NIDEC MOTORS & ACTUATORS ⇄ MOTOR SERIES

# 0321 (GMPS)

⇄ DC MOTORS WITH WORM GEAR



## ⇄ TECHNICAL DESCRIPTION

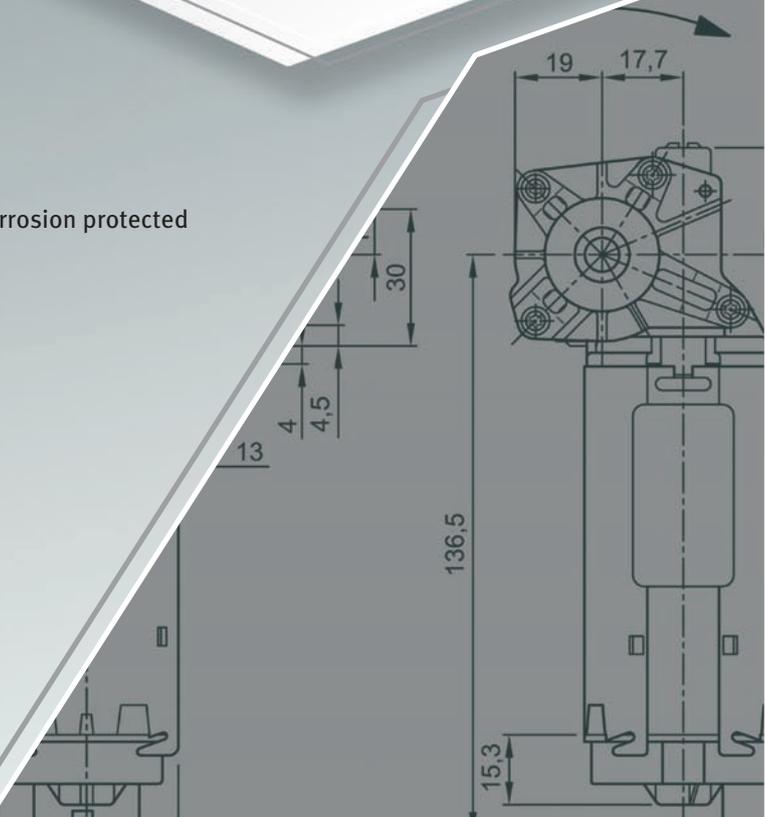
Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	zinc die cast
Gear wheel material:	plastic
Lubrication:	grease
Mechanical interface:	steel lead screw
Electric interface:	connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

## ⇄ INDUSTRIAL APPLICATION

Home automation

## ⇄ AUTOMOTIVE APPLICATION

Seat tilt and height adjustment



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

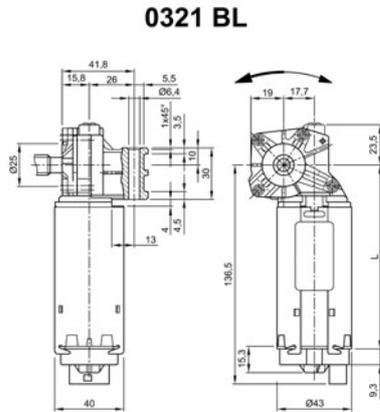
Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	1.50
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	180.0
Nominal power [W]	$P_N$	21.3
Nominal current [A]	$I_N$	9.0
Nominal force [kN]	$F_N$	2.00
Duty cycle	s3	

Sensor data	
Pulses	29
Output channels	1

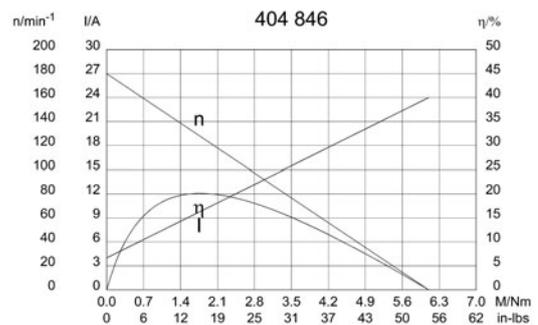
Other data	
Gear ratio	29/1
Gear wheel material	plastic
Suppression components	5,5 $\mu$ H, 47nF, (0,47 $\mu$ F)
Enclosure class	IP 40
Weight [kg]	0.880

Remarks: L = 116mm, 1 start worm

**Characteristic curves**

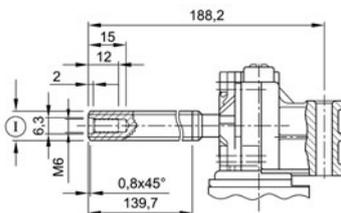


**Motor picture**



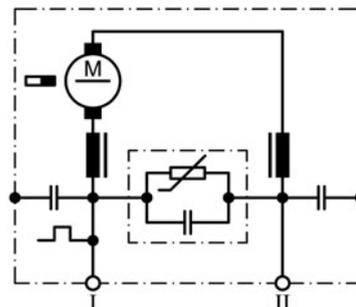
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

**W 288**



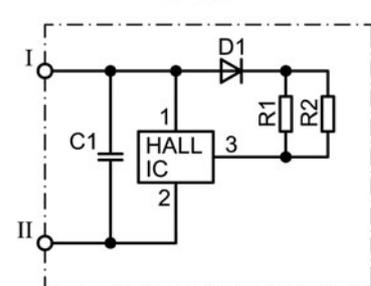
shape 7/16-8 STUB ACME RH, pressure angle 20°, pitch 3,175mm (0,125"), no of starts 1

**S 93**



I Terminal 1  
 II Terminal 5

**S 85**



I Terminal 4, Hall-IC +  
 II Terminal 2, Hall-IC -



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Sleeve - B:Sleeve

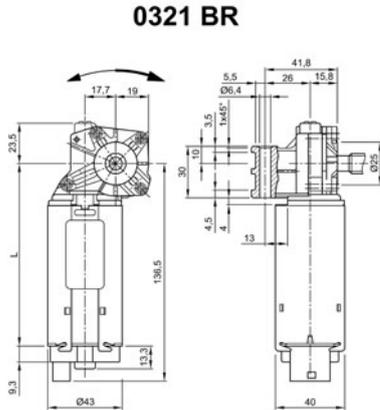
Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	1.50
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	180.0
Nominal power [W]	$P_N$	21.3
Nominal current [A]	$I_N$	6.0
Nominal force [kN]	$F_N$	2.00
Duty cycle		s3

Sensor data	
Pulses	29
Output channels	1

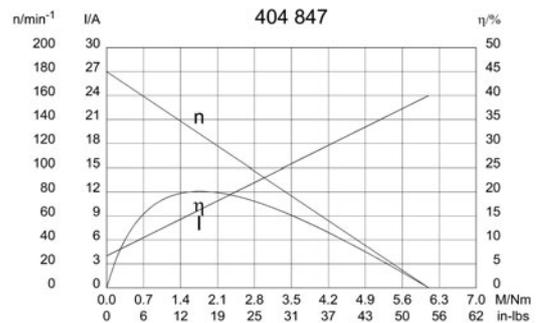
Other data	
Gear ratio	29/1
Gear wheel material	plastic
Suppression components	5,5 $\mu$ H, 47nF, (0,47 $\mu$ F)
Enclosure class	IP 40
Weight [kg]	0.880

Remarks: L = 116mm, 1 start worm

**Characteristic curves**

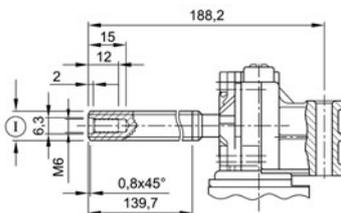


**Motor picture**



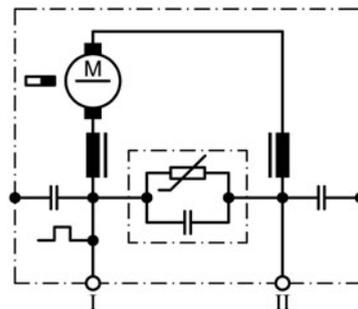
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

**W 288**



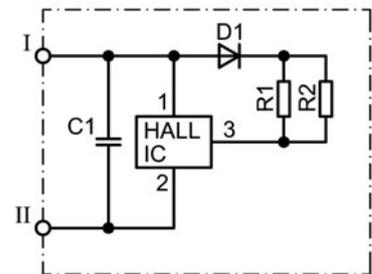
shape 7/16-8 STUB ACME RH, pressure angle 20°, pitch 3,175mm (0,125"), no of starts 1

**S 93**



I Terminal 1  
 II Terminal 5

**S 85**



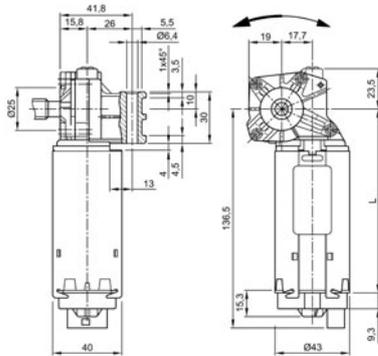
I Terminal 4, Hall-IC +  
 II Terminal 2, Hall-IC -



Design Data	
Commutation	none
Direction of rotation	Bi-directional
Bearing type	A: Sleeve - B: Sleeve

Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	1.50
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	145.0
Nominal power [W]	$P_N$	16.6
Nominal current [A]	$I_N$	6.0
Nominal force [kN]	$F_N$	1.50
Duty cycle	s3	

**0321 BL**



Sensor data	
Pulses	29
Output channels	1

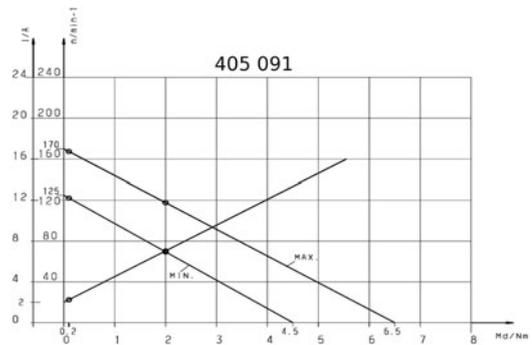
Other data	
Gear ratio	29/1
Gear wheel material	
Suppression components	5,5 $\mu$ H, 47nF, (0,47 $\mu$ F)
Enclosure class	IP40
Weight [kg]	0.880

Remarks: 1 start worm

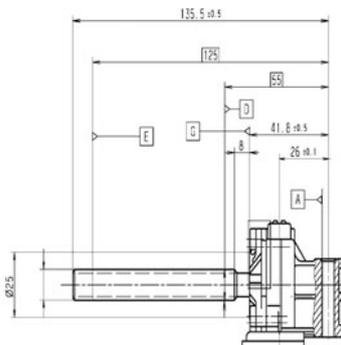
**Motor picture**



**Characteristic curves**

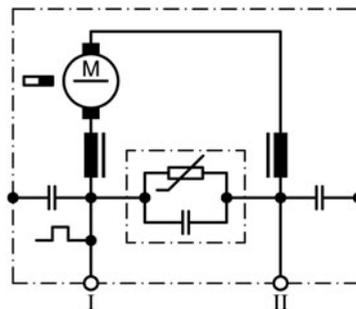


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



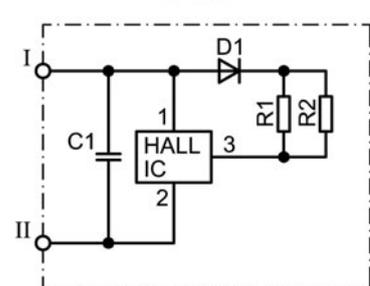
Output spindle: 7 / 16 Stub ACME RH

**S 93**



I Terminal 1  
 II Terminal 5

**S 85**



I Terminal 4, Hall-IC +  
 II Terminal 2, Hall-IC -



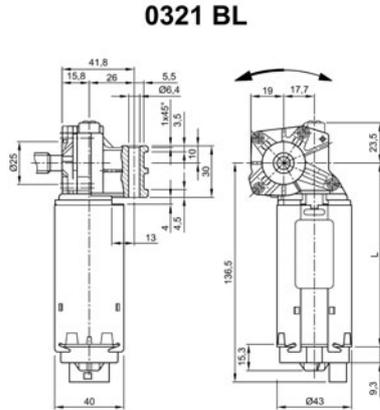
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Sleeve - B: Sleeve

Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	1.50
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	145.0
Nominal power [W]	$P_N$	16.6
Nominal current [A]	$I_N$	6.0
Nominal force [kN]	$F_N$	1.50
Duty cycle	s3	

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	29/1
Gear wheel material	
Suppression components	5,5 $\mu$ H, 47nF, (0,47 $\mu$ F)
Enclosure class	IP40
Weight [kg]	0.880

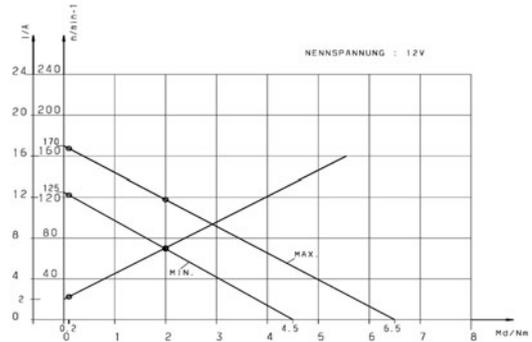
Remarks: 1 start worm



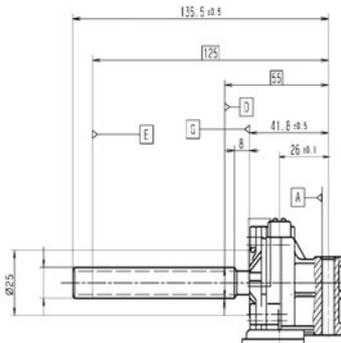
**Motor picture**



**Characteristic curves**

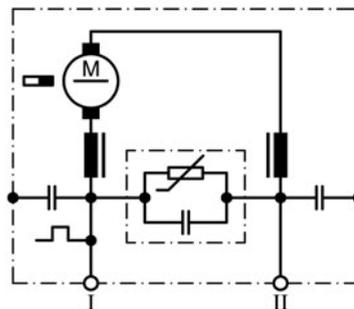


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



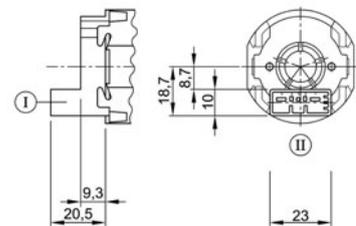
Output spindle: 7 / 16 Stub ACME RH

**S 93**



I Terminal 1  
 II Terminal 5

**K 220**

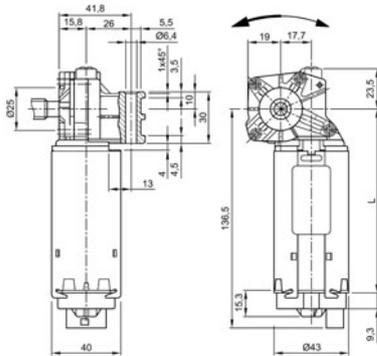


Connector TYCO C-208-15621 (Z) mating with:  
**Connector housing 1379217-3 & cover**  
 1379218-2  
[www.tycoelectronics.com](http://www.tycoelectronics.com)

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Sleeve - B: Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	1.50
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	145.0
Nominal power [W]	$P_N$	17.2
Nominal current [A]	$I_N$	4.5
Nominal force [kN]	$F_N$	1.50
Duty cycle	s3	

**0321 BL**



Sensor data	
Pulses	0
Output channels	0

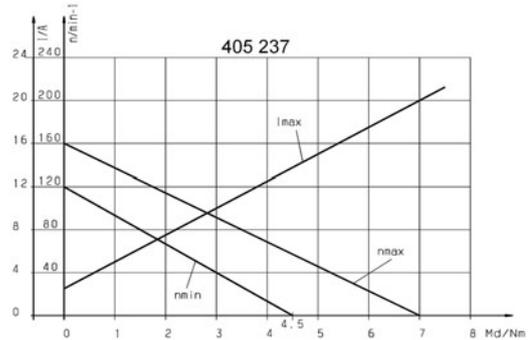
Other data	
Gear ratio	29/1
Gear wheel material	
Suppression components	
Enclosure class	IP40
Weight [kg]	0.880

Remarks: L = 116mm

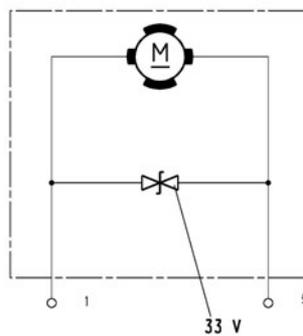
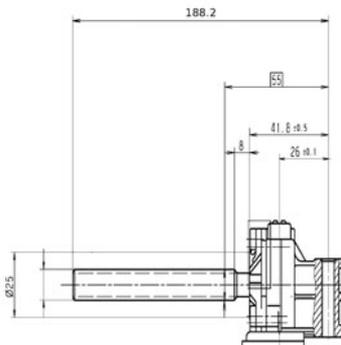
**Motor picture**



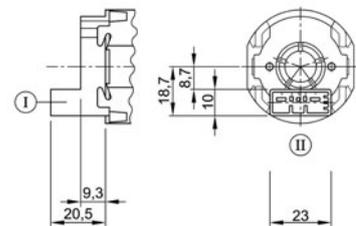
**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**K 220**



Output spindle: 7 / 16 Stub ACME RH

Connector TYCO C-208-15621 (Z) mating with:  
 Connector housing 1379217-3 & cover  
 1379218-2  
[www.tycoelectronics.com](http://www.tycoelectronics.com)





NIDEC MOTORS & ACTUATORS ❖❖❖ MOTOR SERIES

# 0266 (DCK31)

❖❖❖ DC MOTORS WITH WORM GEAR



## ❖❖❖ TECHNICAL DESCRIPTION

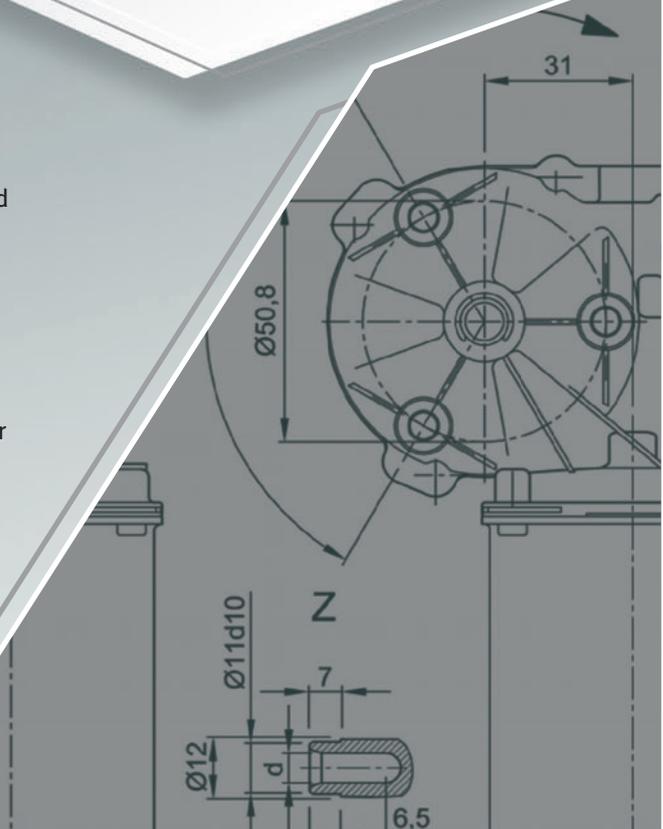
Motorhousing:	deep drawn & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	zinc die cast
Gear wheel material:	plastic, steel
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	connector or leads with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

## ❖❖❖ INDUSTRIAL APPLICATION

Door & gate openers, pumps, lubricating technology, appliance, linear actuators

## ❖❖❖ AUTOMOTIVE APPLICATION

Trunk & tailgate opening & closing



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:ball - B:sleeve

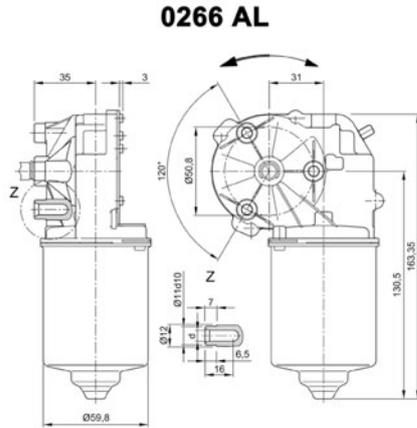
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	65.0
Nominal power [W]	$P_N$	25.0
Nominal current [A]	$I_N$	4.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	69
Output channels	1

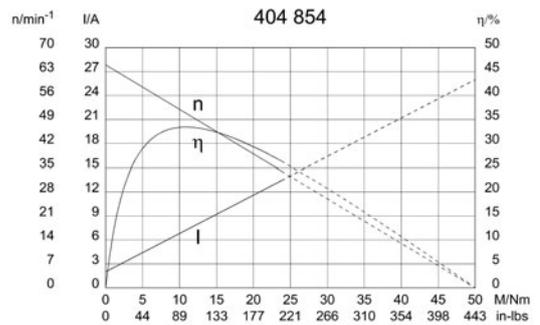
Other data	
Gear ratio	69/1
Gear wheel material	plastic
Suppression components	6 $\mu\text{H}$
Enclosure class	IP 30
Weight [kg]	1.250

Remarks: d=for selftapping screw M6 DIN ISO 965-2

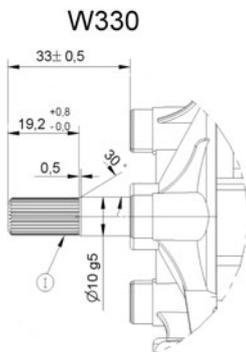
**Characteristic curves**



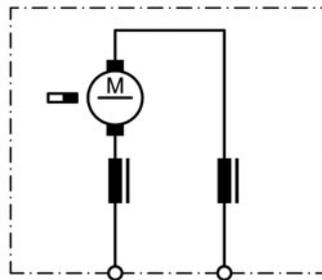
**Motor picture**



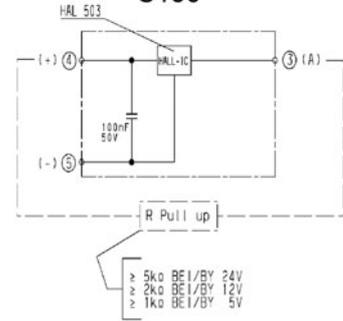
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 27**



**S150**



I serration (rolled): no of teeth 28, pitch circle dia 9 mm, tip circle dia 9.6 mm, root circle dia 8.26 mm space width angle 60° - go/no go gauge Frenco 33906 - www.frenco.de



**Design Data**

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: ball - B:sleeve

**Performance data**

Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	66.0
Nominal power [W]	$P_N$	25.4
Nominal current [A]	$I_N$	4.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

**Sensor data**

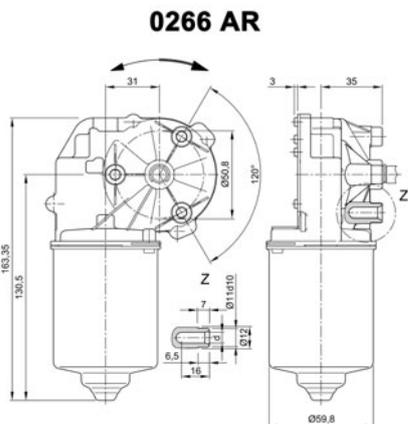
Pulses	0
Output channels	0

**Other data**

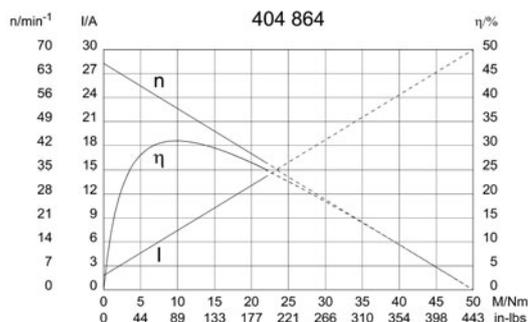
Gear ratio	69/1
Gear wheel material	plastic
Suppression components	3,5 $\mu$ H, 1 $\mu$ F
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

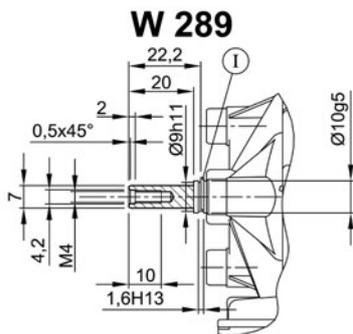
**Characteristic curves**



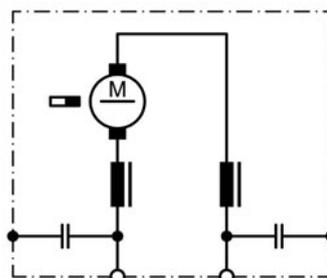
**Motor picture**



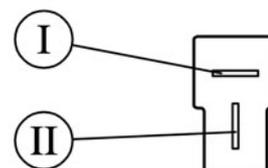
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 30**



**K 320**



I Circlip

Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 [www.tycoelectronics.com](http://www.tycoelectronics.com)

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

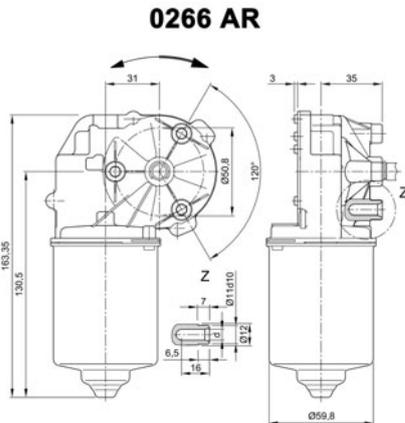
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	75.0
Nominal power [W]	$P_N$	28.9
Nominal current [A]	$I_N$	5.5
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	69
Output channels	2

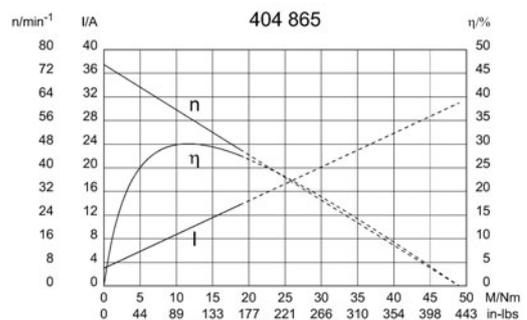
Other data	
Gear ratio	69/1
Gear wheel material	Plastic
Suppression components	6.0 $\mu$ H, 1nF
Enclosure class	IP30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

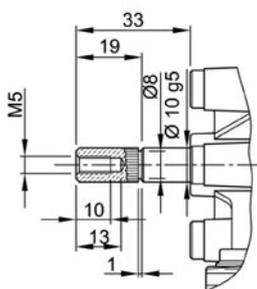
**Characteristic curves**



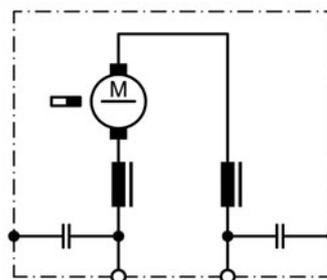
**Motor picture**



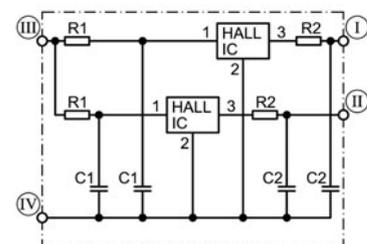
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 30**



**S 141**



- I Hall-IC A1, terminal 3
- II Hall-IC A2, terminal 4
- III Hall-IC +, terminal 5
- IV Hall-IC -, terminal 6



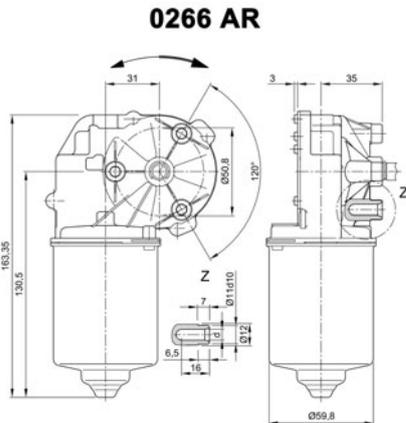
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:ball - B:sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	64.0
Nominal power [W]	$P_N$	24.4
Nominal current [A]	$I_N$	4.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	69/1
Gear wheel material	plastic
Suppression components	6 $\mu$ H, 1nF
Enclosure class	IP 30
Weight [kg]	1.216

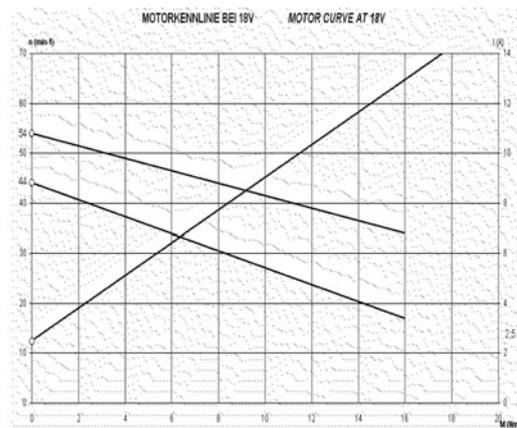
Remarks: d = for thread-forming screw M6 DIN ISO 965-2



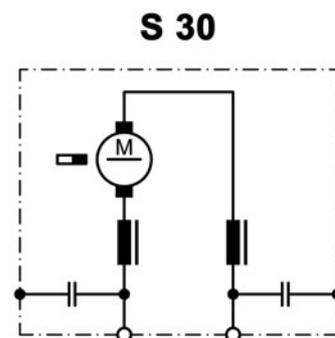
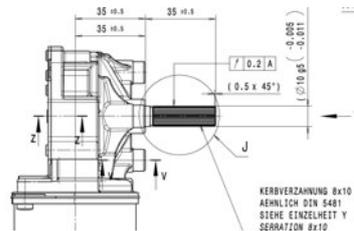
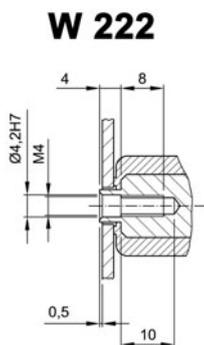
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



! Only for connection of encoder



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: ball - B: sleeve

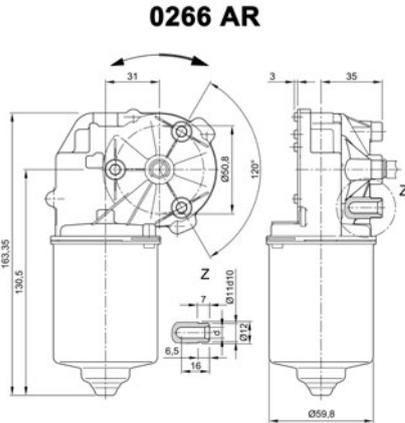
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	6.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	35.0
Nominal power [W]	$P_N$	19.2
Nominal current [A]	$I_N$	3.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

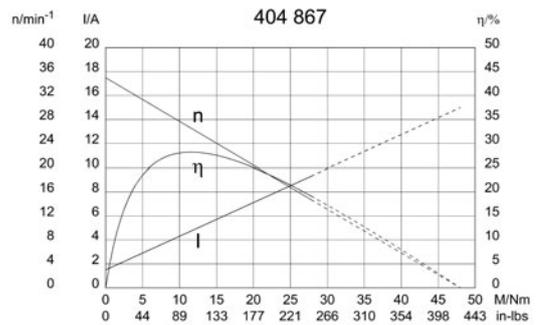
Other data	
Gear ratio	69/1
Gear wheel material	plastic
Suppression components	$6\mu\text{H}$ , $1\text{nF}$
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

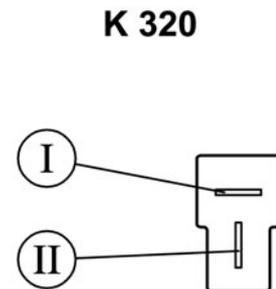
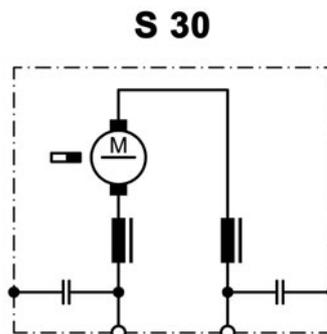
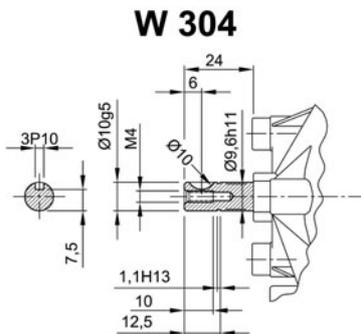
**Characteristic curves**



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 [www.tycoelectronics.com](http://www.tycoelectronics.com)



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

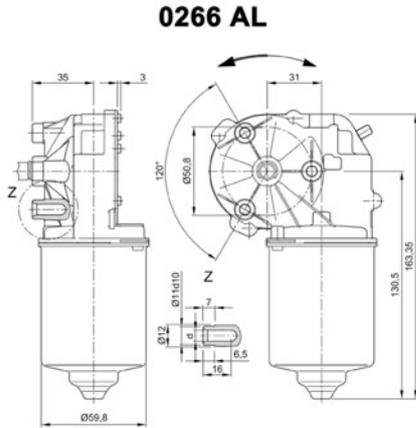
Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	30.0
Nominal power [W]	$P_N$	10.8
Nominal current [A]	$I_N$	3.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

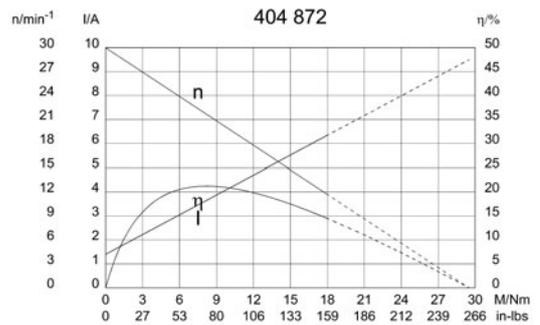
Other data	
Gear ratio	69/1
Gear wheel material	plastic
Suppression components	6 $\mu$ H
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

**Characteristic curves**

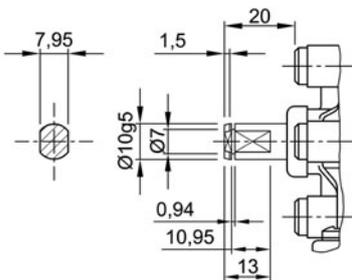


**Motor picture**

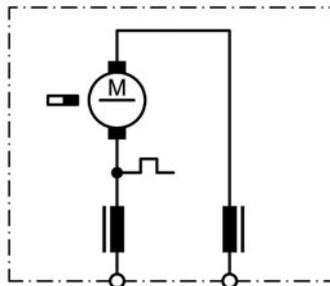


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

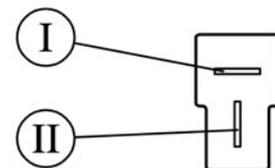
**W 252**



**S 25**



**K 320**



Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 [www.tycoelectronics.com](http://www.tycoelectronics.com)

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

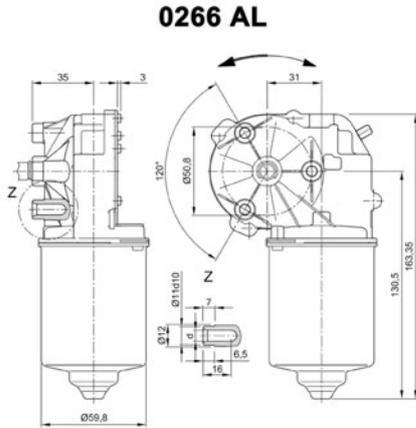
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	160.0
Nominal power [W]	$P_N$	30.9
Nominal current [A]	$I_N$	4.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	1
Output channels	2

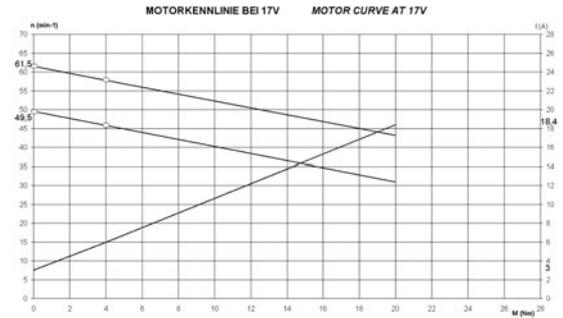
Other data	
Gear ratio	53/2
Gear wheel material	plastic
Suppression components	6 $\mu$ H, 1nF
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d= for thread forming screw M6 DIN ISO 965-2

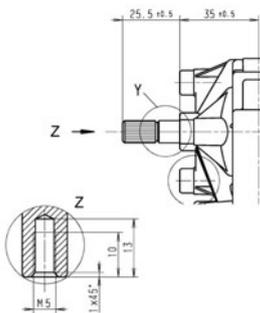
**Characteristic curves**



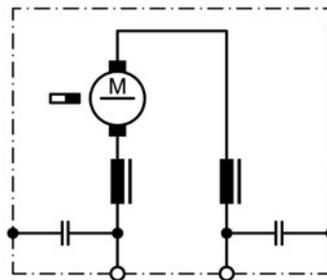
**Motor picture**



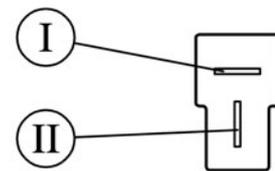
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 30**



**K 320**



I serration (rolled): **No teeth 28, pitch circle dia 9 mm, tip circle dia 9.6 mm, root circle dia 8.26 mm space width angle 60° - go/no go gauge** Frenco 33906 - [www.frenco.de](http://www.frenco.de)

Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 [www.tycoelectronics.com](http://www.tycoelectronics.com)

**Design Data**

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B:Sleeve

**Performance data**

Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	3.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	14.0
Nominal power [W]	$P_N$	3.60
Nominal current [A]	$I_N$	1.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

**Sensor data**

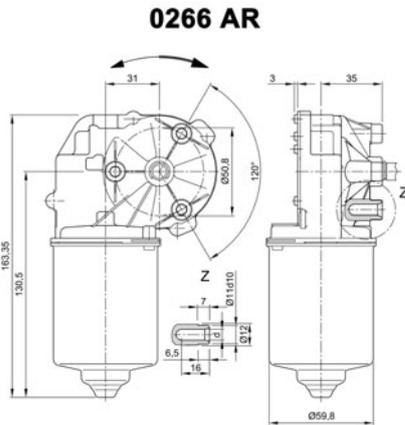
Pulses	234
Output channels	1

**Other data**

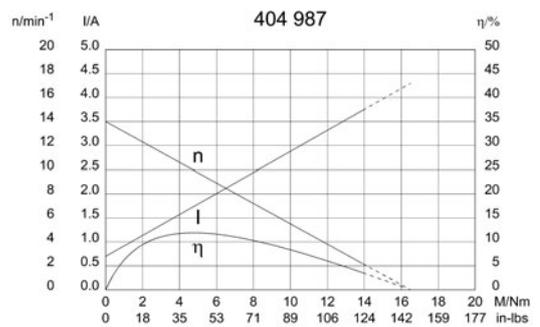
Gear ratio	78/1
Gear wheel material	bronze
Suppression components	$6\mu\text{H}, 1\text{nF}$
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

**Characteristic curves**

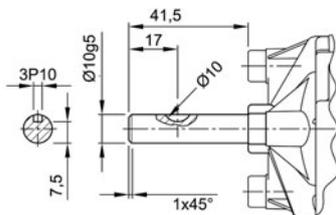


**Motor picture**

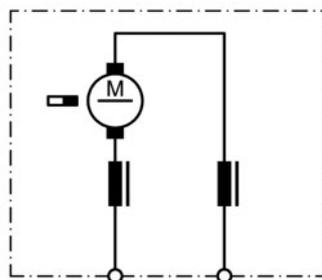


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

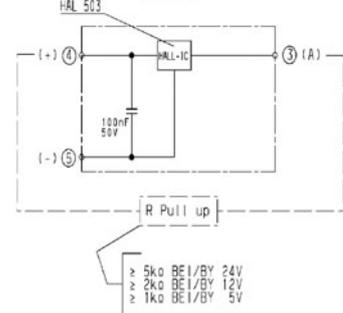
**W 327**



**S 27**



**S150**













Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball- B:Sleeve

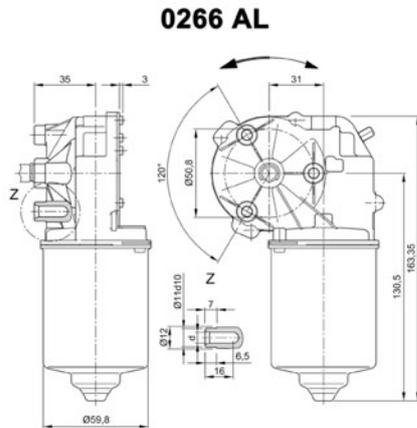
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	1.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	270.0
Nominal power [W]	$P_N$	24.5
Nominal current [A]	$I_N$	3.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	10.25
Output channels	1

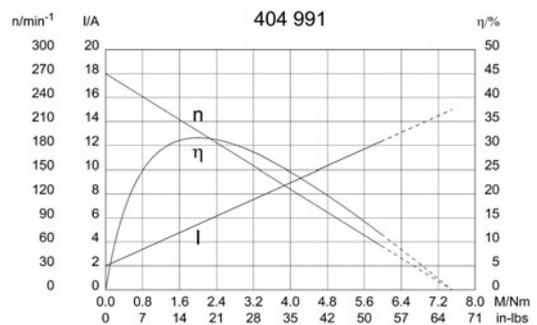
Other data	
Gear ratio	41/4
Gear wheel material	plastic
Suppression components	6 $\mu$ H, 1nF
Enclosure class	IP 30
Weight [kg]	1.250

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

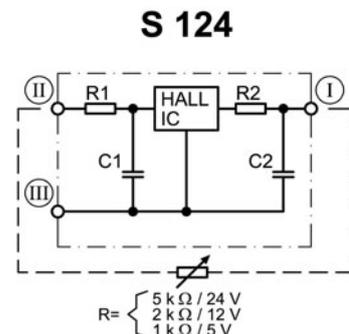
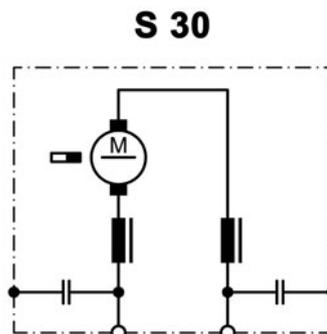
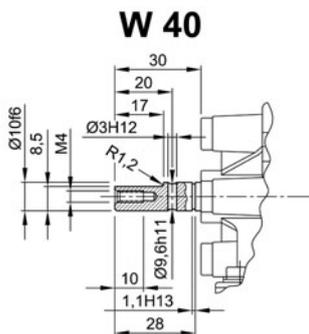
**Characteristic curves**



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



- I Terminal 3, A
- II Terminal 4, +
- III Terminal 5, -



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

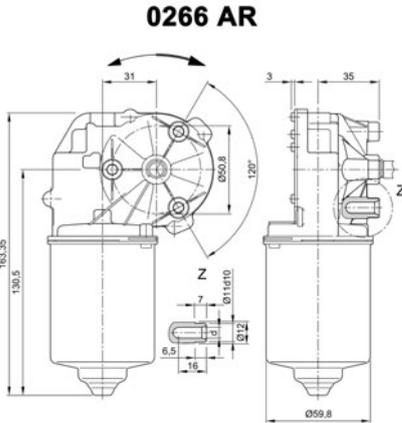
Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	21.0
Nominal power [W]	$P_N$	7.79
Nominal current [A]	$I_N$	3.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

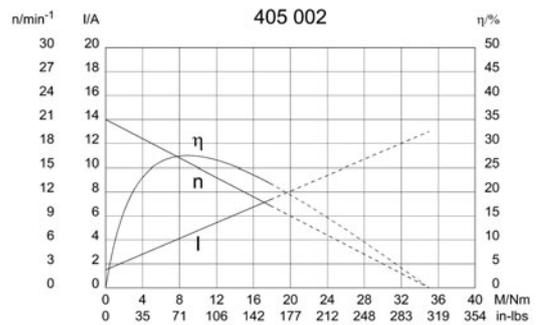
Other data	
Gear ratio	69/1
Gear wheel material	plastic
Suppression components	3,5 $\mu$ H, 1 $\mu$ F
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

**Characteristic curves**

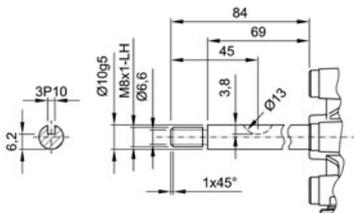


**Motor picture**

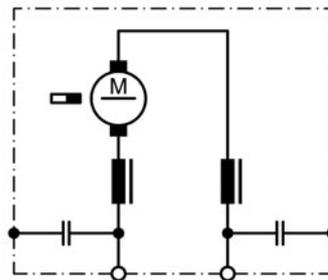


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

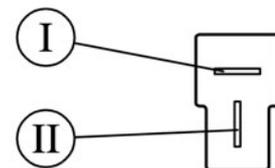
**W 120**



**S 30**



**K 320**



Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 [www.tycoelectronics.com](http://www.tycoelectronics.com)

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

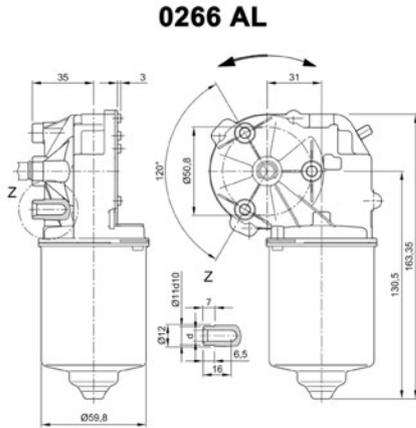
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	65.0
Nominal power [W]	$P_N$	25.0
Nominal current [A]	$I_N$	3.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	69
Output channels	2

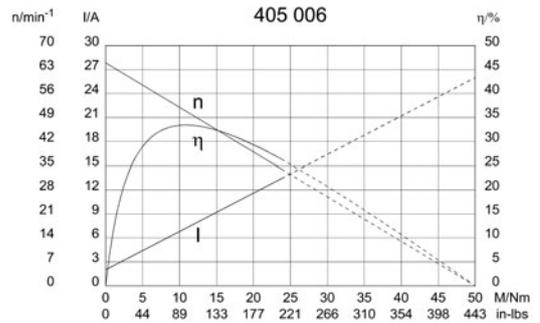
Other data	
Gear ratio	69/1
Gear wheel material	plastic
Suppression components	6 $\mu$ H
Enclosure class	IP 30
Weight [kg]	1.250

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

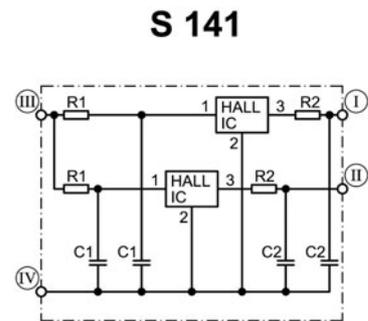
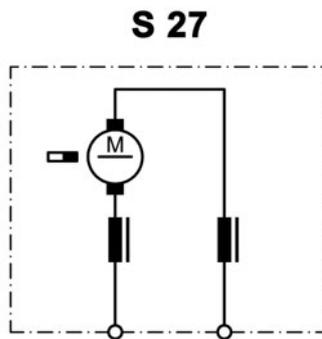
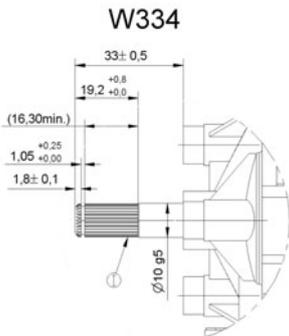
**Characteristic curves**



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



I serration (rolled): no of teeth 28, pitch circle dia 9 mm, tip circle dia 9.6 mm, root circle dia 8.26 mm space width angle 60° - go/no go gauge Frenco 33906 - www.frenco.de

I Hall-IC A1, terminal 3  
 II Hall-IC A2, terminal 4  
 III Hall-IC +, terminal 5  
 IV Hall-IC -, terminal 6







Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

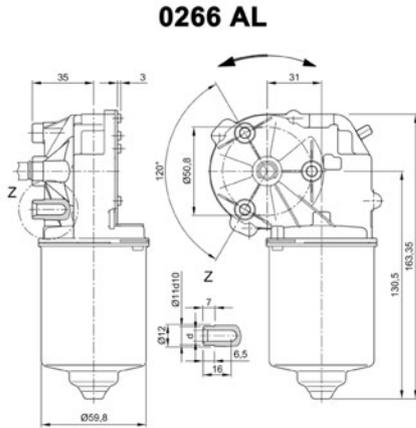
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	55.0
Nominal power [W]	$P_N$	21.5
Nominal current [A]	$I_N$	5.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	78
Output channels	1

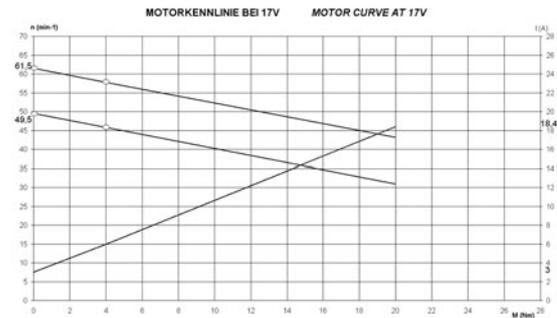
Other data	
Gear ratio	78/1
Gear wheel material	plastic
Suppression components	6 $\mu$ H, 1nF
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d= for thread forming screw M6 DIN ISO 965-2

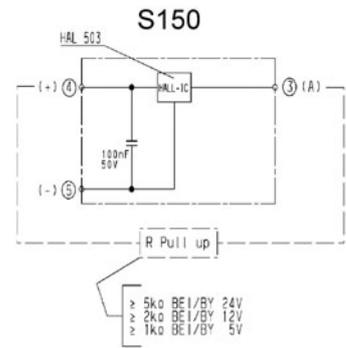
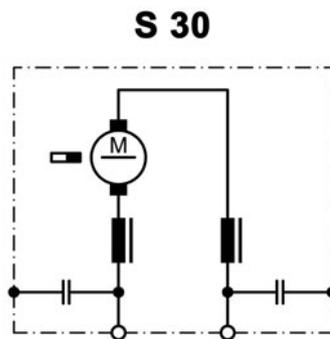
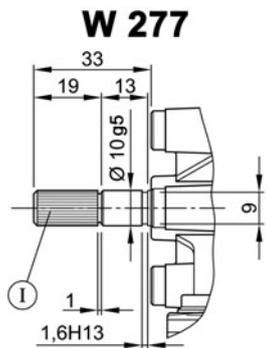
**Characteristic curves**



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



I serration (rolled)  
 no of teeth 28, pitch circle dia 9 mm, tip circle dia 9.6 mm, root circle dia 8.26 mm space width angle 60°  
 goes with go/no go gauge Frenco 33906  
 www.frenco.de



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

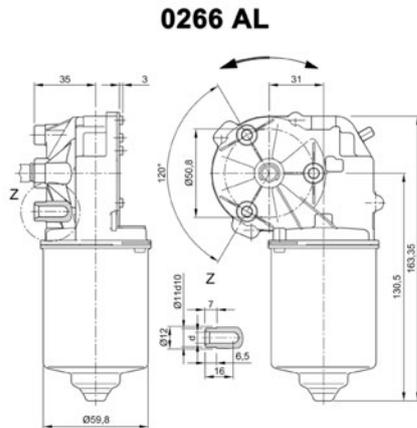
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	90.0
Nominal power [W]	$P_N$	35.9
Nominal current [A]	$I_N$	5.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	69
Output channels	1

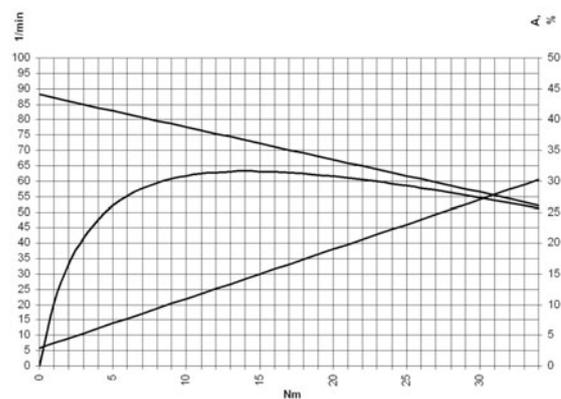
Other data	
Gear ratio	69/1
Gear wheel material	plastic
Suppression components	$6\mu\text{H}$ , $1\text{nF}$
Enclosure class	IP 30
Weight [kg]	1.210

Remarks: d=for thread forming screws M6 DIN-ISO 965-2

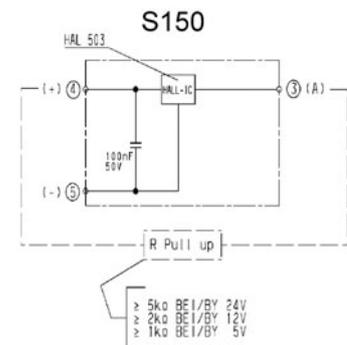
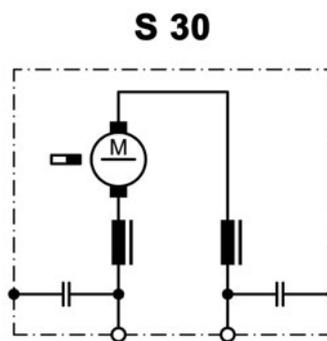
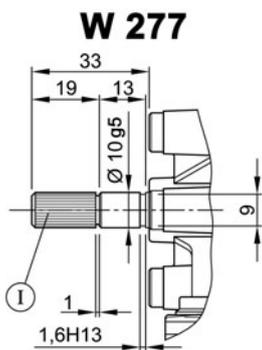
**Characteristic curves**



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



I serration (rolled)  
 no of teeth 28, pitch circle dia 9 mm, tip circle dia 9.6 mm, root circle dia 8.26 mm space width angle 60°  
 goes with go/no go gauge Frenco 33906  
 www.frenco.de



### Design Data

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

### Performance data

Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	120.0
Nominal power [W]	$P_N$	22.0
Nominal current [A]	$I_N$	4.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

### Sensor data

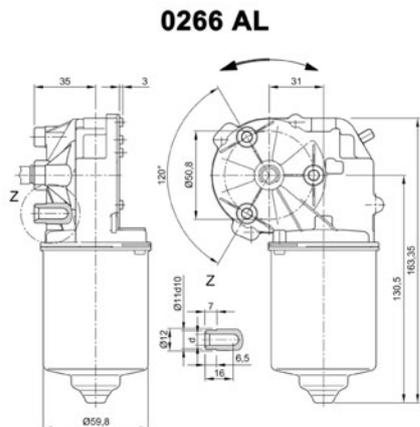
Pulses	79.5
Output channels	1

### Other data

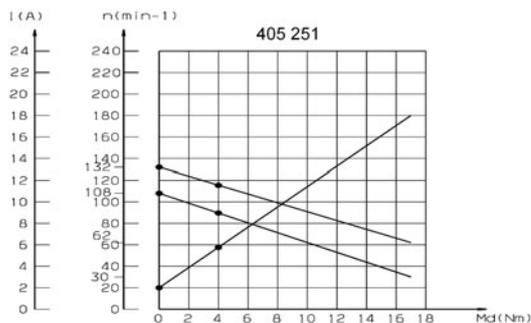
Gear ratio	53/2
Gear wheel material	Plastic
Suppression components	$6.0\mu\text{H}$ , $1\text{nF}$
Enclosure class	IP30
Weight [kg]	1.210

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

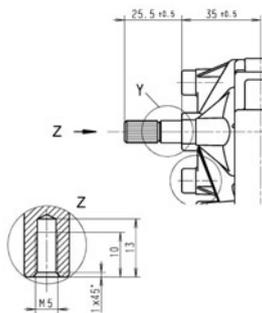
### Characteristic curves



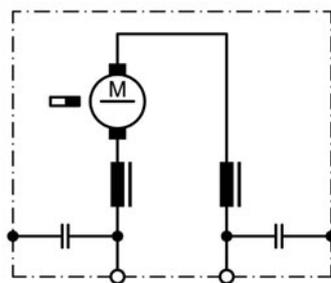
### Motor picture



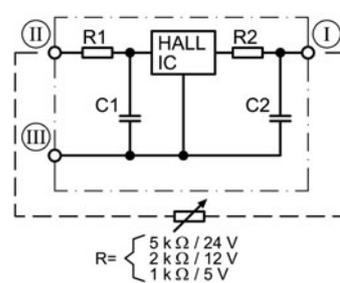
### Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



### S 30



### S 124

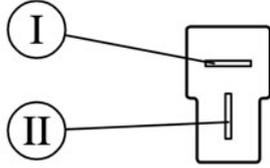


I serration (rolled): **No teeth 28, pitch circle dia 9 mm, tip circle dia 9.6 mm, root circle dia 8.26 mm space width angle 60° - go/no go gauge** Frenco 33906 - [www.frengo.de](http://www.frengo.de)

I Terminal 3, A  
 II Terminal 4, +  
 III Terminal 5, -

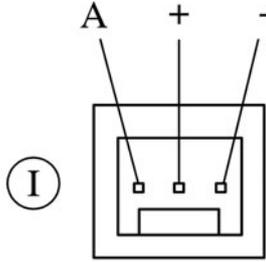
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

**K 320**



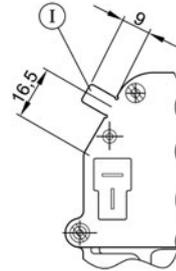
Flat plug (DIN 46244) 6.3x0.8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0.5-1.5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 [www.tycoelectronics.com](http://www.tycoelectronics.com)

**K 325**



MAS-CON Solder tail MLAS 100-3435 mating with end connector CE100F-22-xx-x-x or CEP100 F-22-xx-x-x [www.itwpancon.com](http://www.itwpancon.com)

**K 312**



Ground connection 6.3 x 0.8 DIN 46 244, d=0.9-0.1mm, mating with receptacle for tab, conductor cross section 0.5-1.5 sqmm/20-16 AWG, part# RSB8240.158 F 6.3-1.5 [www.stocko.de](http://www.stocko.de)

**Notes**

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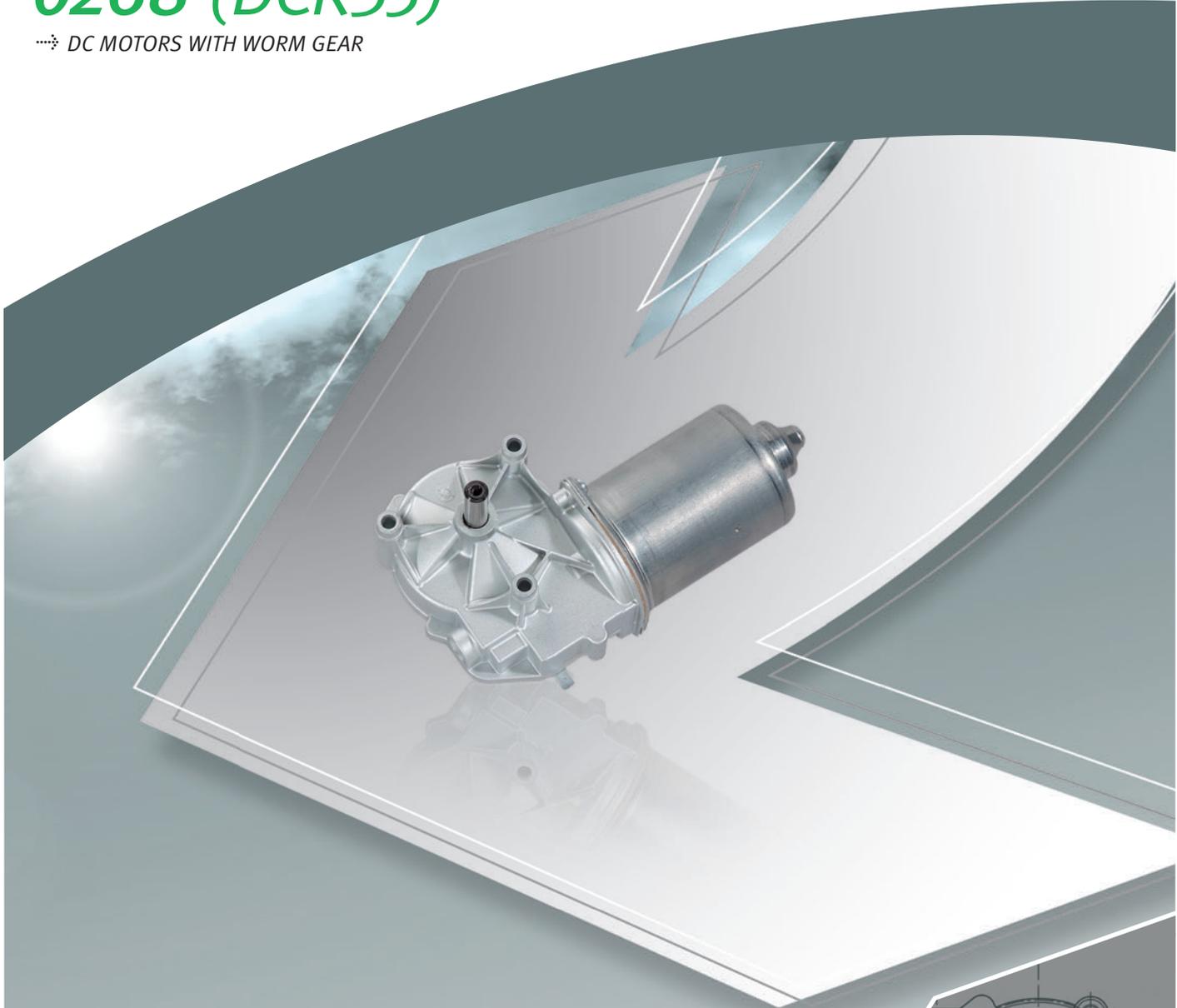
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NIDEC MOTORS & ACTUATORS ❖❖❖ MOTOR SERIES

# 0268 (DCK35)

❖❖❖ DC MOTORS WITH WORM GEAR



## ❖❖❖ TECHNICAL DESCRIPTION

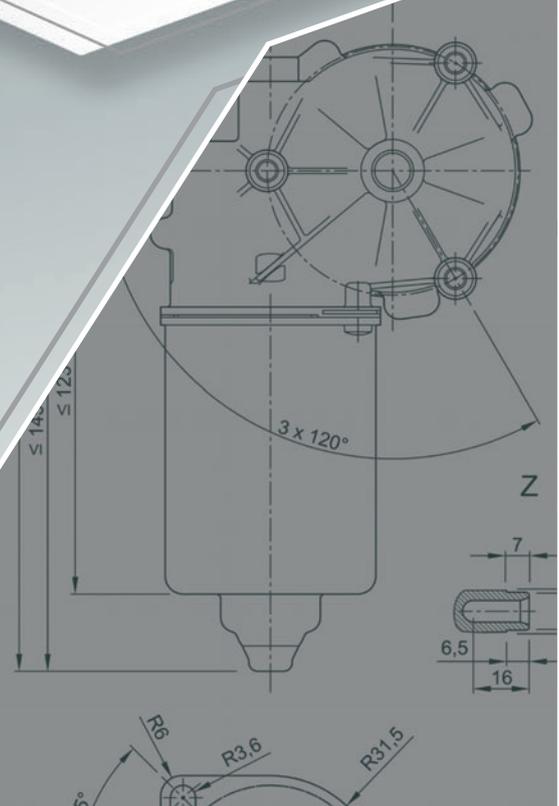
Motorhousing:	deep drawn & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	zinc die cast
Gear wheel material:	plastic
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

## ❖❖❖ INDUSTRIAL APPLICATION

Home automation, machine construction

## ❖❖❖ AUTOMOTIVE APPLICATION

Trunk & tailgate opening & closing



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

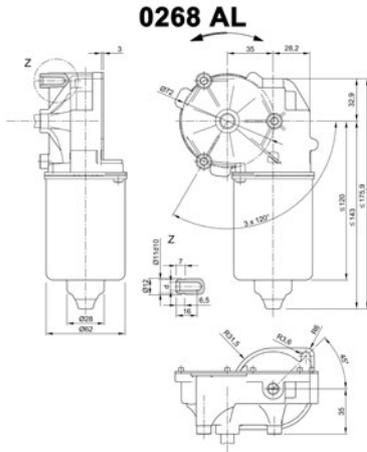
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	5.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	62.0
Nominal power [W]	$P_N$	29.8
Nominal current [A]	$I_N$	5.5
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	63
Output channels	2

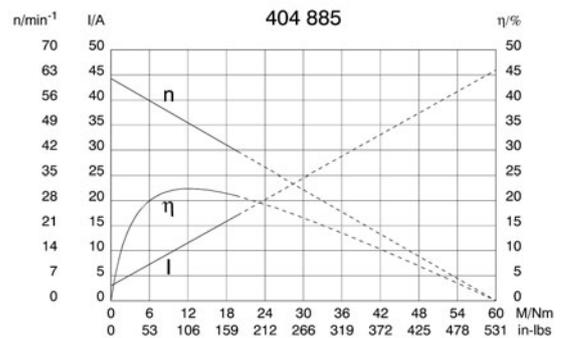
Other data	
Gear ratio	63/1
Gear wheel material	plastic
Suppression components	3,5 $\mu$ H
Enclosure class	IP 30
Weight [kg]	1.250

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

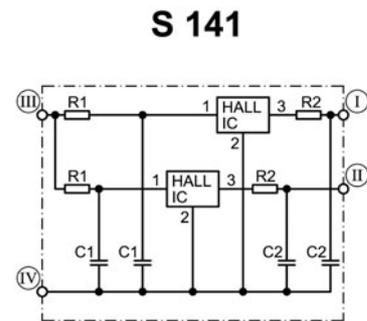
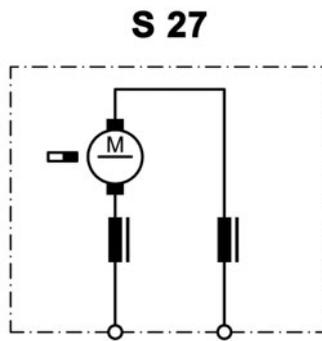
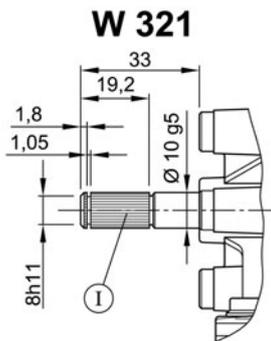
**Characteristic curves**



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

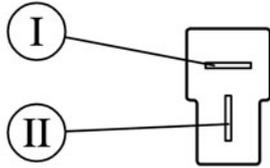


I serration (rolled): no of teeth 28, pitch circle dia 9 mm, tip circle dia 9.6 mm, root circle dia 8.26 mm space width angle 60°- go/no go gauge Frenco 33906 - [www.frenco.de](http://www.frenco.de)

I Hall-IC A1, terminal 3  
 II Hall-IC A2, terminal 4  
 III Hall-IC +, terminal 5  
 IV Hall-IC -, terminal 6

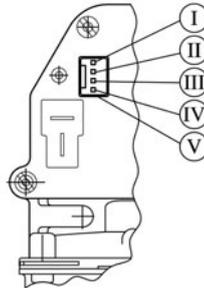
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

**K 320**



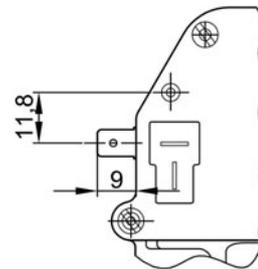
Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907 & Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 [www.tycoelectronics.com](http://www.tycoelectronics.com)

**K 319**



- I Hall-IC A1, terminal 3
- II Hall-IC A2, terminal 4
- III Hall-IC +, terminal 5
- IV Hall-IC -, terminal 6
- V Mating connector: Panduit CE100 F22 - 04

**K 314**



- I Ground connection  
Blade terminal 6.3 x 0.8 DIN 46 244

**Notes**

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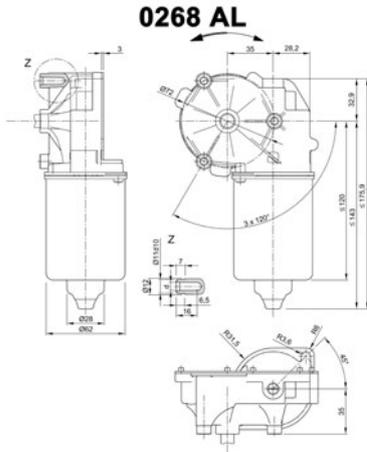
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	6.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	50.0
Nominal power [W]	$P_N$	28.7
Nominal current [A]	$I_N$	4.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	63/1
Gear wheel material	plastic
Suppression components	3,5 $\mu$ H, 1nF
Enclosure class	IP 30
Weight [kg]	1.250

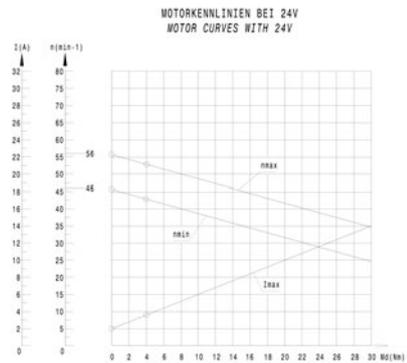
Remarks: d=for thread forming screws M6 DIN ISO 965-2



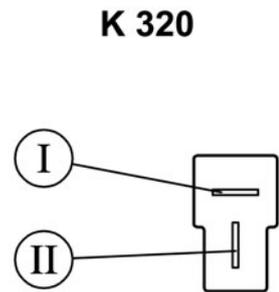
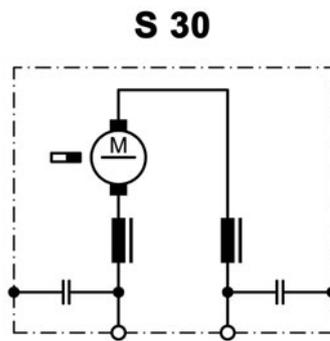
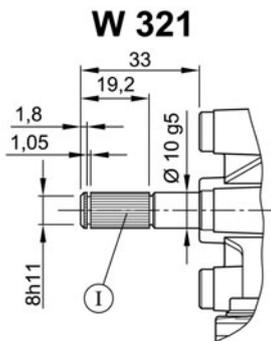
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



I serration (rolled): no of teeth 28, pitch circle dia 9 mm, tip circle dia 9.6 mm, root circle dia 8.26 mm space width angle 60°- go/no go gauge Frenco 33906 - [www.frenco.de](http://www.frenco.de)

Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 [www.tycoelectronics.com](http://www.tycoelectronics.com)

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

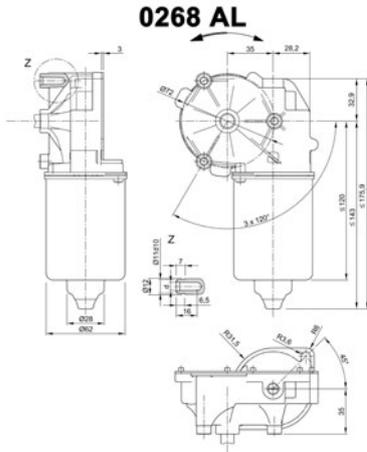
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	5.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	70.0
Nominal power [W]	$P_N$	33.5
Nominal current [A]	$I_N$	4.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

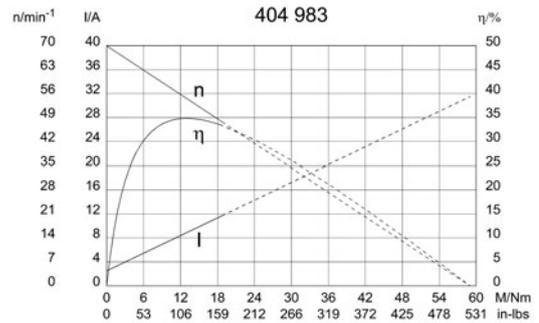
Other data	
Gear ratio	55/1
Gear wheel material	plastic
Suppression components	3,5 $\mu$ H, 1nF
Enclosure class	IP 30
Weight [kg]	1.250

Remarks: d = for thread-forming screw M6 DIN ISO 965-2

**Characteristic curves**

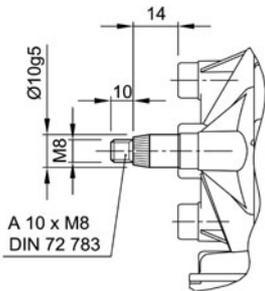


**Motor picture**

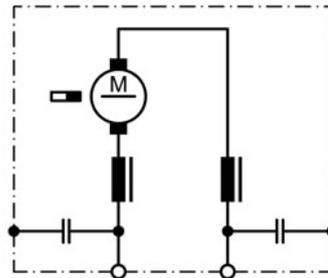


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

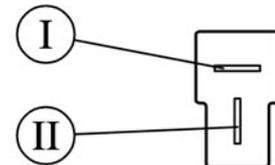
**W 305**



**S 30**



**K 320**



Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 [www.tycoelectronics.com](http://www.tycoelectronics.com)

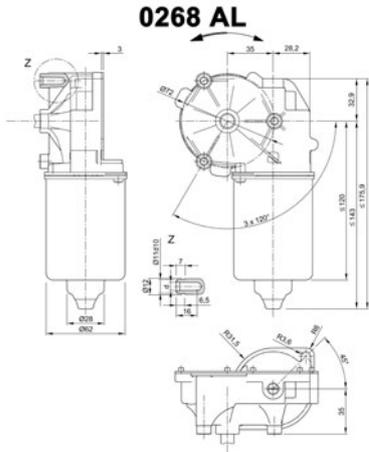
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	6.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	60.0
Nominal power [W]	$P_N$	29.3
Nominal current [A]	$I_N$	7.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	63/1
Gear wheel material	plastic
Suppression components	3,5 $\mu$ H
Enclosure class	IP 30
Weight [kg]	1.376

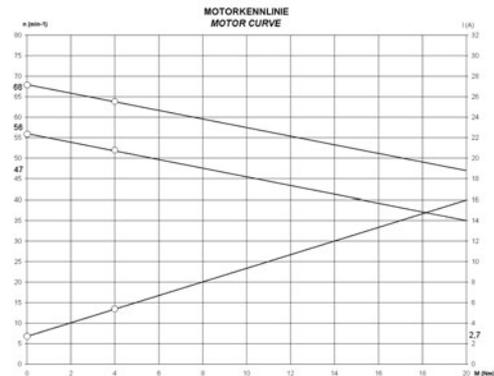
Remarks:



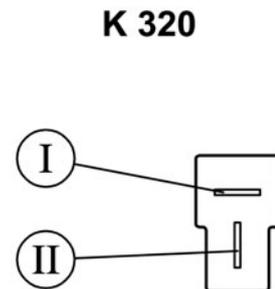
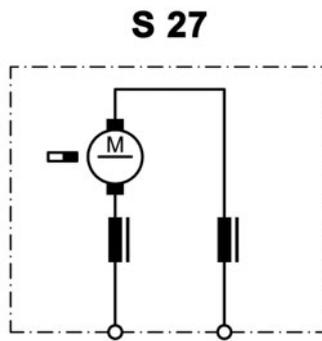
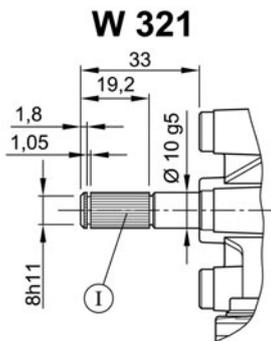
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

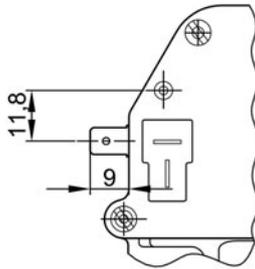


I serration (rolled): no of teeth 28, pitch circle dia 9 mm, tip circle dia 9.6 mm, root circle dia 8.26 mm space width angle 60°- go/no go gauge Frenco 33906 - [www.frenco.de](http://www.frenco.de)

Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 [www.tycoelectronics.com](http://www.tycoelectronics.com)

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

**K 314**



I Ground connection  
 Blade terminal 6.3 x 0.8 DIN 46 244

**Notes**

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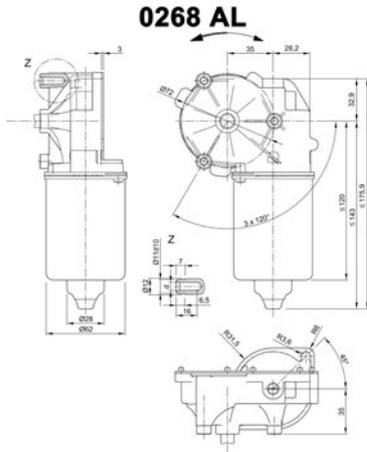
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	8.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	75.0
Nominal power [W]	$P_N$	37.7
Nominal current [A]	$I_N$	7.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	63
Output channels	1

Other data	
Gear ratio	63/1
Gear wheel material	Plastic
Suppression components	3.5 $\mu\text{H}$
Enclosure class	IP30
Weight [kg]	1.250

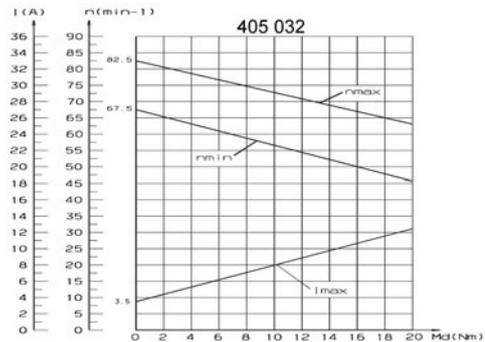
Remarks: d = for thread-forming screw M6 DIN ISO 965-2



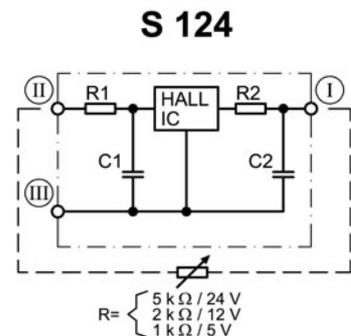
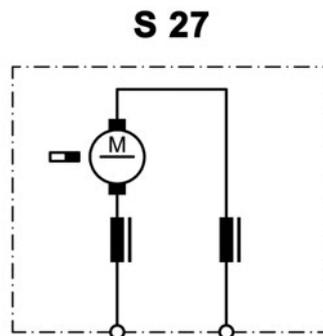
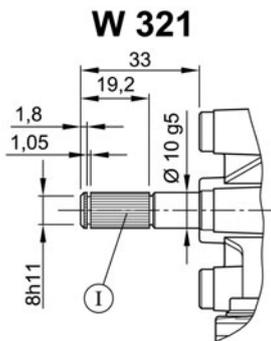
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



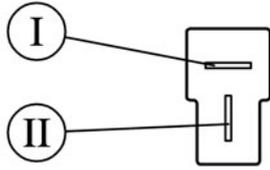
I serration (rolled): no of teeth 28, pitch circle dia 9 mm, tip circle dia 9.6 mm, root circle dia 8.26 mm space width angle 60°- go/no go gauge Frenco 33906 - [www.frenco.de](http://www.frenco.de)

I Terminal 3, A  
 II Terminal 4, +  
 III Terminal 5, -

$R = \begin{cases} 5 \text{ k}\Omega / 24 \text{ V} \\ 2 \text{ k}\Omega / 12 \text{ V} \\ 1 \text{ k}\Omega / 5 \text{ V} \end{cases}$

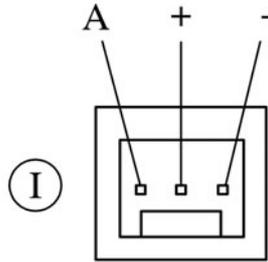
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

**K 320**



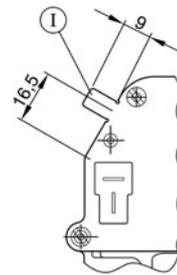
Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907 & Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 [www.tycoelectronics.com](http://www.tycoelectronics.com)

**K 325**



MAS-CON Solder tail MLAS 100-3435 mating with end connector CE100F-22-xx-x-x or CEP100 F-22-xx-x-x [www.itwpancon.com](http://www.itwpancon.com)

**K 312**



Ground connection 6.3 x 0.8 DIN 46 244, d=0.9-0.1mm, mating with receptacle for tab, conductor cross section 0.5-1.5 sqmm/20-16 AWG, part# RSB8240.158 F 6.3-1.5 [www.stocko.de](http://www.stocko.de)

**Notes**

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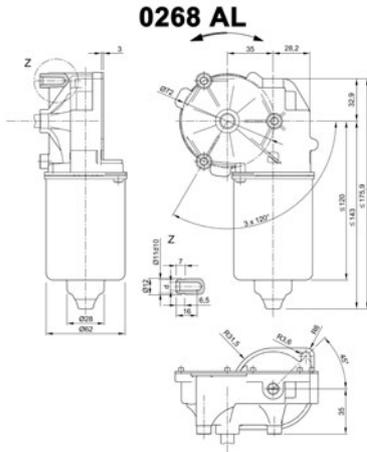
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	8.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	53.0
Nominal power [W]	$P_N$	39.2
Nominal current [A]	$I_N$	6.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	91
Output channels	1

Other data	
Gear ratio	91/1
Gear wheel material	plastic
Suppression components	3,5 $\mu$ H, 1nF
Enclosure class	IP 30
Weight [kg]	1.250

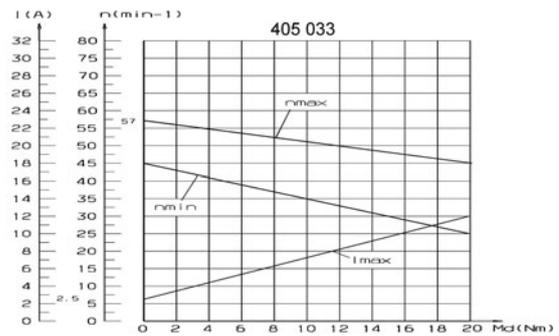
Remarks: d=for thread forming screws M6 DIN ISO 965-2



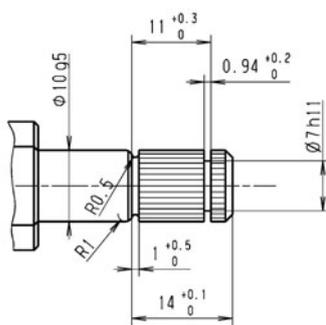
### Motor picture



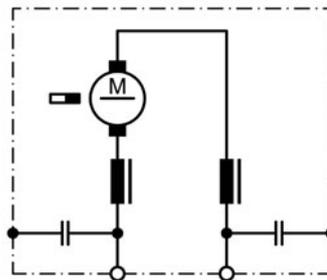
### Characteristic curves



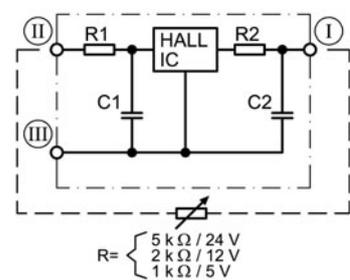
### Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



### S 30



### S 124

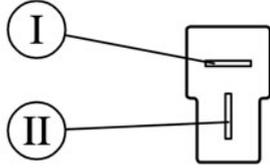


**Splines:** 8 x 10 (according to DIN 5481)  
 Output shaft length = 28mm

I Terminal 3, A  
 II Terminal 4, +  
 III Terminal 5, -

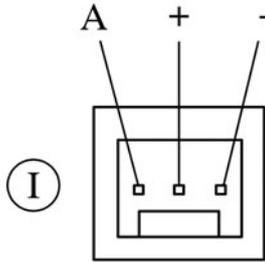
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

**K 320**



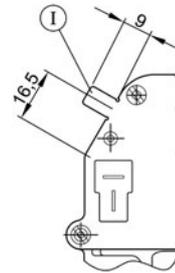
Flat plug (DIN 46244) 6,3x0,8 mating with receptacle housing part#180907, drwg# C-180907& Receptacles for tabs, conductor cross section 0,5-1,5 sqmm (20-18AWG) part# 925603-x, drwg# 925603 [www.tycoelectronics.com](http://www.tycoelectronics.com)

**K 325**



MAS-CON Solder tail MLAS 100-3435 mating with end connector CE100F-22-xx-x-x or CEP100 F-22-xx-x-x [www.itwpancon.com](http://www.itwpancon.com)

**K 312**



Ground connection 6.3 x 0.8 DIN 46 244, d=0.9-0.1mm, mating with receptacle for tab, conductor cross section 0.5-1.5 sqmm/20-16 AWG, part# RSB8240.158 F 6.3-1.5 [www.stocko.de](http://www.stocko.de)

**Notes**

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Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

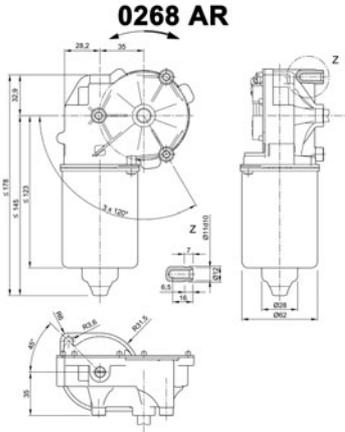
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	6.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	60.0
Nominal power [W]	$P_N$	35.0
Nominal current [A]	$I_N$	6.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	91
Output channels	1

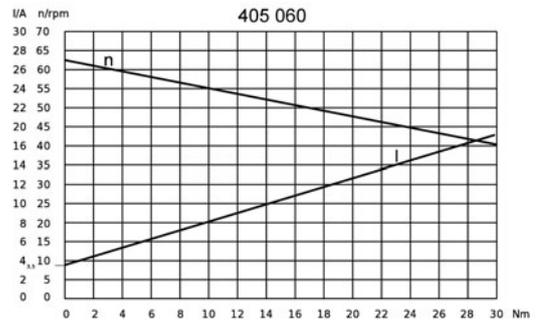
Other data	
Gear ratio	91/1
Gear wheel material	plastic
Suppression components	3,5 $\mu$ , 1nF
Enclosure class	IP 30
Weight [kg]	0.000

Remarks: d=for thread forming screw M6 DIN ISO 964-2

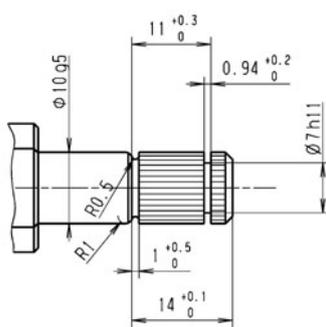
**Characteristic curves**



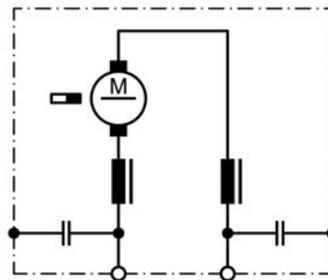
**Motor picture**



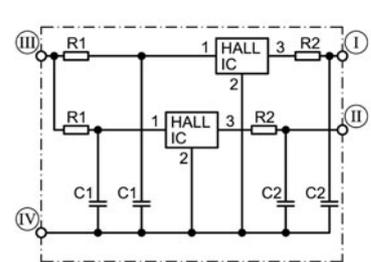
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 30**



**S 141**

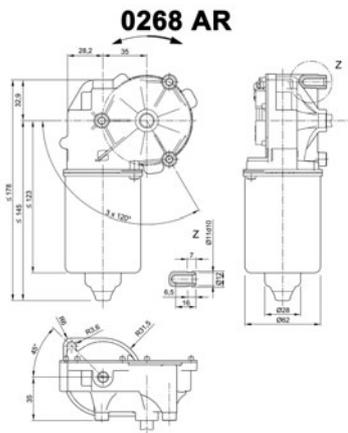


**Splines:** 8 x 10 (according to DIN 5481)  
 Output shaft length = 28mm

- I Hall-IC A1, terminal 3
- II Hall-IC A2, terminal 4
- III Hall-IC +, terminal 5
- IV Hall-IC -, terminal 6



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve



### Motor picture



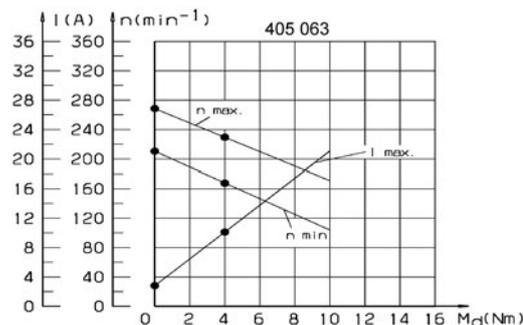
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	3.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	240.0
Nominal power [W]	$P_N$	65.6
Nominal current [A]	$I_N$	8.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	17.5
Output channels	2

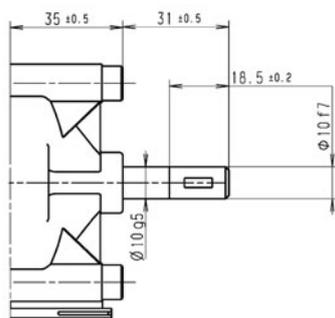
Other data	
Gear ratio	70/4
Gear wheel material	plastic
Suppression components	6 $\mu$ H, 1nF
Enclosure class	IP 30
Weight [kg]	1.366

Remarks: d=for thread forming screw M6 DIN ISO 965-2

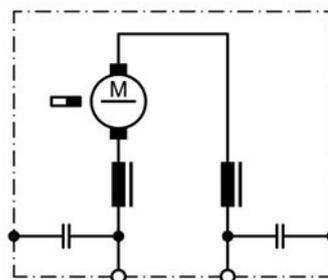
### Characteristic curves



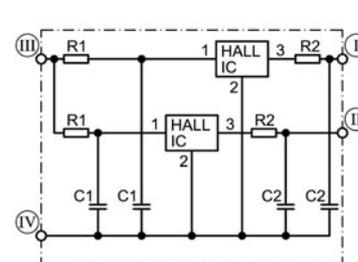
### Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



S 30



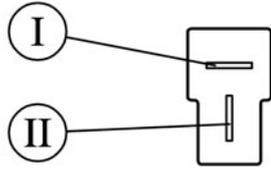
S 141



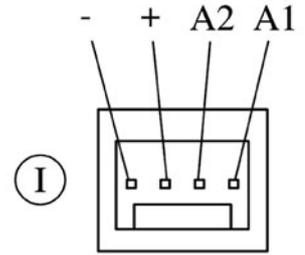
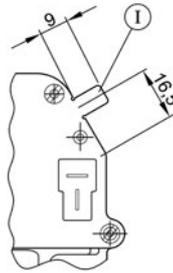
- I Hall-IC A1, terminal 3
- II Hall-IC A2, terminal 4
- III Hall-IC +, terminal 5
- IV Hall-IC -, terminal 6

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

**K 320**



**K 321**



Flat plug (DIN 46244) 6,3x0,8 mating with  
 receptacle housing part#180907, drwg#  
 C-180907& Receptacles for tabs, conductor cross  
 section 0,5-1,5 sqmm (20-18AWG) part# 925603-  
 x, drwg# 925603 [www.tycoelectronics.com](http://www.tycoelectronics.com)

I Ground connection  
 Blade terminal 6.3 x 0.8 DIN 46 244

I Mating connector: Panduit CE100 F22-04

**Notes**

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**Notes**

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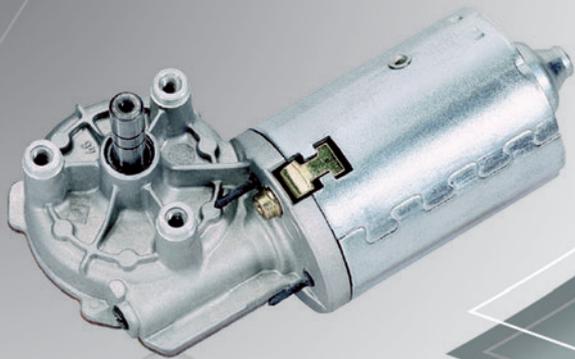
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NIDEC MOTORS & ACTUATORS ❖❖❖ MOTOR SERIES

# 0270 (SWMK)

❖❖❖ DC MOTORS WITH WORM GEAR

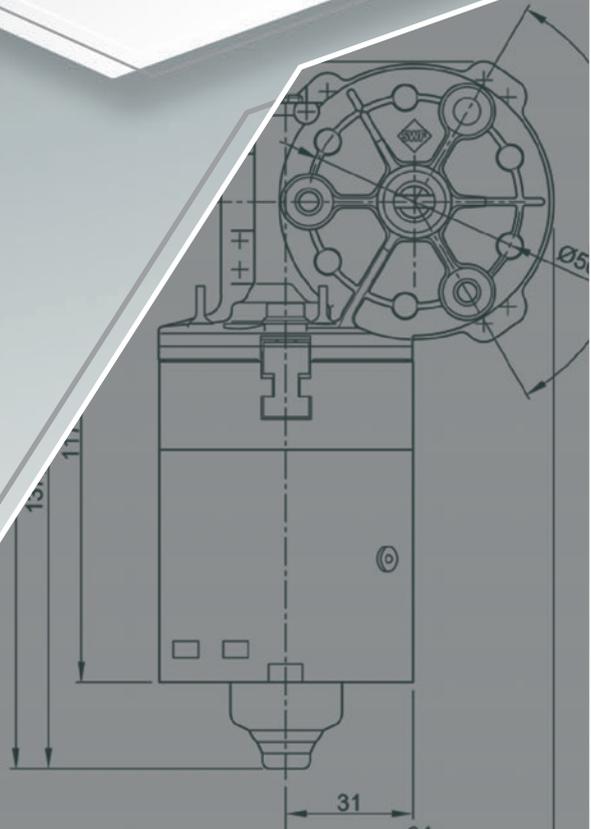


## ❖❖❖ TECHNICAL DESCRIPTION

Motorhousing:	rolled, corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	aluminium die cast
Gear wheel material:	plastic
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	connector or tinned leads
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

## ❖❖❖ APPLICATION

Industry, Linear drives, General machinery,  
 Vending machines, Agricultural technology,  
 Office machines, Laboratory devices,  
 Medical technology, Traffic & communications  
 technology, Film/optics



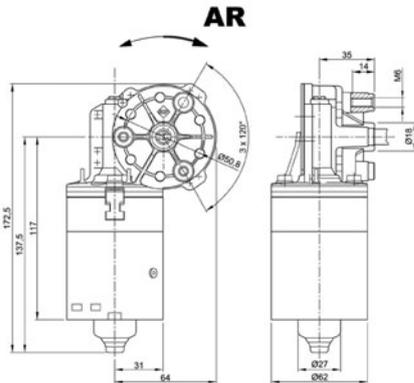
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	50.0
Nominal power [W]	$P_N$	17.7
Nominal current [A]	$I_N$	2.5
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	55/1
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	1.200

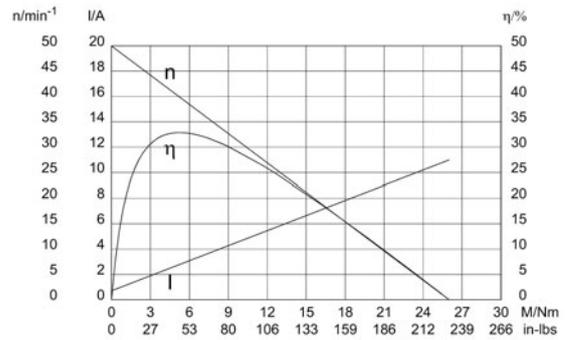
Remarks:



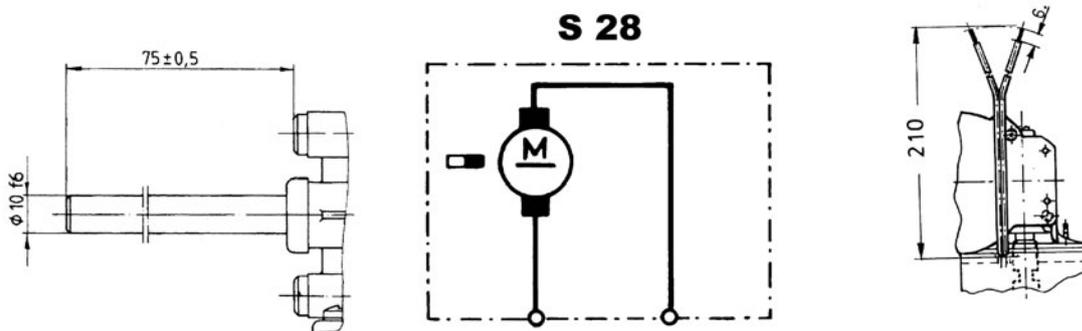
**Motor picture**



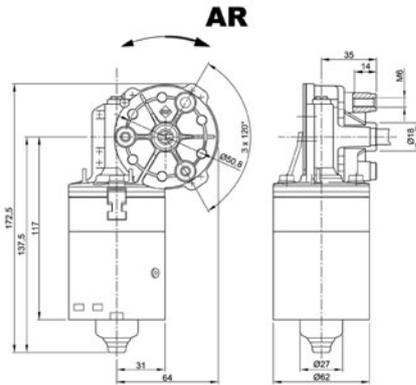
**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	



Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	33.0
Nominal power [W]	$P_N$	11.7
Nominal current [A]	$I_N$	3.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

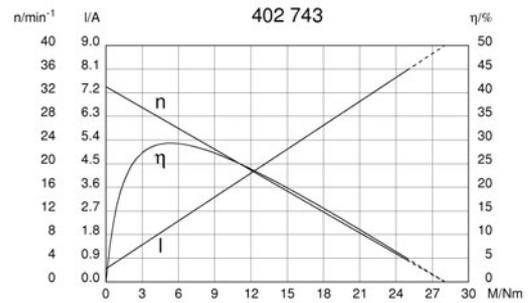
Other data	
Gear ratio	69/1
Gear wheel material	Plastic
Suppression components	4.7 $\mu\text{H}$
Enclosure class	IP30
Weight [kg]	1.200

Remarks:

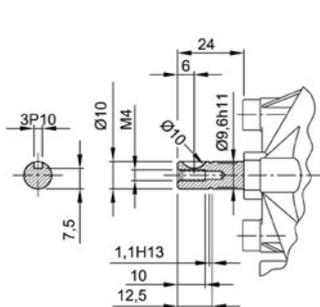
**Motor picture**



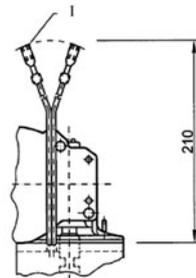
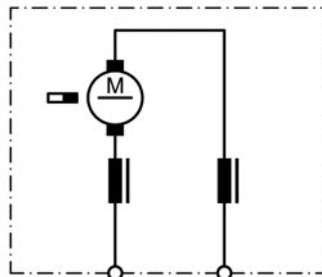
**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 27**



I: Spade connector 2.8 x 0.8 DIN 46 247

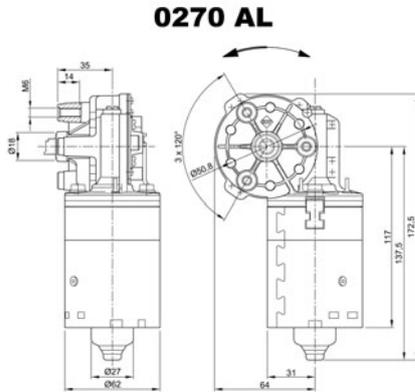
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	3.50
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	50.0
Nominal power [W]	$P_N$	15.9
Nominal current [A]	$I_N$	2.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	55/1
Gear wheel material	Plastic
Suppression components	4.7 $\mu$ H, 1nF
Enclosure class	IP30
Weight [kg]	1.200

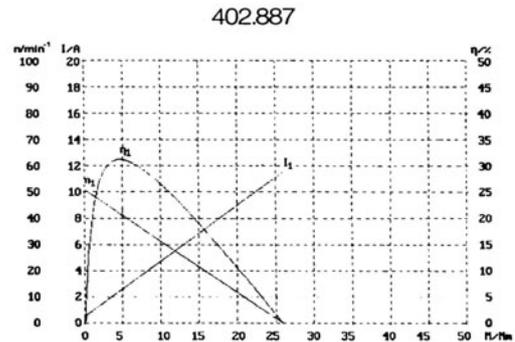
Remarks:



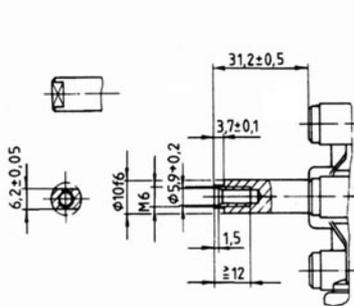
**Motor picture**



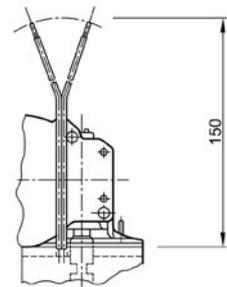
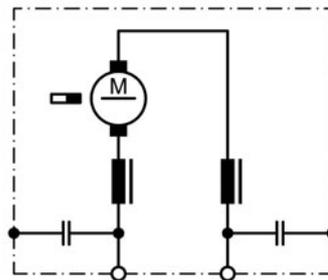
**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 30**



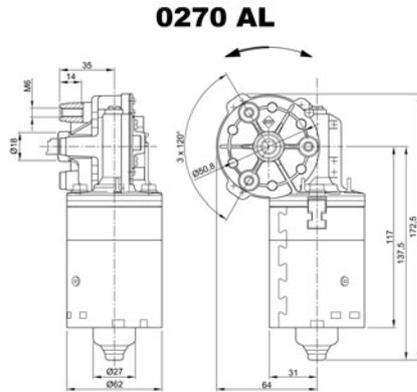
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	1.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	280.0
Nominal power [W]	$P_N$	24.9
Nominal current [A]	$I_N$	4.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	41/4
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	1.200

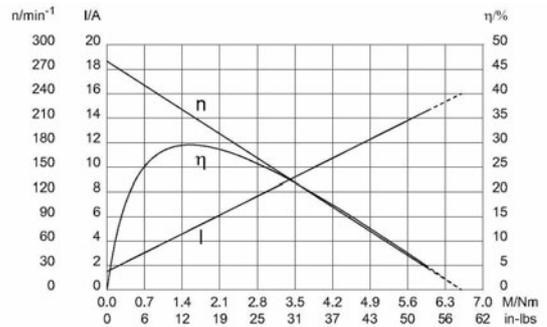
Remarks:



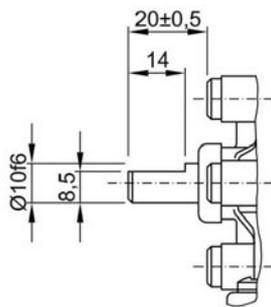
**Motor picture**



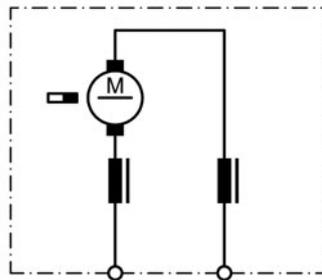
**Characteristic curves**



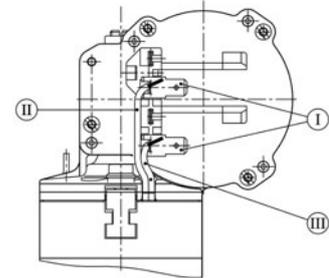
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 27**



**K 42**



- I Blade terminal ends  
6,3 x 0,8 DIN 46 244
- II green
- III red

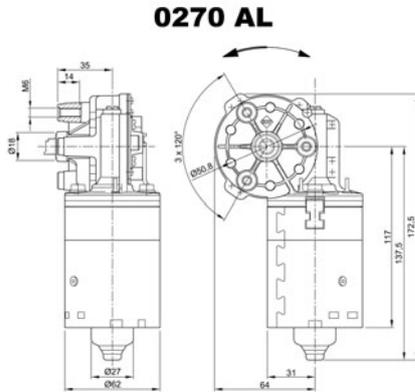
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data		
Rated voltage [V]	$U_N$	36
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	100.0
Nominal power [W]	$P_N$	18.3
Nominal current [A]	$I_N$	3.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

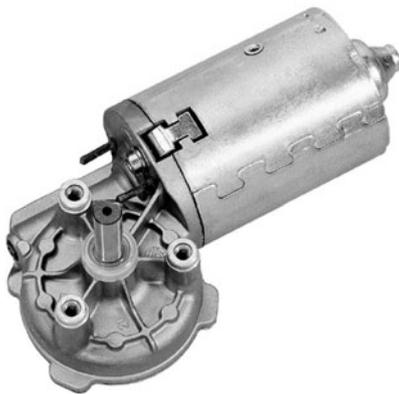
Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	53/2
Gear wheel material	Plastic
Suppression components	4.7 $\mu$ H, 1nF
Enclosure class	IP30
Weight [kg]	1.200

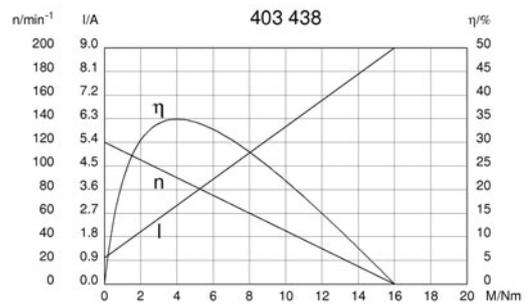
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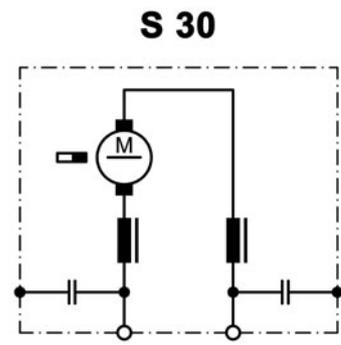
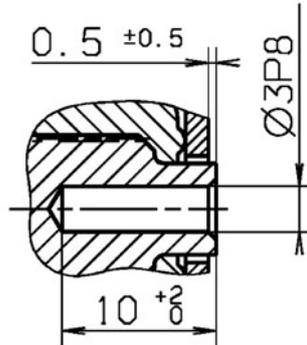
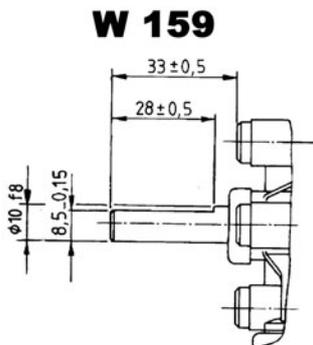
**Motor picture**



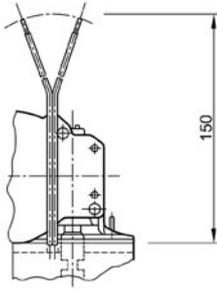
**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



**Notes**

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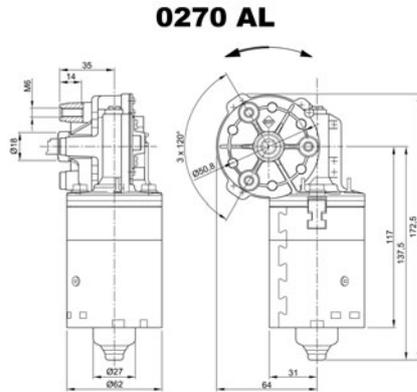
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	0.80
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	350.0
Nominal power [W]	$P_N$	27.0
Nominal current [A]	$I_N$	8.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	41/4
Gear wheel material	plastic
Suppression components	""
Enclosure class	IP 30
Weight [kg]	1.200

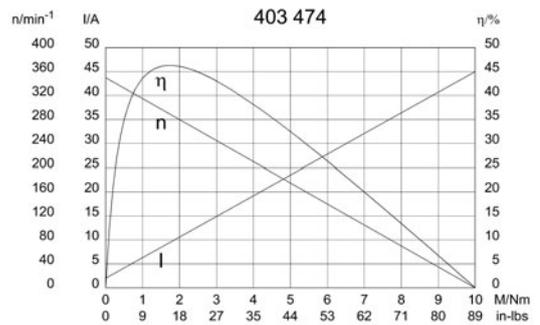
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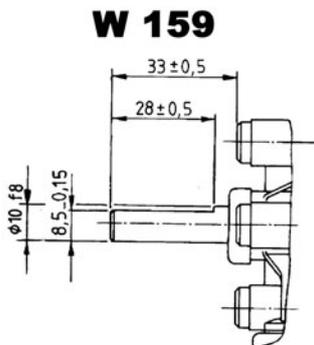
**Motor picture**



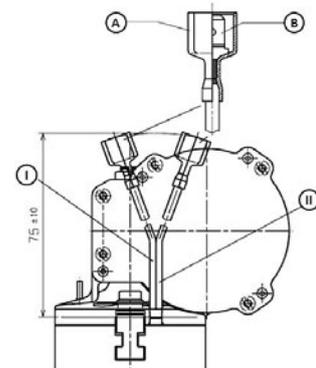
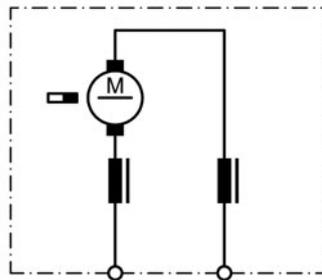
**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 27**



A: housing MST AMP No. 2-521055-2  
 B: spade terminals 6.3 x 0.8 DIN 46 244  
 I: red  
 II: green

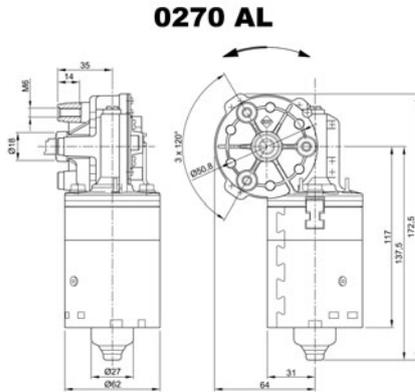
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	0.80
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	350.0
Nominal power [W]	$P_N$	27.0
Nominal current [A]	$I_N$	4.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	41/4
Gear wheel material	plastic
Suppression components	1nF
Enclosure class	IP 30
Weight [kg]	1.200

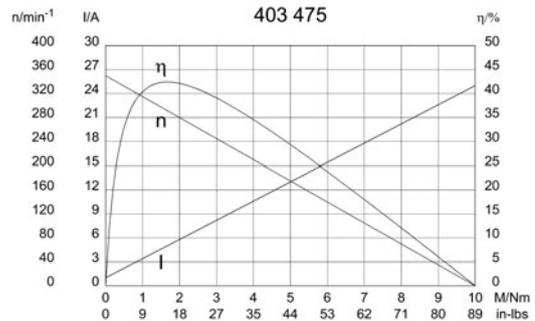
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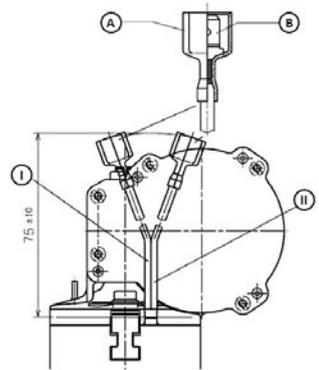
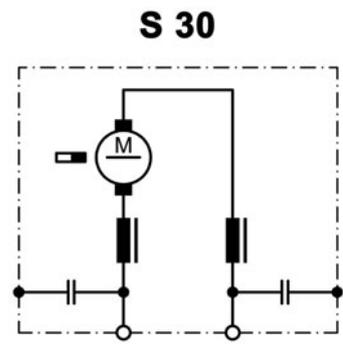
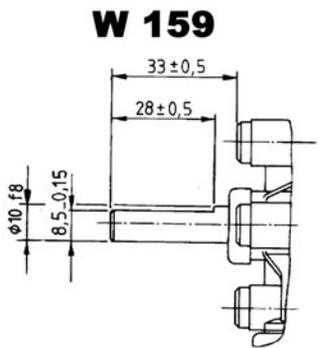
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



A: housing MST AMP No. 2-521055-2  
 B: spade terminals 6.3 x 0.8 DIN 46 244  
 I: red  
 II: green

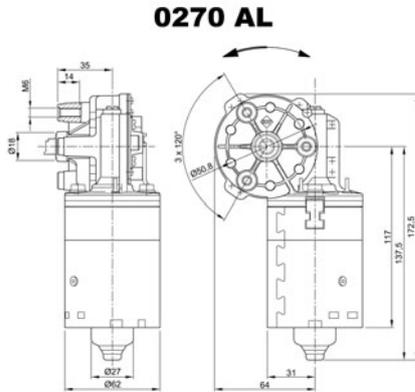
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	110.0
Nominal power [W]	$P_N$	20.8
Nominal current [A]	$I_N$	3.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	53/2
Gear wheel material	Plastic
Suppression components	4.7 $\mu$ H, 1nF
Enclosure class	IP30
Weight [kg]	1.200

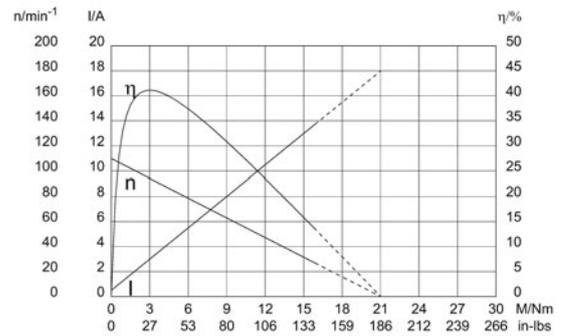
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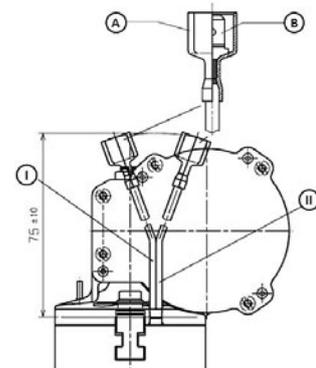
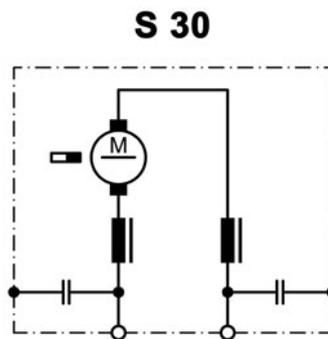
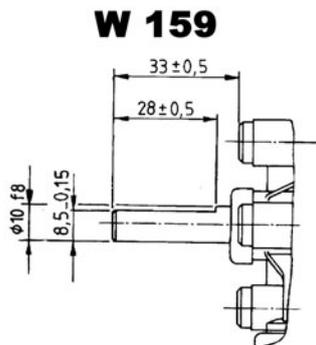
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



A: housing MST AMP No. 2-521055-2  
 B: spade terminals 6.3 x 0.8 DIN 46 244  
 I: red  
 II: green

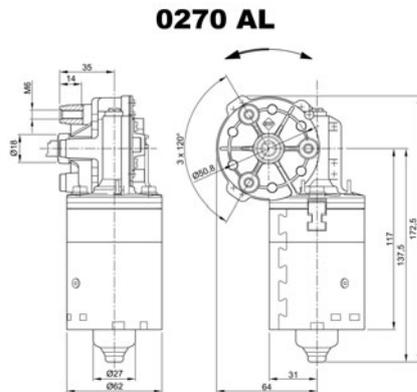
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	1.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	260.0
Nominal power [W]	$P_N$	23.0
Nominal current [A]	$I_N$	10.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	41/4
Gear wheel material	Plastic
Suppression components	
Enclosure class	
Weight [kg]	1.200

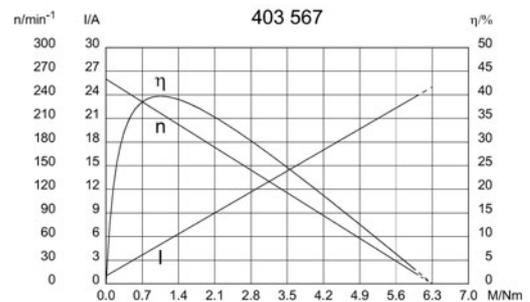
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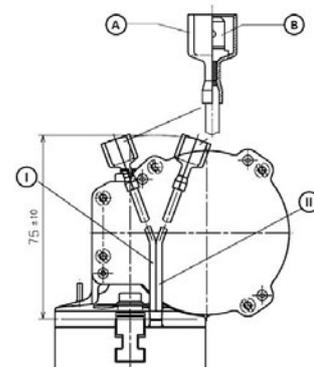
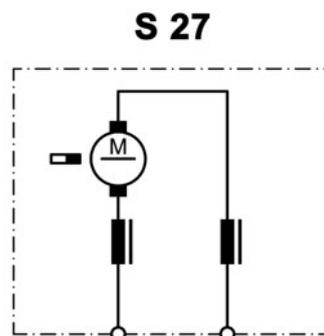
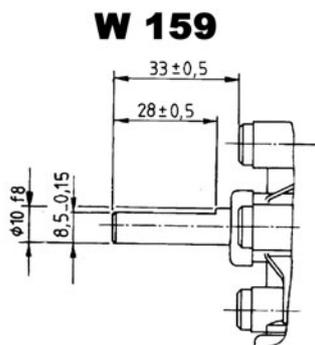
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



- A: housing MST AMP No. 2-521055-2
- B: spade terminals 6.3 x 0.8 DIN 46 244
- I: red
- II: green

**Design Data**

Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

**Performance data**

Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	2.50
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	21.0
Nominal power [W]	$P_N$	4.87
Nominal current [A]	$I_N$	1.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

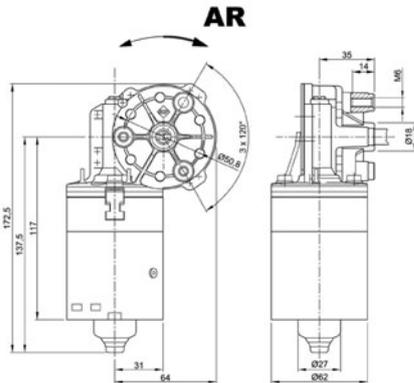
**Sensor data**

Pulses	0
Output channels	0

**Other data**

Gear ratio	69/1
Gear wheel material	Plastic
Suppression components	$4.7\mu\text{H}$ , $1\mu\text{F}$
Enclosure class	IP30
Weight [kg]	1.200

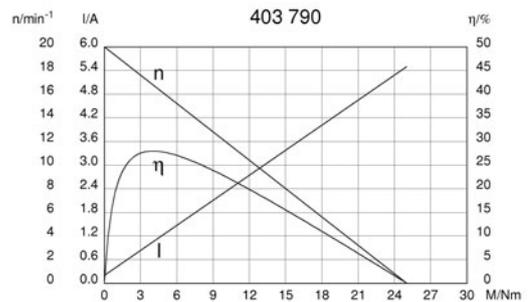
Remarks:



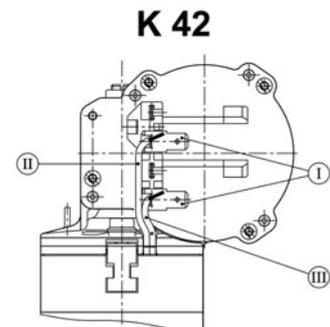
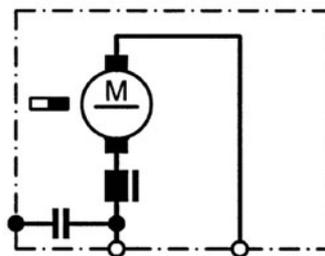
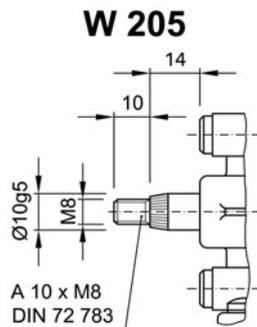
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



- I Blade terminal ends  
6,3 x 0,8 DIN 46 244
- II green
- III red

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

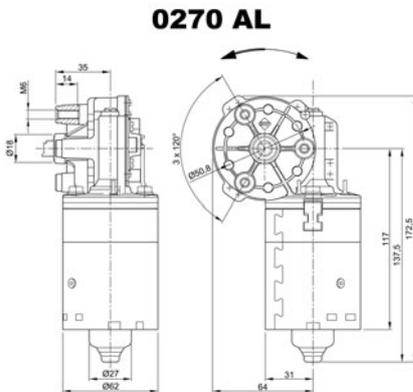
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	1.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	264.0
Nominal power [W]	$P_N$	23.2
Nominal current [A]	$I_N$	4.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	10.25
Output channels	1

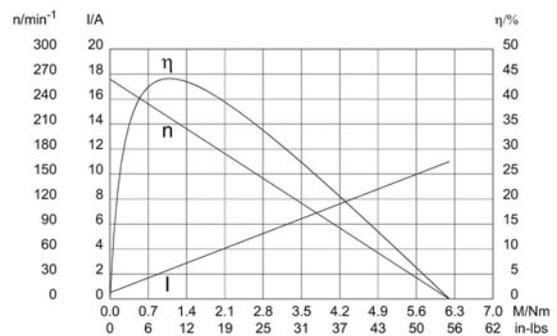
Other data	
Gear ratio	41/4
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP30
Weight [kg]	1.200

Remarks:

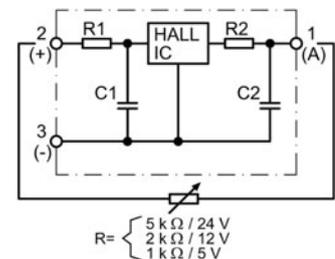
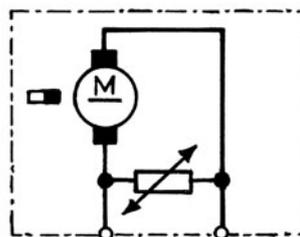
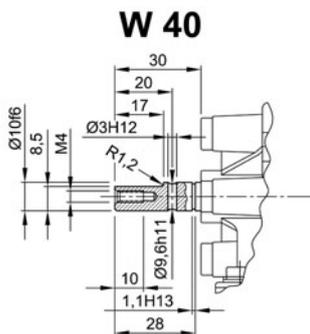
**Motor picture**



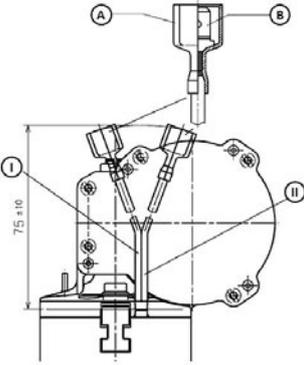
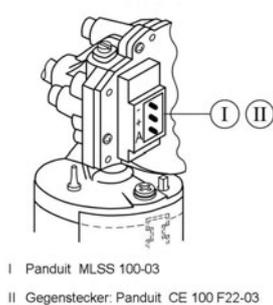
**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



- A: housing MST AMP No. 2-521055-2
- B: spade terminals 6.3 x 0.8 DIN 46 244
- I: red
- II: green

**Notes**

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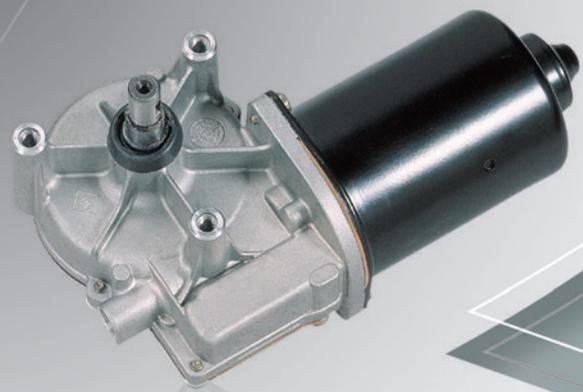
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NIDEC MOTORS & ACTUATORS ❖❖❖ MOTOR SERIES

# 0277 (SW2K)

❖❖❖ DC MOTORS WITH WORM GEAR

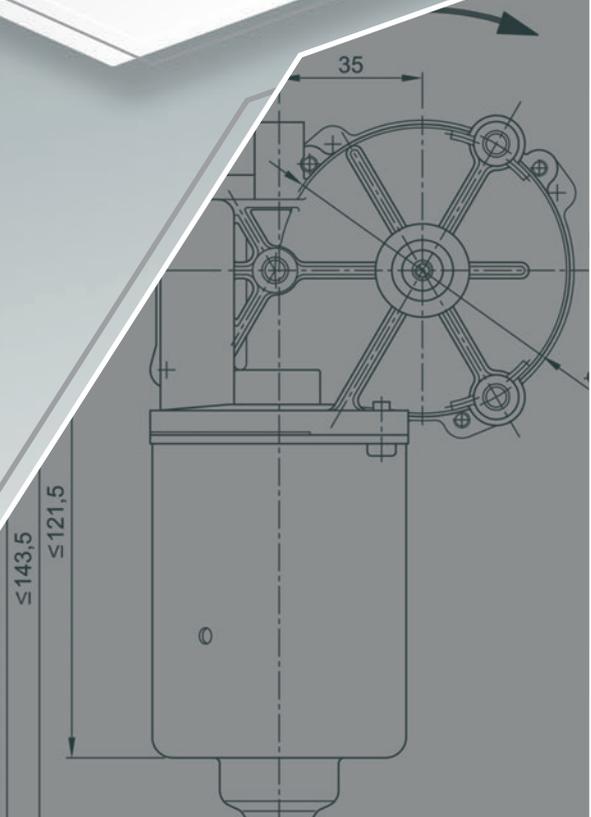


## ❖❖❖ TECHNICAL DESCRIPTION

Motorhousing:	deep drawn & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	aluminium die cast
Gear wheel material:	plastic
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	connector or tinned leads
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

## ❖❖❖ APPLICATION

Industry, Linear drives, General machinery,  
Vending machines, Agricultural technology,  
Office machines, Laboratory devices,  
Medical technology, Traffic & communications  
technology, Film/optics



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

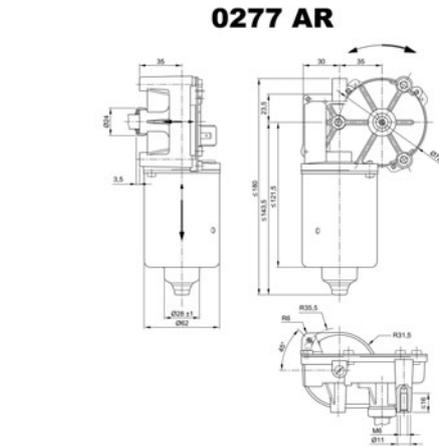
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	5.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	40.0
Nominal power [W]	$P_N$	16.8
Nominal current [A]	$I_N$	3.5
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

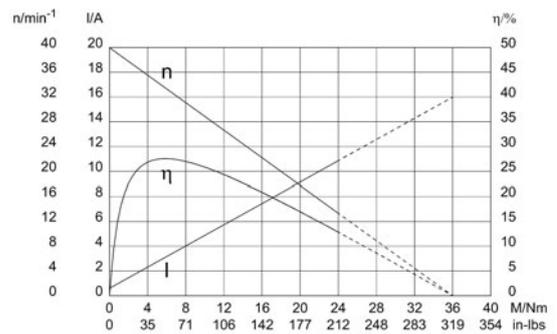
Other data	
Gear ratio	78/1
Gear wheel material	Plastic
Suppression components	4.7 $\mu$ H, 1nF
Enclosure class	IP40
Weight [kg]	1.200

Remarks: Ball bearing

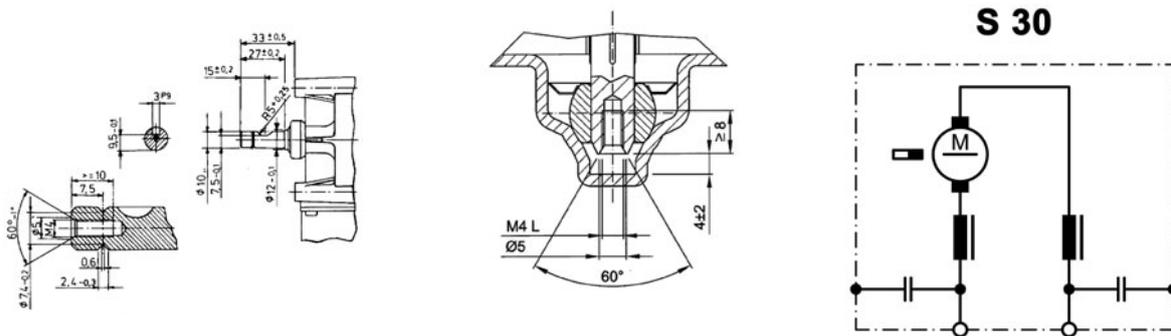
**Characteristic curves**



**Motor picture**



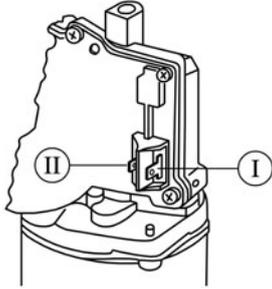
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



! Lefthand thread

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

**K 144**



- I Blade terminal ends 6,3 x 0,8 DIN 46 244
- II Blade terminal ends 4,8 x 0,8 DIN 46 244

### Notes

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Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

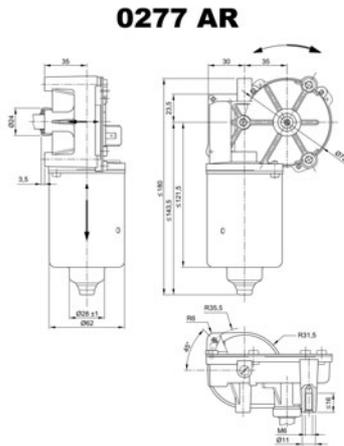
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	230.0
Nominal power [W]	$P_N$	44.2
Nominal current [A]	$I_N$	6.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

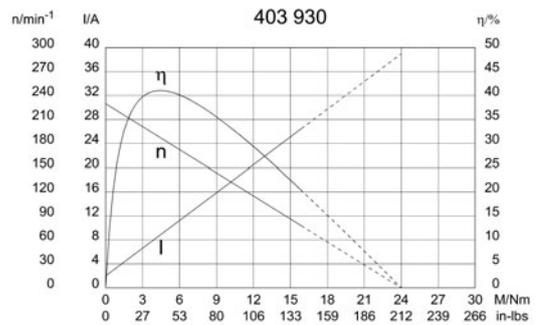
Other data	
Gear ratio	70/4
Gear wheel material	plastic
Suppression components	""
Enclosure class	IP 40
Weight [kg]	1.200

Remarks: Ball bearing

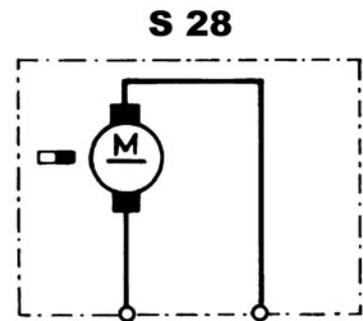
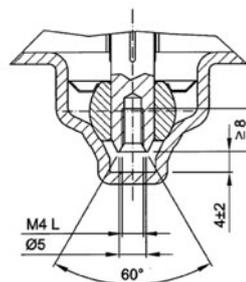
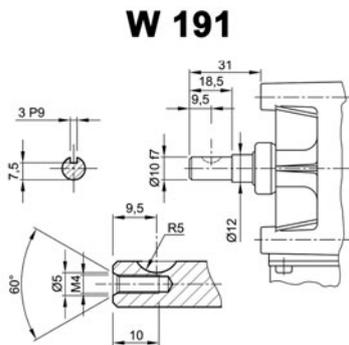
**Characteristic curves**



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



! Lefthand thread



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

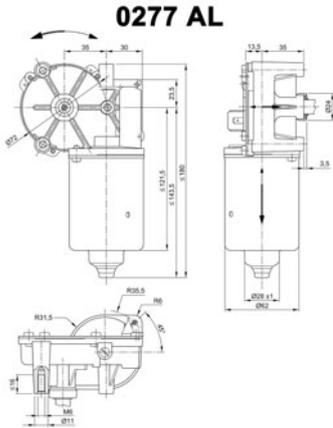
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	126.0
Nominal power [W]	$P_N$	23.0
Nominal current [A]	$I_N$	3.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

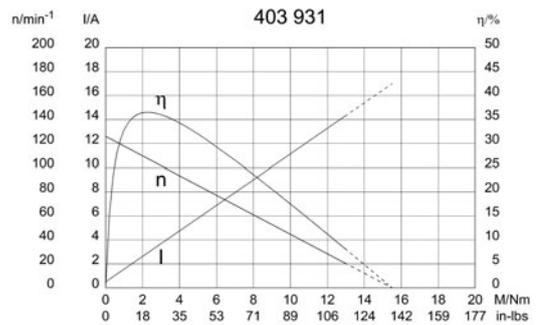
Other data	
Gear ratio	70/4
Gear wheel material	plastic
Suppression components	$4.7\mu\text{H}$ , $1\text{nF}$
Enclosure class	IP 40
Weight [kg]	1.200

Remarks: Ball bearing

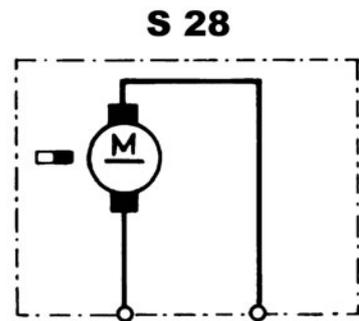
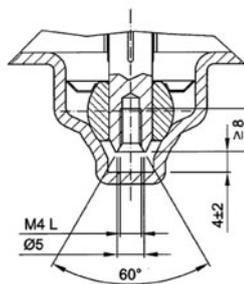
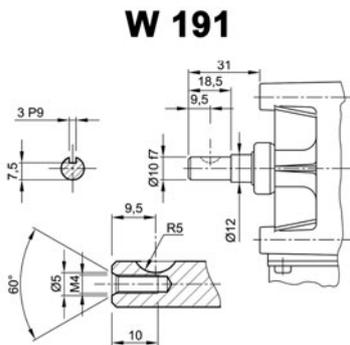
**Characteristic curves**



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



! Lefthand thread



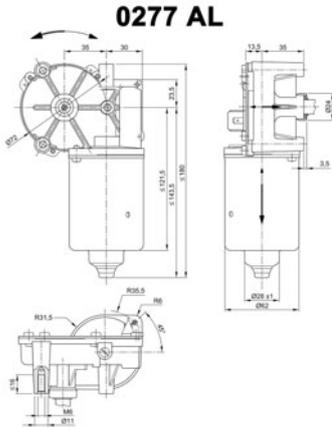
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	2.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	230.0
Nominal power [W]	$P_N$	44.2
Nominal current [A]	$I_N$	6.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

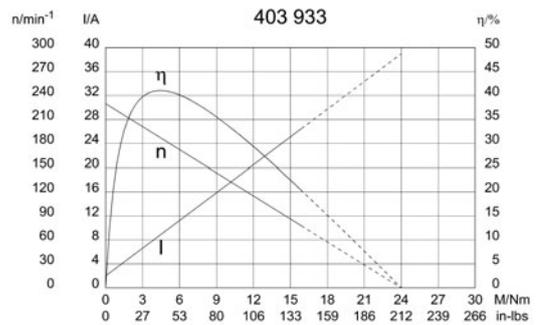
Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	70/4
Gear wheel material	plastic
Suppression components	""
Enclosure class	IP 40
Weight [kg]	1.200

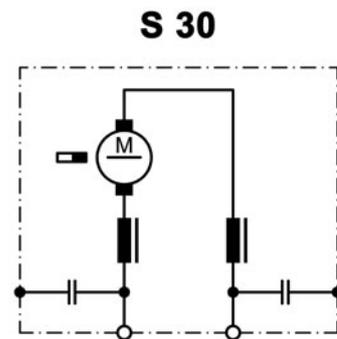
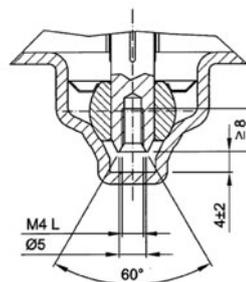
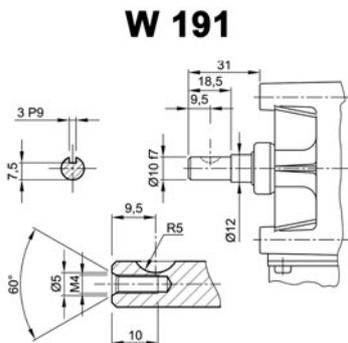
Remarks: Ball bearing



Motor picture



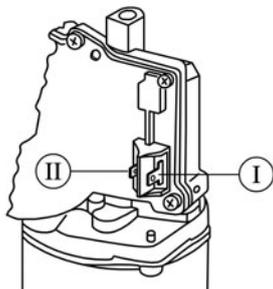
Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)



! Lefthand thread

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

**K 144**



- I Blade terminal ends 6,3 x 0,8 DIN 46 244
- II Blade terminal ends 4,8 x 0,8 DIN 46 244

**Notes**

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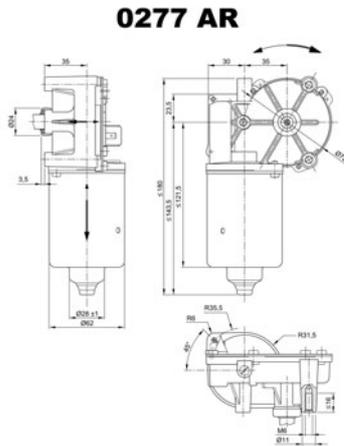
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	5.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	54.0
Nominal power [W]	$P_N$	26.3
Nominal current [A]	$I_N$	5.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	78/1
Gear wheel material	plastic
Suppression components	$5\mu\text{H}$ , $1\text{nF}$
Enclosure class	IP 40
Weight [kg]	1.200

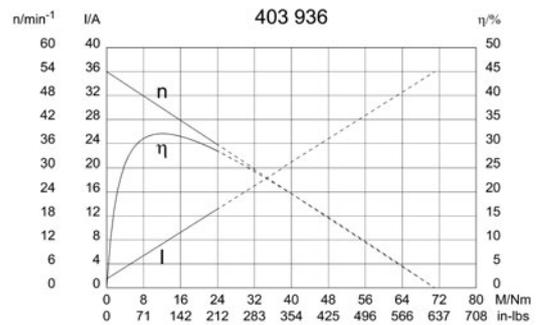
Remarks:



**Motor picture**

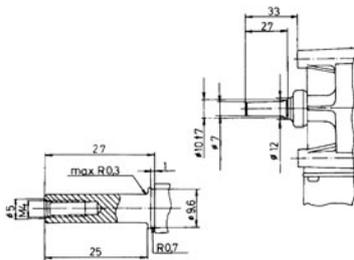


**Characteristic curves**

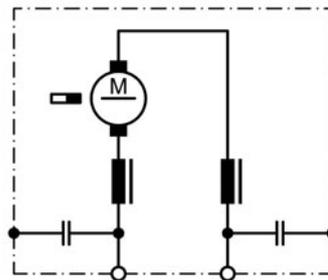


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

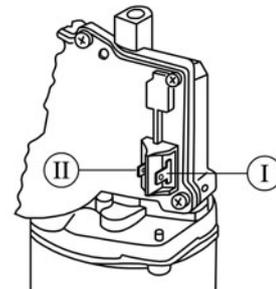
**W 194**



**S 30**



**K 144**



I - Blade terminal ends 6,3 x 0,8 DIN 46 244  
 II - Blade terminal ends 4,8 x 0,8 DIN 46 244

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

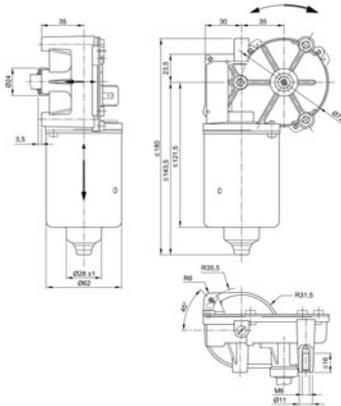
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	5.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	40.0
Nominal power [W]	$P_N$	16.8
Nominal current [A]	$I_N$	3.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

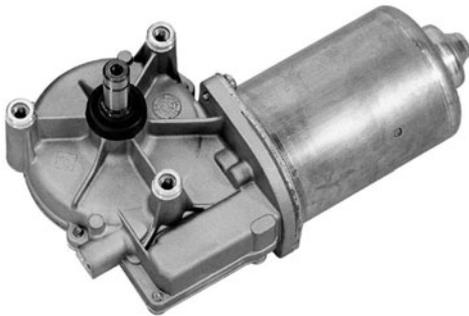
Other data	
Gear ratio	78/1
Gear wheel material	Plastic
Suppression components	
Enclosure class	IP40
Weight [kg]	1.200

Remarks:

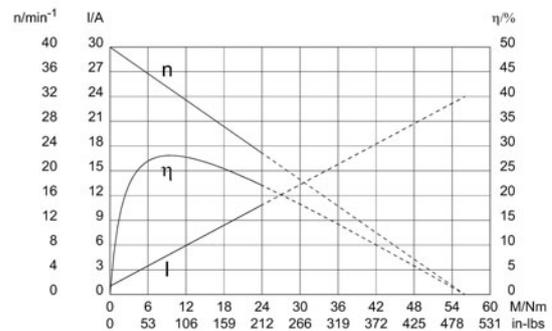
**0277 AR**



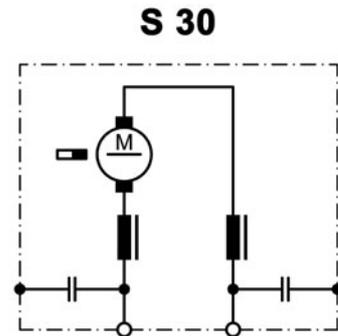
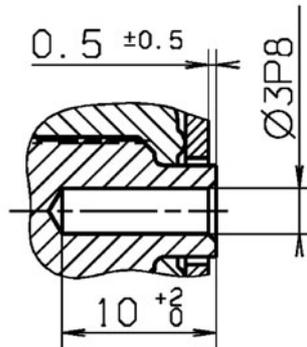
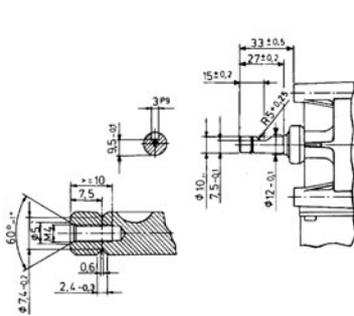
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**





Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

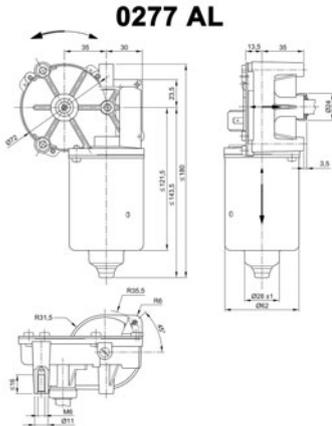
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	5.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	65.0
Nominal power [W]	$P_N$	27.2
Nominal current [A]	$I_N$	4.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

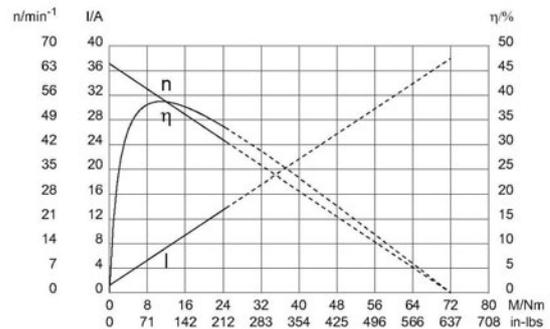
Other data	
Gear ratio	63/1
Gear wheel material	Plastic
Suppression components	4.7 $\mu$ H, 1nF
Enclosure class	IP40
Weight [kg]	1.200

Remarks: Ball bearing

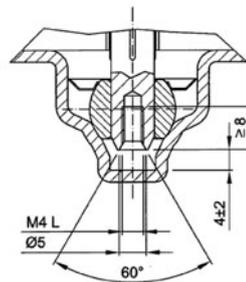
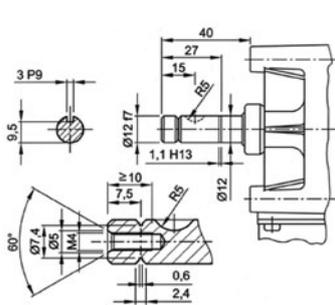
**Characteristic curves**



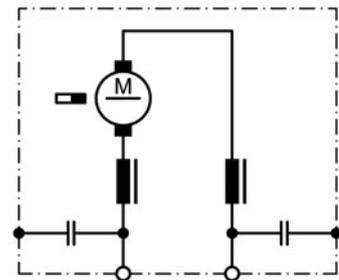
**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



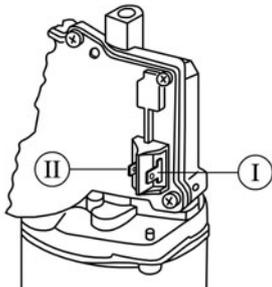
**S 30**



! Lefthand thread

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

**K 144**



- I Blade terminal ends 6,3 x 0,8 DIN 46 244
- II Blade terminal ends 4,8 x 0,8 DIN 46 244

**Notes**

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Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

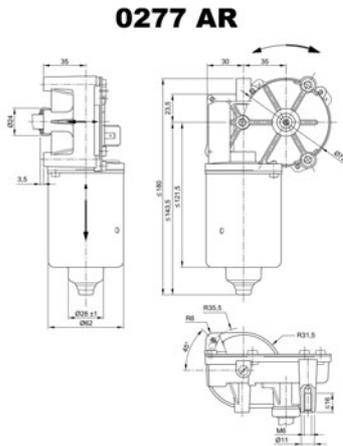
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	5.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	65.0
Nominal power [W]	$P_N$	27.2
Nominal current [A]	$I_N$	4.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

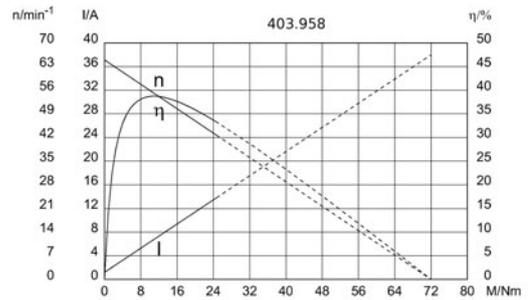
Other data	
Gear ratio	63/1
Gear wheel material	Plastic
Suppression components	4.7 $\mu$ H, 1nF
Enclosure class	IP40
Weight [kg]	1.200

Remarks: Ball bearing

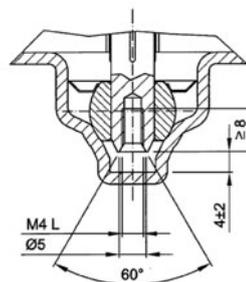
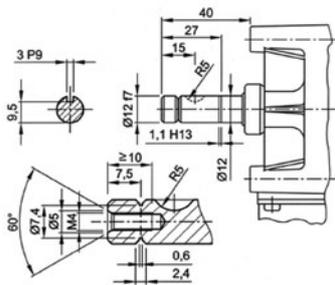
**Characteristic curves**



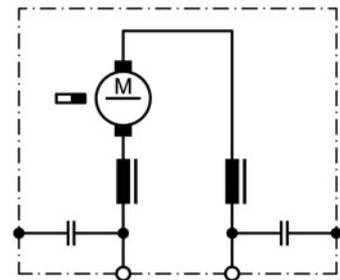
**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 30**



! Lefthand thread



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	

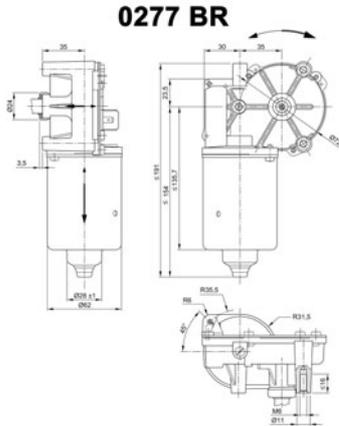
Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	3.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	270.0
Nominal power [W]	$P_N$	68.9
Nominal current [A]	$I_N$	15.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

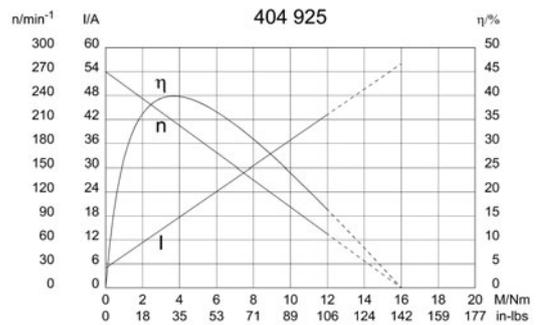
Other data	
Gear ratio	70/4
Gear wheel material	plastic
Suppression components	1.9 $\mu$ H, 1 $\mu$ F
Enclosure class	IP 40
Weight [kg]	1.200

Remarks: Ball bearing

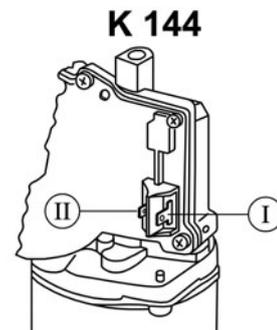
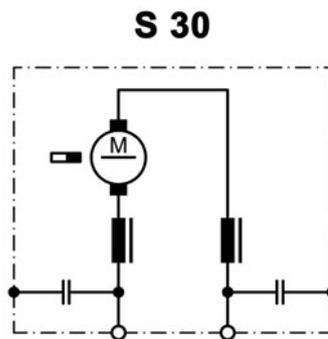
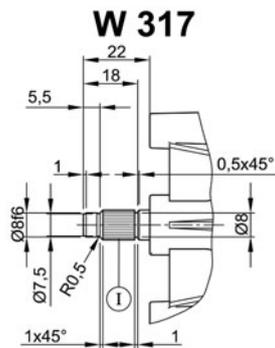
**Characteristic curves**



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



I Tapered splines 8 x 10 f  
(similar DIN 5481)

I Blade terminal ends 6,3 x 0,8 DIN 46 244  
II Blade terminal ends 4,8 x 0,8 DIN 46 244

**Notes**

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NIDEC MOTORS & ACTUATORS ❖❖❖ MOTOR SERIES

# 0278 (SW2L)

❖❖❖ DC MOTORS WITH WORM GEAR

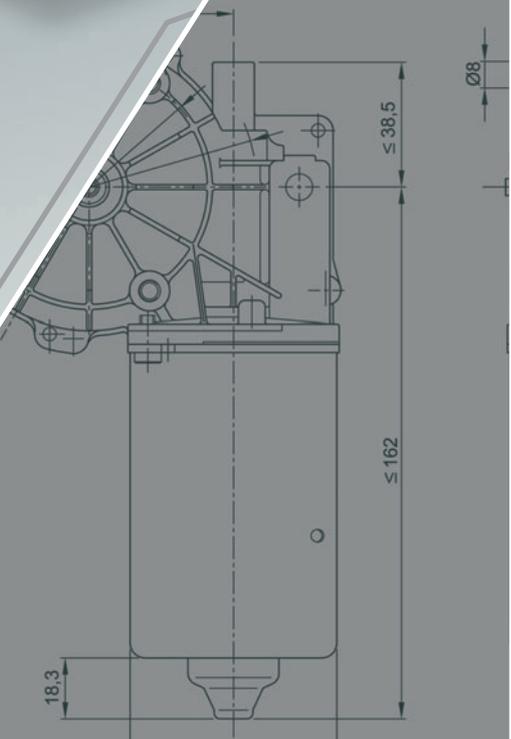


## ❖❖❖ TECHNICAL DESCRIPTION

Motorhousing:	deep drawn & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	aluminium die cast
Gear wheel material:	plastic
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

## ❖❖❖ INDUSTRIAL APPLICATION

Gate Opener, Patient Hoist,  
Machine construction



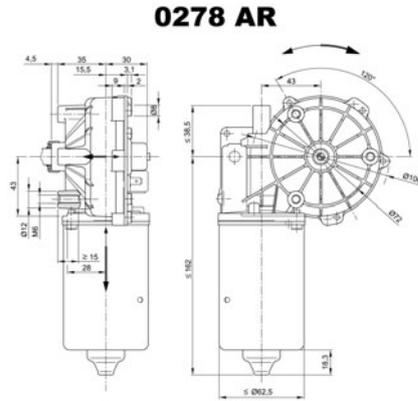
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	6.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	48.0
Nominal power [W]	$P_N$	27.9
Nominal current [A]	$I_N$	6.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	74/1
Gear wheel material	plastic
Suppression components	4,7 $\mu$ H, 1 $\mu$ F
Enclosure class	IP40
Weight [kg]	1.716

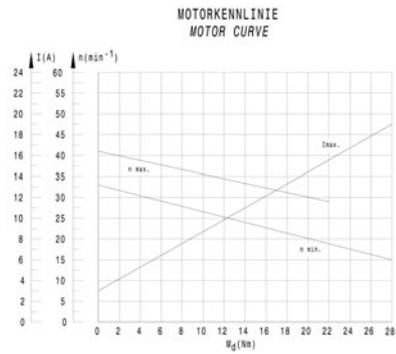
Remarks:



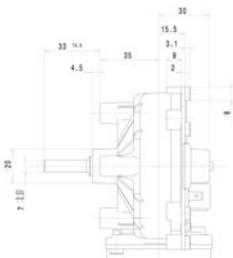
**Motor picture**



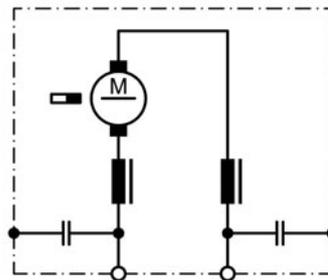
**Characteristic curves**



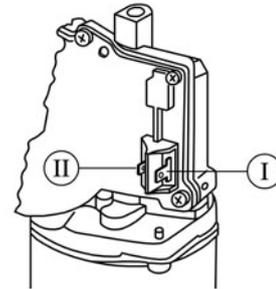
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 30**



**K 144**



- I - Blade terminal ends 6,3 x 0,8 DIN 46 244
- II - Blade terminal ends 4,8 x 0,8 DIN 46 244

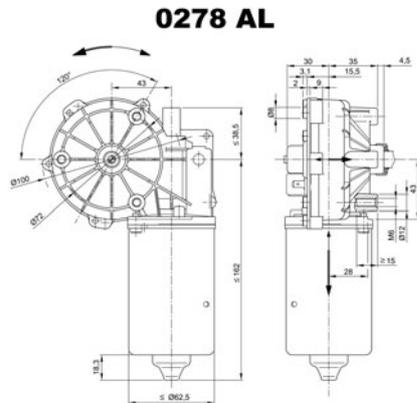
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	8.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	48.0
Nominal power [W]	$P_N$	36.3
Nominal current [A]	$I_N$	5.5
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	74/1
Gear wheel material	Plastic
Suppression components	4.7 $\mu\text{H}$ , 1 $\mu\text{F}$
Enclosure class	IP40
Weight [kg]	1.700

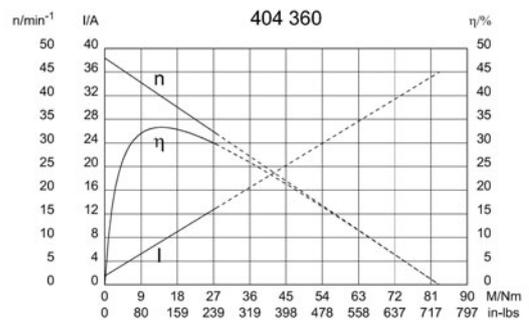
Remarks:



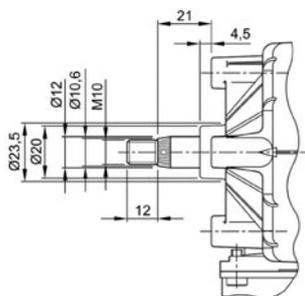
**Motor picture**



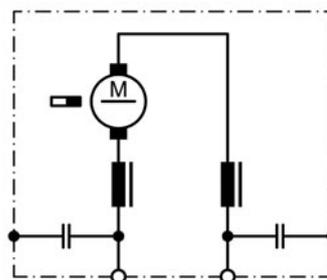
**Characteristic curves**



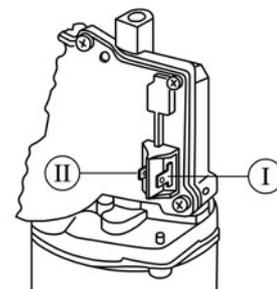
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 30**



**K 144**



I - Blade terminal ends 6,3 x 0,8 DIN 46 244  
 II - Blade terminal ends 4,8 x 0,8 DIN 46 244

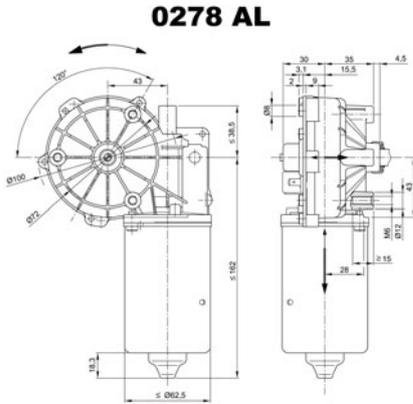
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	190.0
Nominal power [W]	$P_N$	73.1
Nominal current [A]	$I_N$	7.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	103/4
Gear wheel material	plastic
Suppression components	4,7 $\mu$ H, 1nF
Enclosure class	IP 40
Weight [kg]	1.700

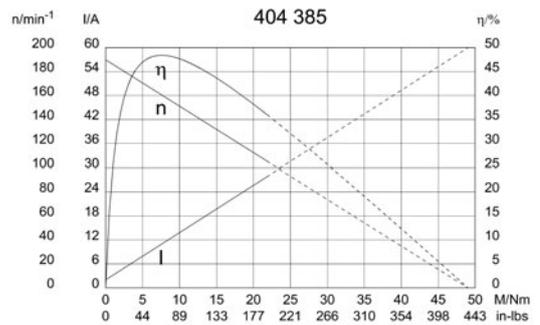
Remarks:



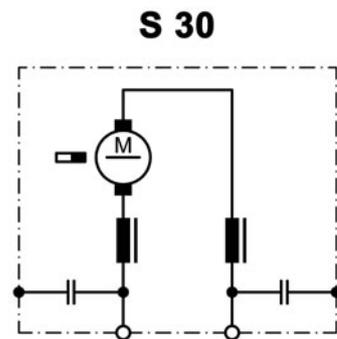
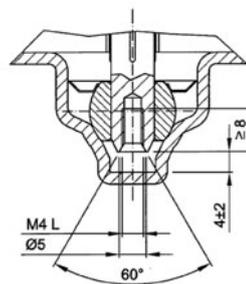
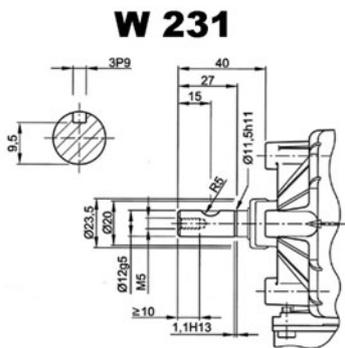
**Motor picture**



**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



! Lefthand thread



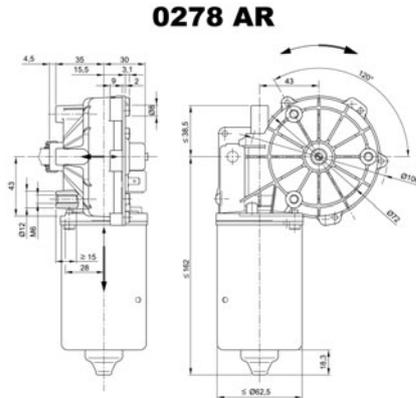
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	4.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	190.0
Nominal power [W]	$P_N$	73.1
Nominal current [A]	$I_N$	7.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	103/4
Gear wheel material	plastic
Suppression components	4,7 $\mu$ H, 1nF
Enclosure class	IP 40
Weight [kg]	1.700

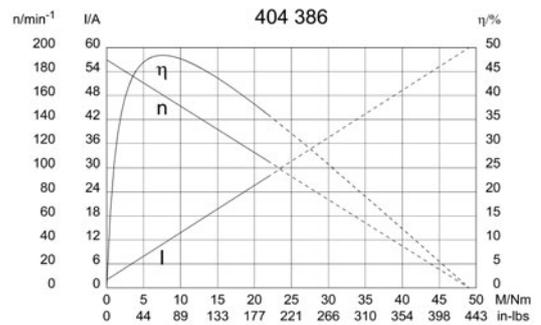
Remarks:



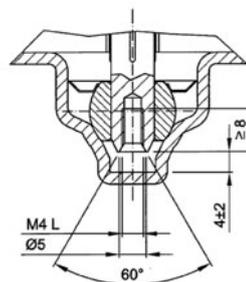
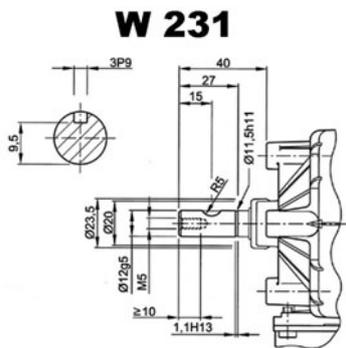
**Motor picture**



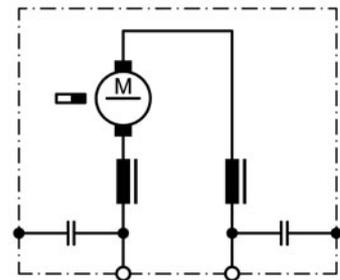
**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



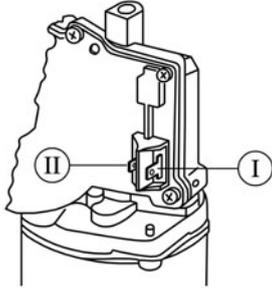
**S 30**



! Lefthand thread

Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)

**K 144**



- I Blade terminal ends 6,3 x 0,8 DIN 46 244
- II Blade terminal ends 4,8 x 0,8 DIN 46 244

**Notes**

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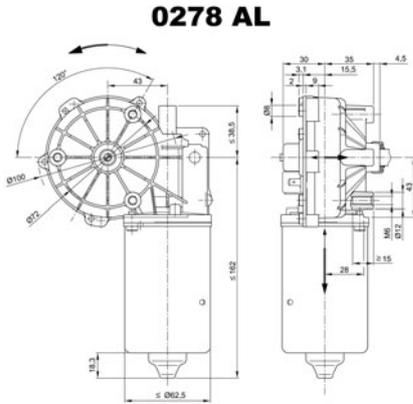
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	6.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	48.0
Nominal power [W]	$P_N$	21.9
Nominal current [A]	$I_N$	4.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	74
Output channels	1

Other data	
Gear ratio	74/1
Gear wheel material	plastic
Suppression components	4,7 $\mu$ H, 1nF
Enclosure class	IP40
Weight [kg]	1.730

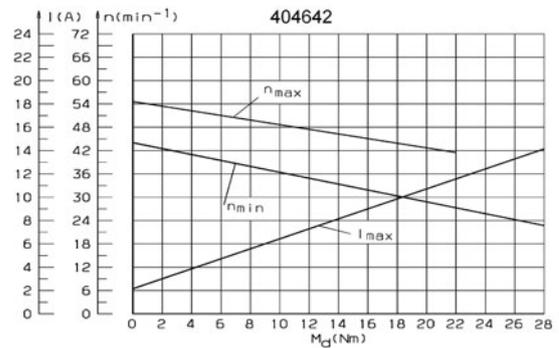
Remarks:



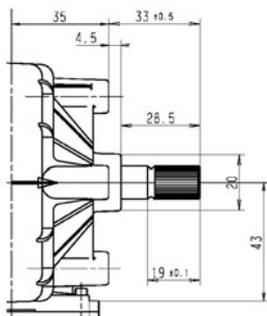
**Motor picture**



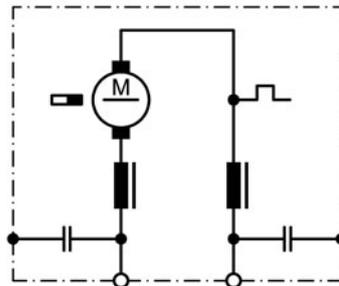
**Characteristic curves**



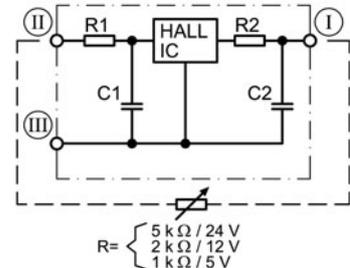
**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 74**



**S 124**



Splines: 10 x 12f (according to DIN 5481)

- I Terminal 3, A
- II Terminal 4, +
- III Terminal 5, -



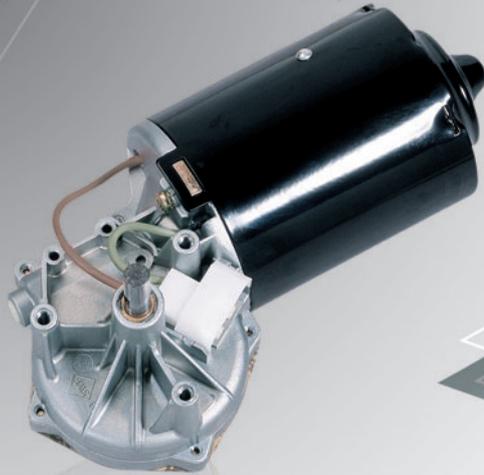




NIDEC MOTORS & ACTUATORS ❖❖❖ MOTOR SERIES

# 0291 (SWMV)

❖❖❖ DC MOTORS WITH WORM GEAR



## ❖❖❖ TECHNICAL DESCRIPTION

Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	zinc die cast
Gear wheel material:	plastic, resin bonded fabrics, steel
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	connector or leads
Sensor:	-
Thermal protection:	-
EMC suppression:	optional

## ❖❖❖ INDUSTRIAL APPLICATION

Machine construction



Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

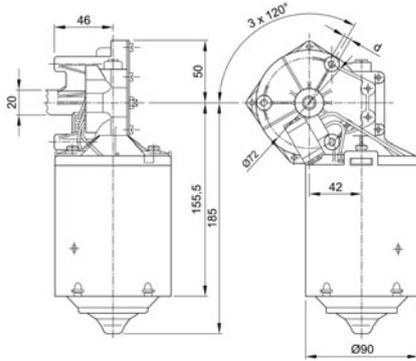
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	6.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	67.0
Nominal power [W]	$P_N$	38.5
Nominal current [A]	$I_N$	5.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	46/1
Gear wheel material	Bronze
Suppression components	
Enclosure class	IP20
Weight [kg]	2.900

Remarks:

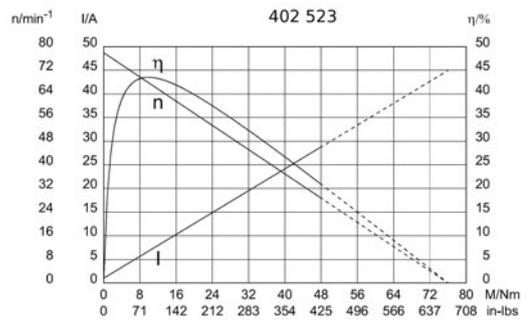
**0291 AL**



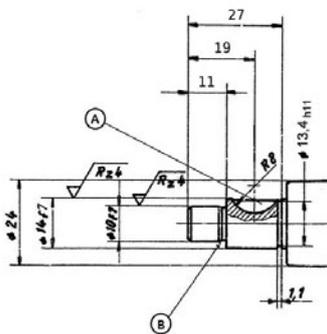
**Motor picture**



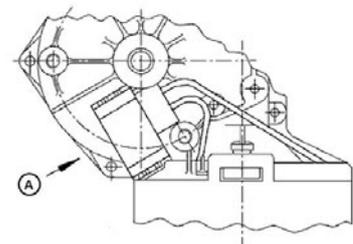
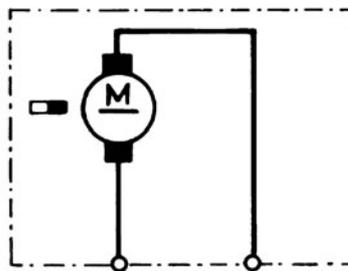
**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 28**



A: keyway 5 - P9 width tolerance  
 B: undercut E 0.6 x 0.2 to DIN 509

A: spade ends 6.3 x 0.8 (according to DIN 46 244)

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

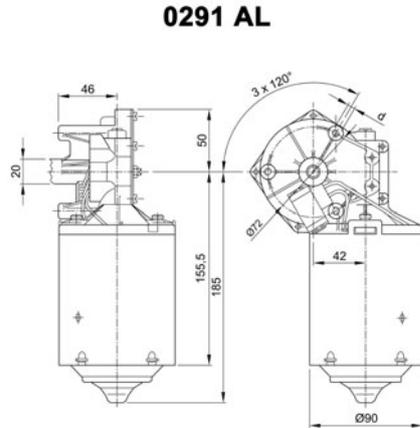
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	8.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	78.0
Nominal power [W]	$P_N$	58.5
Nominal current [A]	$I_N$	6.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

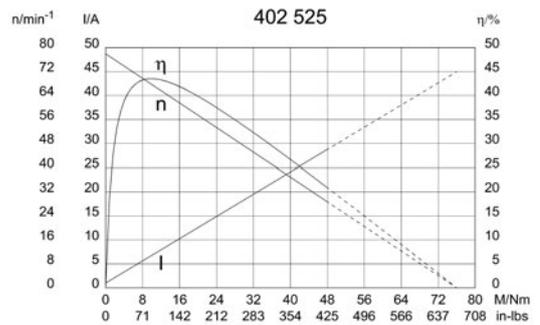
Other data	
Gear ratio	46/1
Gear wheel material	Resinbonded fabric
Suppression components	
Enclosure class	IP 20
Weight [kg]	2.900

Remarks: d = M6x16mm

**Characteristic curves**

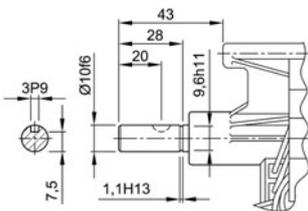


**Motor picture**

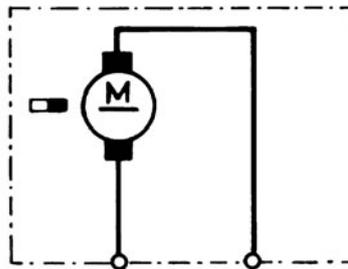


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

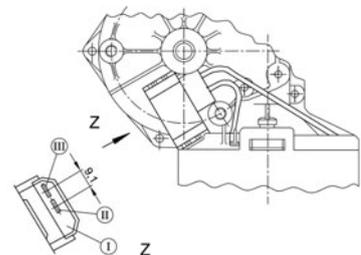
**W 278**



**S 28**



**K 243**



Flat plug 6,8x0,8 DIN 46244 mating with receptacle for tabs and connector housing 163 006-1, drwg C163006, [www.tycoelectronics.com](http://www.tycoelectronics.com)

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

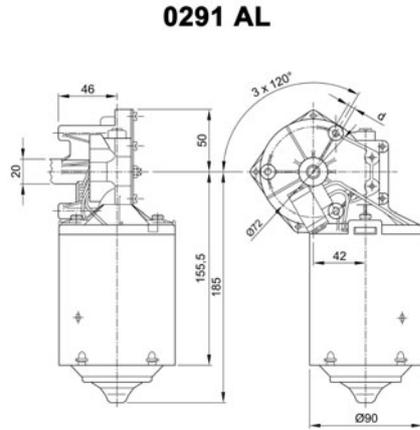
Performance data		
Rated voltage [V]	$U_N$	12
Nominal torque [Nm]	$M_N$	6.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	52.0
Nominal power [W]	$P_N$	29.7
Nominal current [A]	$I_N$	6.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

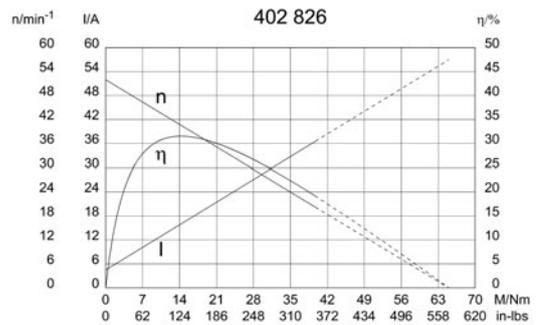
Other data	
Gear ratio	59/1
Gear wheel material	Resinbonded fabric
Suppression components	
Enclosure class	IP 20
Weight [kg]	2.900

Remarks: d = M6x16mm

**Characteristic curves**

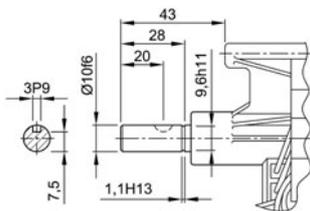


**Motor picture**

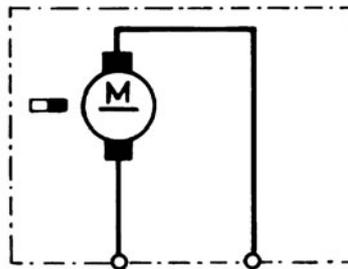


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

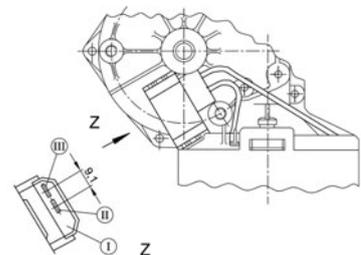
**W 278**



**S 28**



**K 243**



Flat plug 6,8x0,8 DIN 46244 mating with receptacle for tabs and connector housing 163 006-1, drwg C163006, [www.tycoelectronics.com](http://www.tycoelectronics.com)

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A: Ball - B: Sleeve

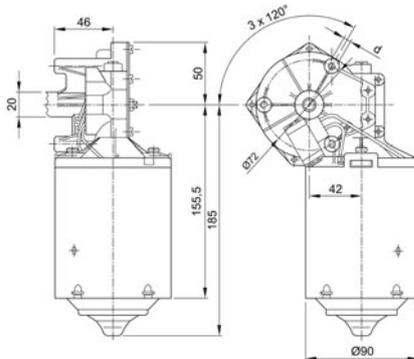
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	8.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	47.0
Nominal power [W]	$P_N$	34.9
Nominal current [A]	$I_N$	11.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	59/1
Gear wheel material	Bronze
Suppression components	5.0 $\mu$ H
Enclosure class	IP20
Weight [kg]	2.900

Remarks:

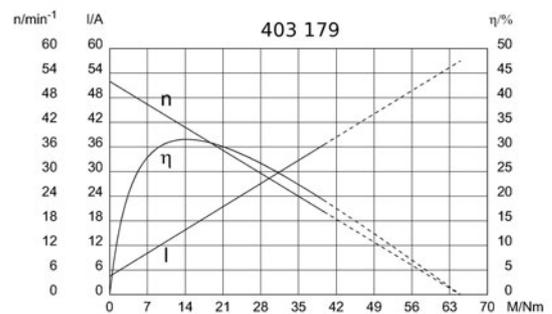
**0291 AL**



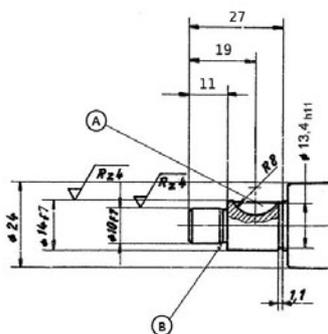
**Motor picture**



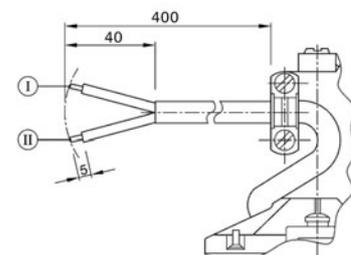
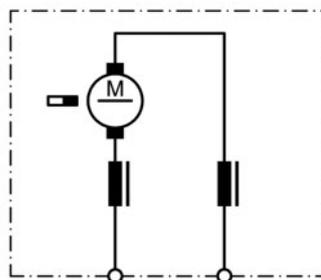
**Characteristic curves**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 27**



A: keyway 5 - P9 width tolerance  
 B: undercut E 0.6 x 0.2 to DIN 509

I: red  
 II: green

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

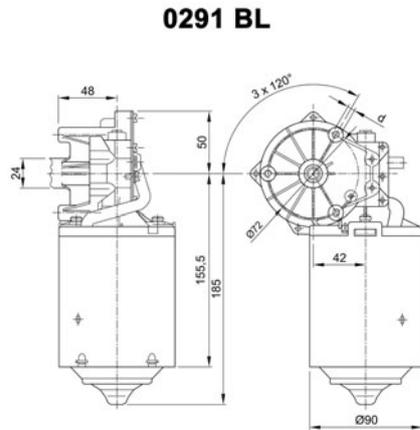
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	3.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	220.0
Nominal power [W]	$P_N$	65.7
Nominal current [A]	$I_N$	8.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

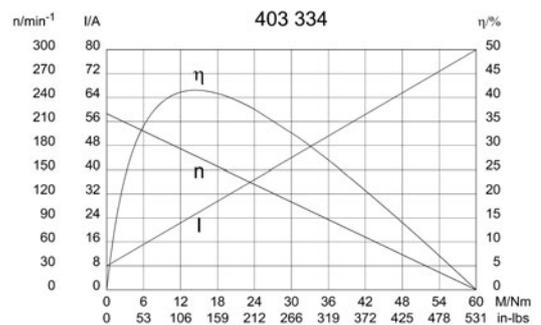
Other data	
Gear ratio	44/2
Gear wheel material	plastic
Suppression components	6,5 $\mu$ H, 1nF
Enclosure class	IP 20
Weight [kg]	2.900

Remarks: d = M8 x 16 mm

**Characteristic curves**

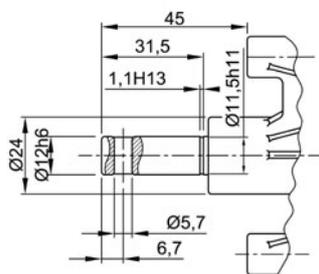


**Motor picture**

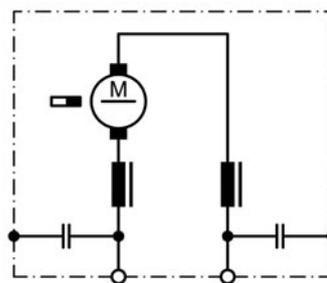


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

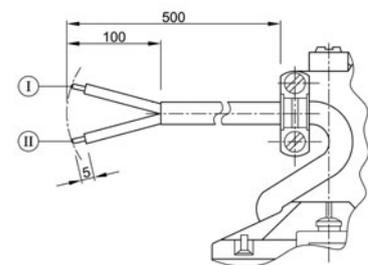
**W 070**



**S 30**



**K 274**



I red  
 II green

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

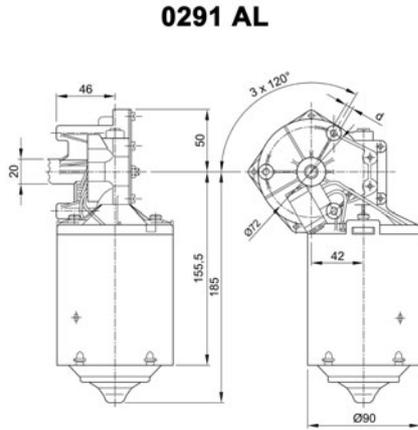
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	5.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	52.0
Nominal power [W]	$P_N$	25.7
Nominal current [A]	$I_N$	5.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

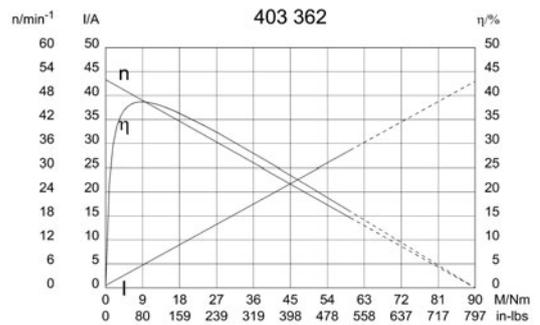
Other data	
Gear ratio	59/1
Gear wheel material	Resinbonded fabric
Suppression components	
Enclosure class	IP 20
Weight [kg]	2.900

Remarks: d = M8 x 23mm

**Characteristic curves**

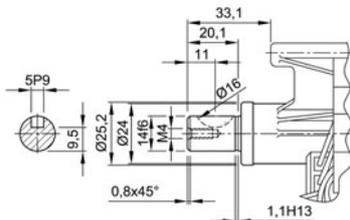


**Motor picture**

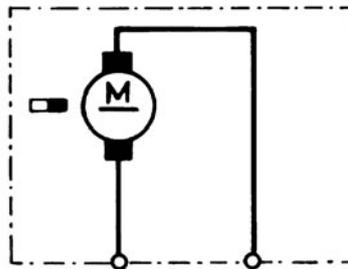


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

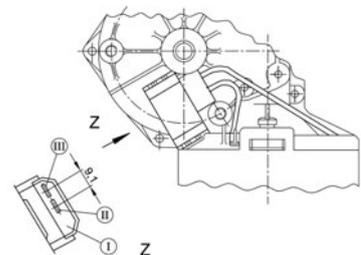
**W 126**



**S 28**



**K 243**



Flat plug 6,8x0,8 DIN 46244 mating with receptacle for tabs and connector housing 163 006-1, drwg C163006, [www.tycoelectronics.com](http://www.tycoelectronics.com)

Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

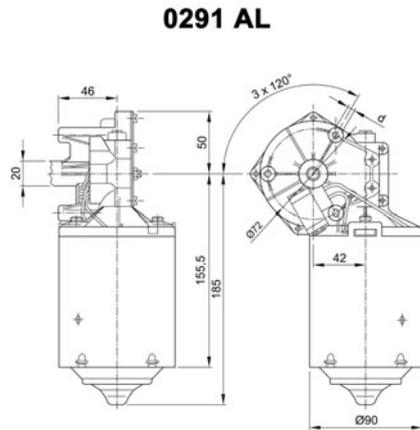
Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	8.00
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	48.0
Nominal power [W]	$P_N$	36.0
Nominal current [A]	$I_N$	7.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

Sensor data	
Pulses	0
Output channels	0

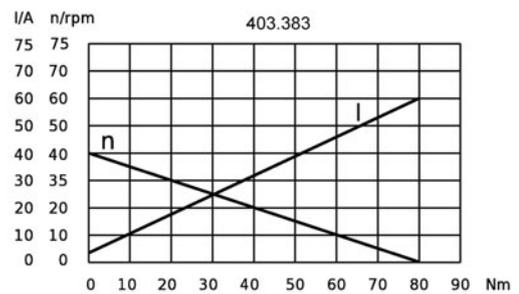
Other data	
Gear ratio	46/1
Gear wheel material	bronze
Suppression components	
Enclosure class	IP20
Weight [kg]	2.900

Remarks: d=M8x23

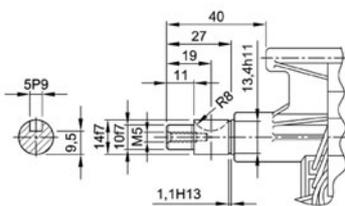
**Characteristic curves**



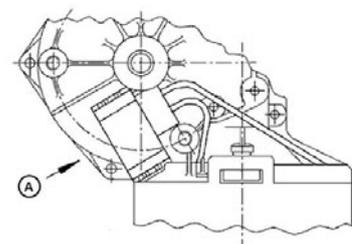
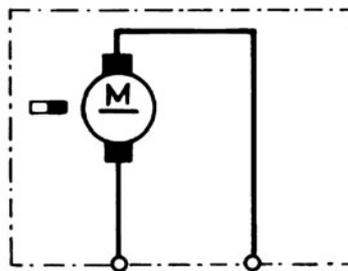
**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**



**S 28**



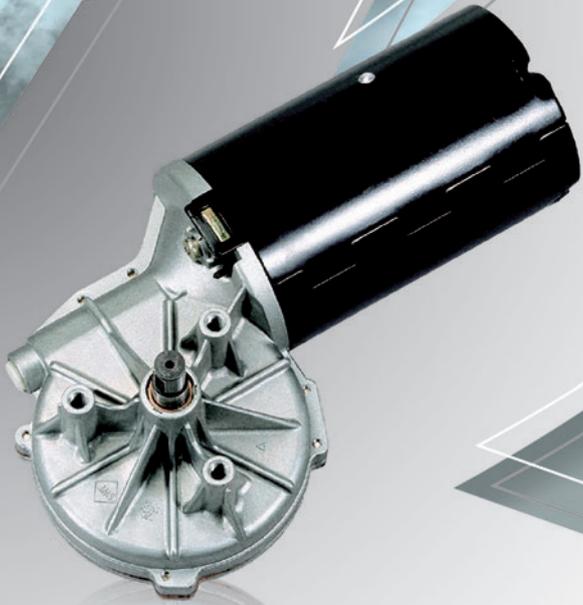
A: spade ends 6.3 x 0.8 (according to DIN 46 244)



NIDEC MOTORS & ACTUATORS ❖❖❖ MOTOR SERIES

# 0292 (SWMG)

❖❖❖ DC MOTORS WITH WORM GEAR



## ❖❖❖ TECHNICAL DESCRIPTION

Motorhousing:	sheet metal, rolled & corrosion protected
Excitation field:	permanent magnet
Type of gear mesh:	worm gear
Gear housing:	zinc die cast
Gear wheel material:	plastic, resin bonded fabrics, steel
Lubrication:	grease
Mechanical interface:	steel shaft
Electric interface:	leads with connector
Sensor:	optional
Thermal protection:	optional
EMC suppression:	optional

## ❖❖❖ INDUSTRIAL APPLICATION

Machine construction



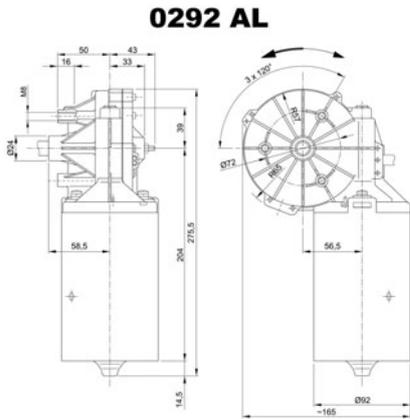
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Ball

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	20.0
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	27.0
Nominal power [W]	$P_N$	44.0
Nominal current [A]	$I_N$	6.0
Nominal force [kN]	$F_N$	0.00
Duty cycle		s1

Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	50/1
Gear wheel material	plastic
Suppression components	
Enclosure class	IP 20
Weight [kg]	4.200

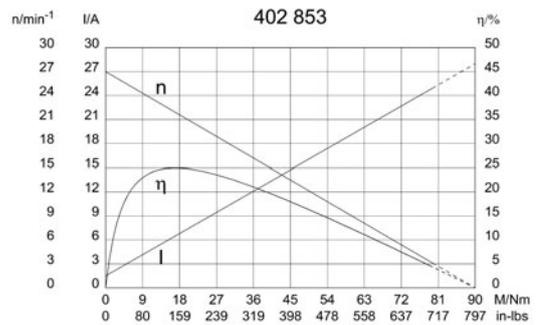
Remarks:



**Motor picture**

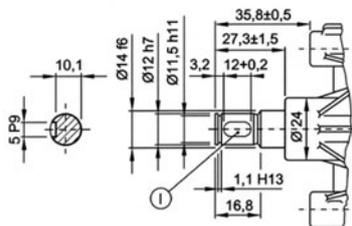


**Characteristic curves**

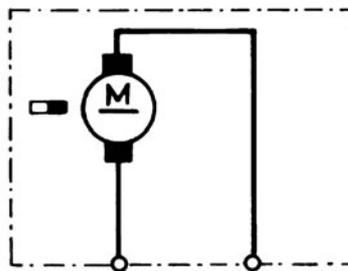


**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**

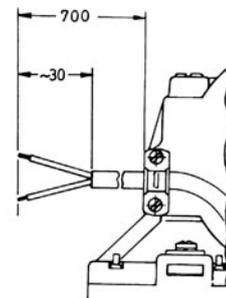
**W 110**



**S 28**



**K 86**



I Groove for feather key A 5x3x12 DIN 6885

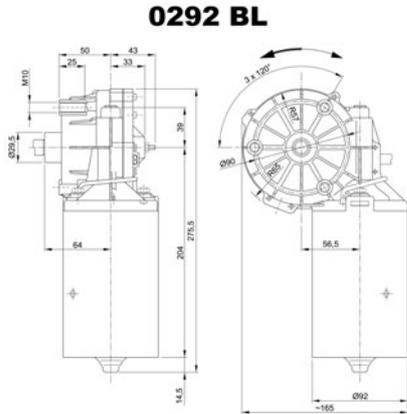
Design Data	
Commutation	Brushed
Direction of rotation	Bi-directional
Bearing type	A:Ball - B:Sleeve

Performance data		
Rated voltage [V]	$U_N$	24
Nominal torque [Nm]	$M_N$	10.0
No-load speed [ $\text{min}^{-1}$ ]	$n_0$	165.0
Nominal power [W]	$P_N$	156
Nominal current [A]	$I_N$	5.0
Nominal force [kN]	$F_N$	0.00
Duty cycle	s1	

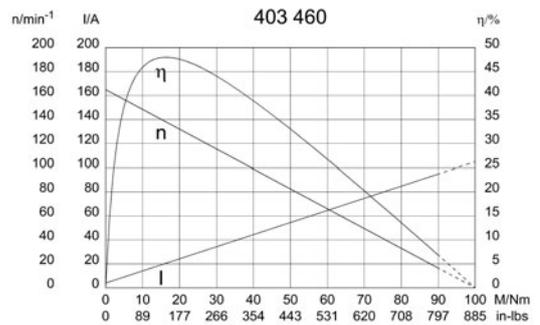
Sensor data	
Pulses	0
Output channels	0

Other data	
Gear ratio	43/3
Gear wheel material	plastic
Suppression components	
Enclosure class	IP 20
Weight [kg]	4.200

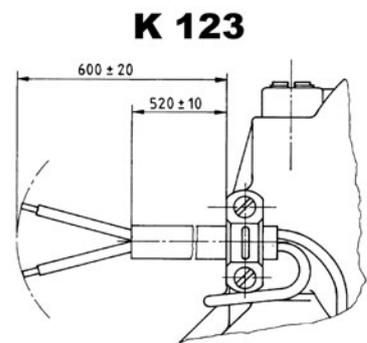
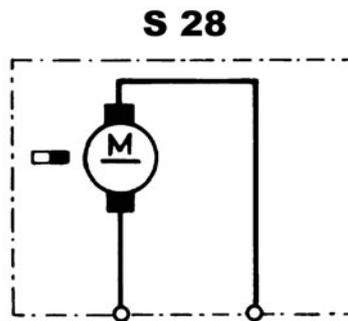
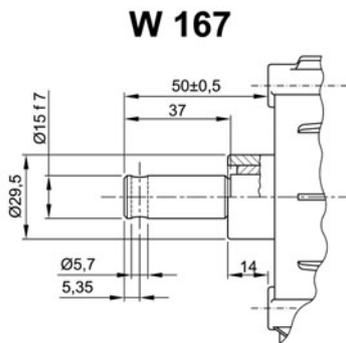
Remarks:



**Motor picture**



**Output shaft drawing (W), Wiring diagrams (S) and Connector layout (K)**











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403 475 .....	156	404 753 .....	20	405 091 .....	95
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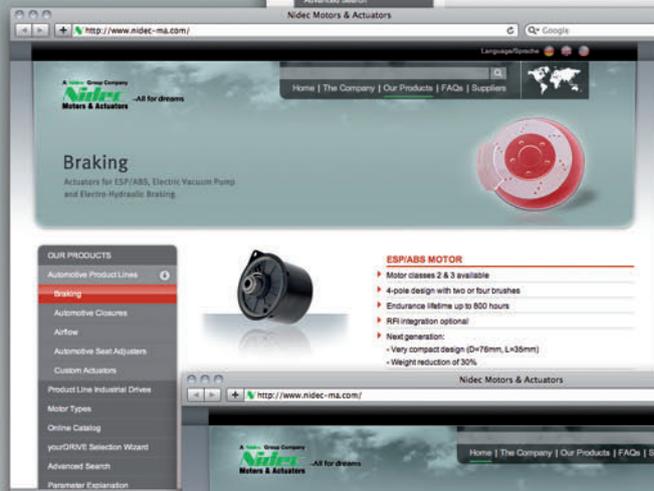
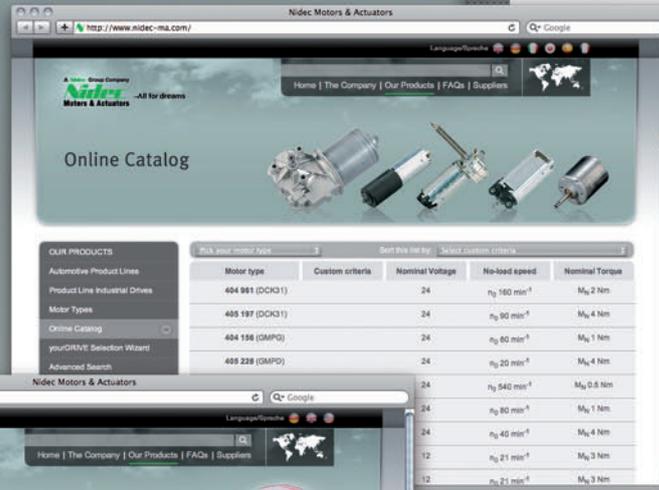
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